

ADVANCED SMARTRECTIFIER™ CONTROL IC

Features

- Secondary side high speed SR controller
- Flyback, Forward and Half-bridge topologies
- CCM operation with SYNC function
- 200 V proprietary IC technology
- Max 500 KHz switching frequency
- Anti-bounce logic and UVLO protection
- 4 A peak turn off drive current
- Micropower start-up & low quiescent current
- 10.7 V gate drive clamp
- 50 ns turn-off propagation delay
- Vcc range from 11 V to 20 V
- Enable function synchronized with MOSFET VDS transition
- Cycle by Cycle MOT Check Circuit prevents multiple false trigger GATE pulses
- Lead-free
- Compatible with 0.3 W Standby, Energy Star, CECP, etc.

Typical Applications

 Telecom SMPS, ATX SMPS, Server SMPS, AC-DC adapters

Product Summary

| Topology | Flyback, Forward, Half- Bridge |
|--|-----------------------------------|
| VD | 200 V |
| V _{OUT} | 10.7 V |
| I _{o+} & I _{o-} (typ.) | +1 A & -4 A |
| Turn on Propagation Delay (typ.) | 70 ns |
| Turn off Propagation Delay (typ.) | 50 ns |

Package Options

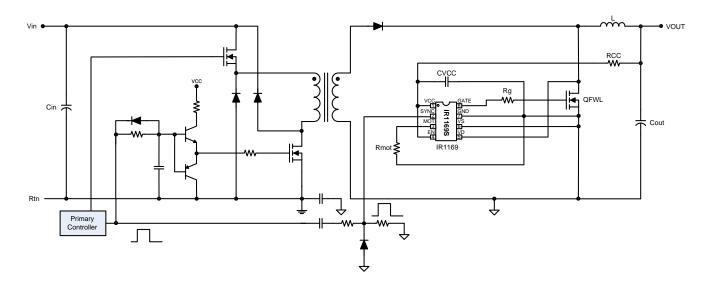


Ordering Information

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|---------------------|--------------|---------------|----------|-------------------------------|
| Base Part Number | Package Type | Form | Quantity | Complete Part Number |
| IR1169S | SOIC8N | Tube/Bulk | 95 | IR1169SPBF |
| 1811095 | SOICON | Tape and Reel | 2500 | IR1169STRPBF |



Typical Connection Diagram





| Table of Contents | Page | | | | |
|--|------|--|--|--|--|
| Ordering Information | 1 | | | | |
| Description | 4 | | | | |
| Absolute Maximum Ratings | 5 | | | | |
| Electrical Characteristics | 6 | | | | |
| Functional Block Diagram | 8 | | | | |
| Input / Output Pin Equivalent Circuit Diagram | | | | | |
| Lead Definitions | | | | | |
| Lead Assignments | | | | | |
| Detailed Pin Description | | | | | |
| Application Information and Additional Details | | | | | |
| Package Details | 25 | | | | |
| Tape and Reel Details | | | | | |
| Part Marking Information | | | | | |
| Qualification Information | 28 | | | | |



Description

IR1169 is a smart secondary-side driver IC designed to drive N-Channel power MOSFETs used as synchronous rectifiers in isolated Flyback, Forward or Half-bridge converters. The IC can control one or more paralleled N-MOSFETs to emulate the behavior of Schottky diode rectifiers. IR1169 works in both DCM and CCM operation modes. The SYNC pin should be used in CCM mode to directly turn-off the MOSFET by a signal from secondary or primary controller. The IC is designed to use simple capacitor coupling interface to communicate with primary controller. In addition to the SYNC control, the drain to source voltage is sensed differentially to determine the polarity of the current and turn the power switch on and off in proximity of the zero current transition. Ruggedness and noise immunity are accomplished using an advanced blanking scheme and double-pulse suppression which allow reliable operation in all operating modes.



Absolute Maximum Ratings

Absolute maximum ratings indicate sustained limits beyond which damage to the device may occur. All voltage parameters are absolute voltages referenced to COM, all currents are defined positive into any lead. The thermal resistance and power dissipation ratings are measured under board mounted and still air conditions.

| Parameters | Symbol | Min. | Max. | Units | Remarks |
|--------------------------------|-------------------|-------------------|------|-------|--------------------------------|
| Supply Voltage | Vcc | -0.3 | 20 | | |
| Enable Voltage | V _{EN} | -0.3 | 20 | V | |
| Cont. SYNC Voltage | V _{SYNC} | -0.3 | 20 |] v | |
| Pulse SYNC Voltage | V _{SYNC} | -0.7 [†] | 20 | | |
| SYNC Current | I _{SYNC} | -10 | 10 | mA | |
| Cont. Drain Sense Voltage | V _D | -1 | 200 | | |
| Pulse Drain Sense Voltage | V _D | -5 | 200 | V | |
| Source Sense Voltage | Vs | -3 | 20 | V | |
| Gate Voltage | V_{GATE} | -0.3 | 20 | | V _{CC} =20V, Gate off |
| Operating Junction Temperature | TJ | -40 | 150 | °C | |
| Storage Temperature | Ts | -55 | 150 | | |
| Thermal Resistance | $R_{\theta JA}$ | | 128 | °C/W | SOIC-8 |
| Package Power Dissipation | P _D | | 970 | mW | SOIC-8, T _{AMB} =25°C |
| Switching Frequency | fsw | | 500 | kHz | |

[†] An input resistor of $2k\Omega$ or above is required to SYNC pin for negative pulse

Recommended Operating Conditions

For proper operation the device should be used within the recommended conditions.

| Symbol | Definition | Min. | Max. | Units | | | |
|----------------|----------------------|-------|------|-------|--|--|--|
| V_{CC} | Supply Voltage | 11 | 19 | \/ | | | |
| V _D | Drain Sense Voltage | -3 ** | 200 | 7 V | | | |
| T_J | Junction Temperature | -25 | 125 | °C | | | |
| Fsw | Switching Frequency | | 500 | kHz | | | |

^{††} V_D -3V negative spike width ≤100ns

Recommended Component Values

| Symbol | Component | Min. | Max. | Units |
|------------------|------------------------|------|------|-------|
| R _{MOT} | MOT pin resistor value | 5 | 75 | kΩ |



Electrical Characteristics

 V_{CC} =15V and T_A = 25°C unless otherwise specified. The output voltage and current (V_O and I_O) parameters are referenced to GND (pin7).

Supply Section

| Parameters | Symbol | Min. | Тур. | Max. | Units | Remarks |
|--|-----------------------|------|------|------|-------|---|
| V _{CC} Turn On Threshold | V _{CC ON} | 9.4 | 10.4 | 11.0 | | |
| V _{CC} Turn Off Threshold (Under Voltage Lock Out) | V _{CC UVLO} | 8.6 | 9.3 | 10.0 | V | |
| V _{CC} Turn On/Off Hysteresis | V _{CC HYST} | | 1.1 | | | |
| Operating Current | - | | 8.5 | 10 | | C _{LOAD} =1nF,f _{SW} =400kHz |
| Operating Current | Icc | | 45 | 55 | mA | C _{LOAD} =10nF,f _{SW} =400kHz |
| Quiescent Current | I _{QCC} | | 1.8 | 2.3 | | SYNC=low |
| Start-up Current | I _{CC START} | | 100 | 200 | | V _{CC} =V _{CC} ON - 0.1V |
| Sleep Current | I _{SLEEP} | | 150 | 200 | μA | V _{EN} =0V, V _{CC} =15V |
| Enable Voltage High | V_{ENHI} | 2.25 | 2.8 | 3.3 | V | |
| Enable Voltage Low | V_{ENLO} | 1.2 | 1.6 | 2.0 | V | |
| Enable Pull-up Resistance | R _{EN} | | 1.5 | | ΜΩ | GBD |

Comparator Section

| Comparator Section | | | | | | |
|------------------------|---------------------|------|------|------|-------|-----------------------|
| Parameters | Symbol | Min. | Тур. | Max. | Units | Remarks |
| Turn-off Threshold | V_{TH1} | -7 | -3.5 | 0 | | |
| Turn-on Threshold | V_{TH2} | -263 | -230 | -197 | mV | |
| Hysteresis | V_{HYST} | | 230 | | | |
| Innut Dica Current | I _{IBIAS1} | | 1 | 7.5 | | $V_D = -50 \text{mV}$ |
| Input Bias Current | I _{IBIAS2} | | 10 | 100 | μΑ | V _D = 200V |
| Input CM Voltage Range | V _{CM} | 0 | | 2 | V | |

One-Shot Section

| Parameters | Symbol | Min. | Тур. | Max. | Units | Remarks |
|-------------------------|--------------------|------|------|------|-------|----------------------------|
| Blanking pulse duration | t _{BLANK} | 9 | 17 | 25 | μs | |
| Dogot Throphold | | | 2.5 | | V | V _{CC} =10V – GBD |
| Reset Threshold | V _{TH3} | | 5.4 | | V | V _{CC} =20V – GBD |
| Hysteresis | V _{HYST3} | | 40 | | mV | V _{CC} =10V – GBD |

Minimum On Time Section

| Parameters | Symbol | Min. | Тур. | Max. | Units | Remarks |
|------------------|-------------|------|------|------|-------|-------------------------------------|
| Minimove on time | 1 | 180 | 240 | 300 | ns | $R_{MOT} = 5k\Omega, V_{CC} = 12V$ |
| Minimum on time | T_{Onmin} | 2.4 | 3 | 3.6 | μs | $R_{MOT} = 75k\Omega, V_{CC} = 12V$ |



Electrical Characteristics

 V_{CC} =15V and T_A = 25°C unless otherwise specified. The output voltage and current (V_O and I_O) parameters are referenced to GND (pin7).

SYNC Section

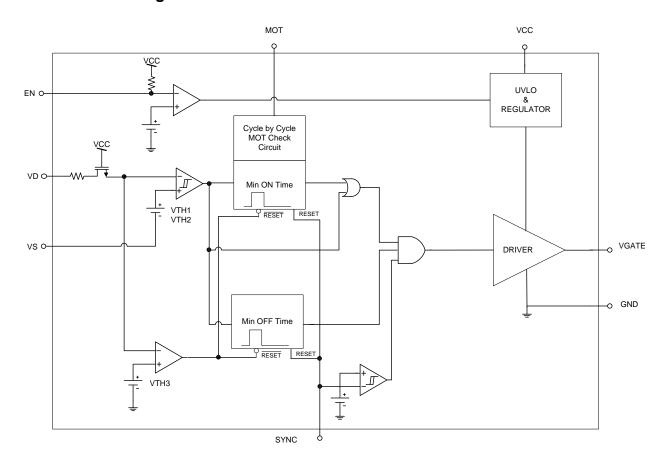
| Parameters | Symbol | Min. | Тур. | Max. | Units | Remarks |
|-----------------------------|-------------------|------|------|------|-------|-------------------|
| SYNC Voltage High (disable) | V_{SYHI} | 2.0 | 2.5 | 3.0 | \/ | |
| SYNC Voltage Low (enable) | V _{SYLO} | 0.6 | 0.8 | 1.0 | V | |
| SYNC Turn-on Prop. Delay | T_{Syon} | | 65 | 100 | | SYNC =high to low |
| SYNC Turn-off Prop. Delay | T_{Syoff} | | 55 | 90 | ns | SYNC=low to high |
| Minimum SYNC pulse width | T _{SYPW} | 50 | | | | GBD |

Gate Driver Section

| Parameters | Symbol | Min. | Тур. | Max. | Units | Remarks |
|------------------------------|-----------------------|------|------|------|-------|--|
| Gate Low Voltage | V_{GLO} | | 0.24 | 0.5 | | I _{GATE} = 200mA |
| Gate High Voltage | V _{GTH} | 9.0 | 10.7 | 14 | V | V _{CC} =12V-18V (internally clamped) |
| Diag Time | t _{r1} | | 20 | | | $C_{LOAD} = 1nF, V_{CC} = 12V$ |
| Rise Time | t _{r2} | | 180 | | | $C_{LOAD} = 10nF, V_{CC}=12V$ |
| Fall Time | t _{f1} | | 10 | | | $C_{LOAD} = 1nF, V_{CC} = 12V$ |
| raii Time | t _{f2} | | 44 | | ns | C _{LOAD} =10nF, V _{CC} =12V |
| Turn on Propagation Delay | t _{Don} | | 70 | 95 | | V _{DS} to V _{GATE} –V _{DS} goes down from 6V to -1V |
| Turn off Propagation Delay | t _{Doff} | | 50 | 75 | | V _{DS} to V _{GATE} –V _{DS} goes up from -1V to 6V |
| Pull up Resistance | r_{up} | | 5 | | 0 | I _{GATE} = 200mA – GBD |
| Pull down Resistance | r _{down} | | 1.2 | | Ω | I _{GATE} = -200mA |
| Output Peak Current (source) | I _{O source} | | 1 | | ۸ | C 10°E CBD |
| Output Peak Current (sink) | I _{O sink} | | 4 | | A | $C_{LOAD} = 10nF - GBD$ |



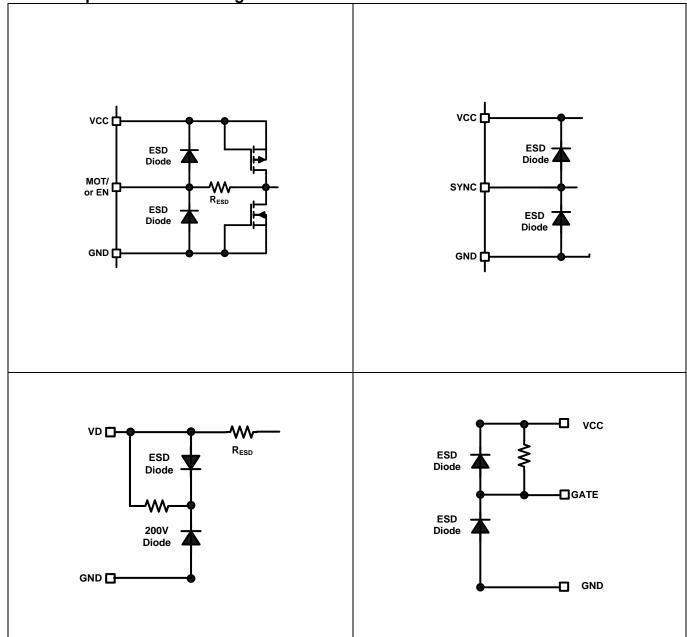
Functional Block Diagram





I/O Pin Equivalent Circuit Diagram

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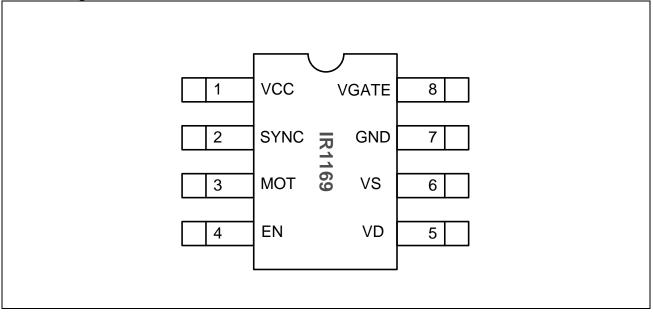




Lead Definitions

| PIN# | Symbol | Description |
|------|--------|--------------------------------|
| 1 | VCC | Supply Voltage |
| 2 | SYNC | SYNC Input for direct turn off |
| 3 | MOT | Minimum On Time |
| 4 | EN | Enable |
| 5 | VD | FET Drain Sensing |
| 6 | VS | FET Source Sensing |
| 7 | GND | Ground |
| 8 | VGATE | Gate Drive Output |







Detailed Pin Description

VCC: Power Supply

This is the supply voltage pin of the IC and it is monitored by the under voltage lockout circuit. It is possible to turn off the IC by pulling this pin below the minimum turn off threshold voltage, without damage to the IC.

To prevent noise problems, a bypass ceramic capacitor connected to Vcc and COM should be placed as close as possible to the IR1169. This pin is internally clamped.

SYNC: Direct Turn-off and Reset

SYNC is used to directly turn-off the SR MOSFET by an external signal. The gate output of IR1169 is low when SYNC voltage is higher than V_{SYHI} threshold. The propagation delay from SYNC goes high to gate turns off is 55ns. The turn-off of SYNC is a direct control and it ignores the MOT time (override).

The SYNC pin will reset MOT and Blanking time when SYNC switches from low to high. It will reset MOT timer and Blanking timer only at the rising edge of signal. This function is useful for very low output voltage condition (such as overload or short circuit) where the VD voltage is too low to reach Vth3 threshold to reset the timers.

SYNC pin also can be used to control the turn-on time of SR MOSFET (adding additional delay time at turn-on for noise immunity).

If not used, SYNC pin should be connected to GND.

MOT: Minimum On Time

The MOT programming pin controls the amount of minimum on time. When V_{SYNC} is low and V_{TH2} is crossed, the gate signal will become active and turn on the power FET. Spurious ringings and oscillations can trigger the input comparator off. The MOT blanks the input comparator keeping the FET on for a minimum time.

The MOT is programmed between 200ns and 3us (typ.) by using a resistor referenced to COM.

EN: Enable

This pin is used to activate the IC "sleep" mode by pulling the voltage level below 1.6V (typ). In sleep mode the IC will consume a minimum amount of current. All switching functions will be disabled and the gate will be inactive. The EN pin voltage cannot linger between the Enable low and Enable high thresholds. The pin is intended to operate as a switch with the pin voltage either above or below the threshold range. The Enable control pin (EN) is not intended to operate at high frequency. For proper operation, EN positive pulse width needs to be longer than 20µs, EN negative pulse width needs to be longer than 10µs. Please refer to Figure 15B for the definition of EN pulse width.

VD: Drain Voltage Sense

VD is the voltage sense pin for the power MOSFET Drain. This is a high voltage pin and particular care must be taken in properly routing the connection to the power MOSFET drain.

VS: Source Voltage Sense

VS is the differential sense pin for the power MOSFET Source. This pin should be connected directly to the power ground pin (7) but must be used to create a kelvin contact as close as possible to the power MOSFET source pin.

GND: Ground

This is ground potential pin of the integrated control circuit. The internal devices and gate driver are referenced to this point.

VGATE: Gate Drive Output

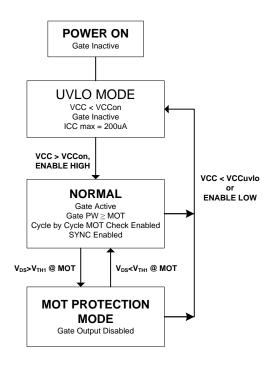
This is the gate drive output of the IC. Drive voltage is internally limited and provides 1A peak source and 4A peak sink capability. Although this pin can be directly connected to the power MOSFET gate, the use of minimal gate resistor is recommended, especially when putting multiple FETs in parallel.

Care must be taken in order to keep the gate loop as short and as small as possible in order to achieve optimal switching performance.



Application Information and Additional Details

State Diagram



UVLO/Sleep Mode

The IC remains in the UVLO condition until the voltage on the VCC pin exceeds the VCC turn on threshold voltage, $V_{CC\ ON}$. During the time the IC remains in the UVLO state, the gate drive circuit is inactive and the IC draws a quiescent current of $I_{CC\ START}$. The UVLO mode is accessible from any other state of operation whenever the IC supply voltage condition of VCC < $V_{CC\ UVLO}$ occurs.

The sleep mode is initiated by pulling the EN pin below 1.6V (typ). In this mode the IC is essentially shut down and draws a very low guiescent supply current.

Normal Mode and Synchronized Enable Function

The IC enters in normal operating mode once the UVLO voltage has been exceeded and EN voltage is above V_{ENHI} threshold. When the IC enters Normal Mode from UVLO Mode, the GATE output is disabled (stays low) until V_{DS} exceeds V_{TH3} to activate the gate. This ensures that the GATE output is not enabled in the middle of a switching cycle. This logic prevents any reverse currents across the device due to minimum on time function in the IC. The gate will continuously drive the SR MOSFET after this one-time activation. The Cycle by Cycle MOT protection circuit is enabled in Normal Mode.

MOT Protection Mode

If the secondary current conduction time is shorter than the MOT (Minimum On Time) setting, the next driver output is disabled. This function can avoid reverse current that occurs when the system works at very low duty-cycles or at very light/no load conditions and reduce system standby power consumption by disabling GATE outputs. The Cycle by Cycle MOT Check circuit is always activated under Normal Mode and MOT Protection Mode, so that the IC can automatically resume normal operation once the load increases to a level and the secondary current conduction time is longer than MOT.



General Description

The IR1169 Smart Rectifier IC can emulate the operation of diode rectifier by properly driving a Synchronous Rectifier (SR) MOSFET. The direction of the rectified current is sensed by the input comparator using the power MOSFET R_{Dson} as a shunt resistance and the GATE pin of the MOSFET is driven accordingly. Internal blanking logic is used to prevent spurious transitions. The Synchronous pin (SYNC) can directly take the signal sent from primary controller to turn off the gate of SR MOSFET prior to the turn-on of primary MOSFET therefore prevent negative current in SR circuit under CCM condition.

IR1169 is suitable for Flyback, Forward and Resonant Half-Bridge topologies.

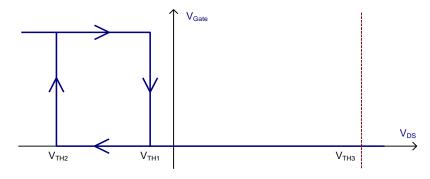


Figure 1: Input comparator thresholds

Flyback Application

The modes of operation for a Flyback circuit differ mainly for the turn-off phase of the SR switch, while the turn-on phase of the secondary switch (which corresponds to the turn off of the primary side switch) is identical.

Turn-on phase

When the conduction phase of the SR FET is initiated, current will start flowing through its body diode, generating a negative V_{DS} voltage across it. The body diode has generally a much higher voltage drop than the one caused by the MOSFET on resistance and therefore will trigger the turn-on threshold V_{TH2} .

At that point, if SYNC voltage is low IR1169 will drive the gate of MOSFET on, which will in turn cause the conduction voltage VDS to drop down. This drop is usually accompanied by some amount of ringing, that can trigger the input comparator to turn off; hence, a Minimum On Time (MOT) blanking period is used that will maintain the power MOSFET on for a minimum amount of time.

The programmed MOT will limit also the minimum duty cycle of the SR MOSFET and, as a consequence, the max duty cycle of the primary side switch.

DCM/CrCM Turn-off phase

Once the SR MOSFET has been turned on, it will remain on until the rectified current will decay to the level where V_{DS} will cross the turn-off threshold V_{TH1} . This will happen differently depending on the mode of operation.

In DCM the current will cross the threshold with a relatively low dl/dt. Once the threshold is crossed, IR1169 will turn off gate and the current will start flowing again thru the body diode, causing the V_{DS} voltage to jump negative. Depending on the amount of residual current, V_{DS} may trigger once again the turn on threshold: for this reason V_{TH2} is blanked for a certain amount of time (T_{BLANK}) after V_{TH1} has been triggered.

The blanking time is internally set. As soon as V_{DS} crosses the positive threshold V_{TH3} the blanking time is terminated and the IC is ready for next conduction cycle.



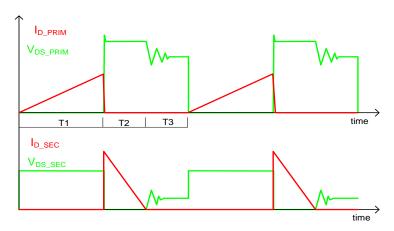


Figure 2: Flyback primary and secondary currents and voltages for DCM mode

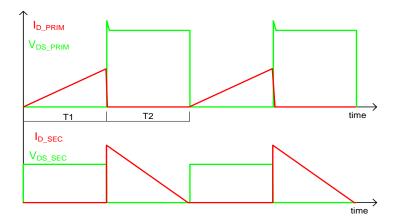


Figure 3: Flyback primary and secondary currents and voltages for CrCM mode

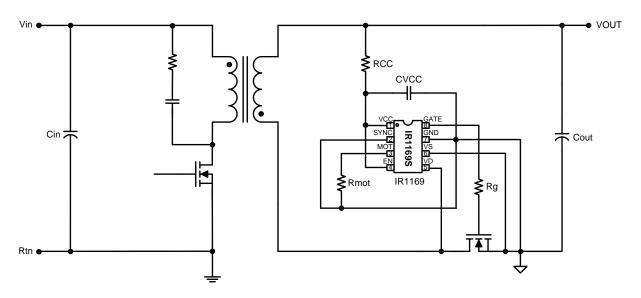


Figure 4: IR1169 schematic in DCM/CrCM mode Flyback



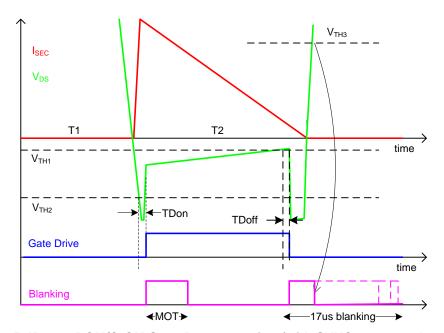


Figure 5: IR1169 DCM/CrCM Sync Rect operation (with SYNC connected to COM)

CCM Turn-off phase

In CCM mode the turn on phase is identical to DCM or CrCM and therefore won't be repeated here.

The turn off transition is much steeper and dl/dt involved is much higher (Figure 6). If the SR controller wait for the primary switch to turn back on and turn the gate off according to the FET current crossing V_{TH1} , it has high chance to get reverse current in the SR MOSFET. A predictable turn-off prior to the primary turn-on is necessary. A decoupling and isolation capacitor can be used to couple the primary gate signal to IR1169 SYNC pin and turn-off the SR MOSFET prior to the current slope goes to negative. Some turn-on delay to the primary MOSFET can guarantee no shoot through between the primary and secondary.

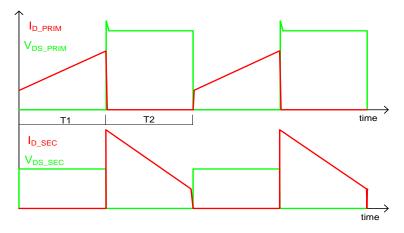


Figure 6: Primary and secondary currents and voltages for CCM mode

In CCM application the connection of IR1169 is recommended as shown in Figure 7.



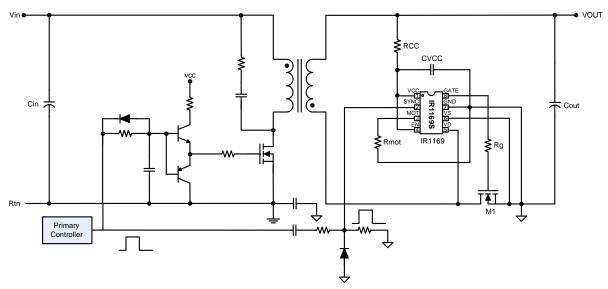


Figure 7: IR1169 schematic in CCM mode Flyback

IR1169 is designed to directly take the control information from primary side with capacitor coupling. A high voltage, low capacitance capacitor is used to send the primary gate driver signal to the SYNC pin. To have the circuit work properly, a Y cap is required between primary ground and secondary ground. No pulse transformer is required for the SYNC function, helps saving cost and PCB area.

The turn-off phase with SYNC control is shown in Figure 8.

In this case a blanking period is not applied; SYNC logic high will reset blanking time.

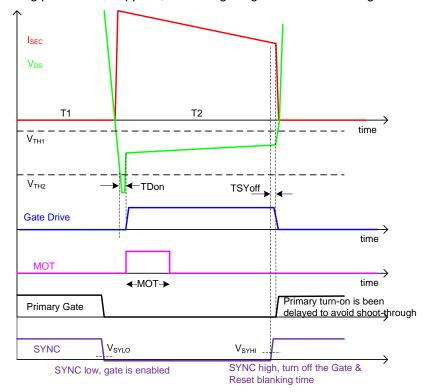


Figure 8: Secondary side CCM operation



Forward Application

The typical forward schematic with IR1169 is shown in Figure 9. The operation waveform of secondary Sync Rect circuit in Forward is similar to the CCM operation of Flyback.

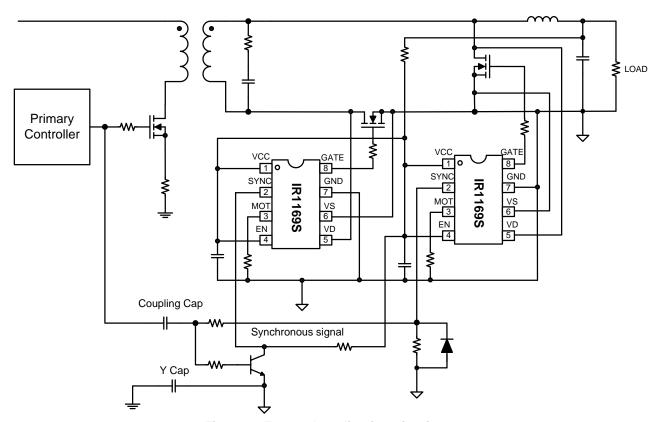


Figure 9: Forward application circuit



Resonant Half-Bridge Application

The typical application circuit of IR1169 in LLC half-bridge is shown in Figure 10.

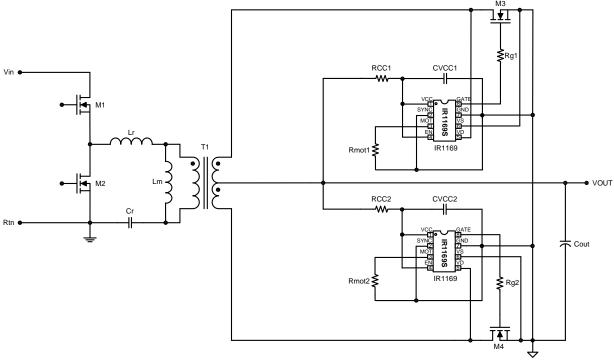


Figure 10: Resonant half-bridge application circuit

The SYNC pin can be tied to COM in LLC converter. The turn-on phase and turn-off phase is similar to Flyback converter except the current shape is sinusoid. The typical operation waveform can be found below.

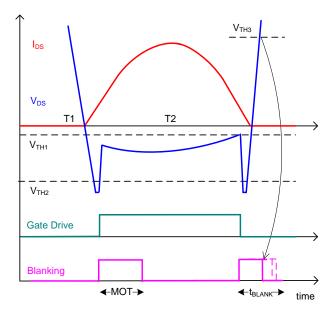


Figure 11: Resonant half-bridge operation waveform (with SYNC connected to GND)



The SYNC pin also can be connected to a control signal for special turn-on and/or turn-off control. Figure 12 is an example where the SYNC function is used to put some delay to the turn-on phase.

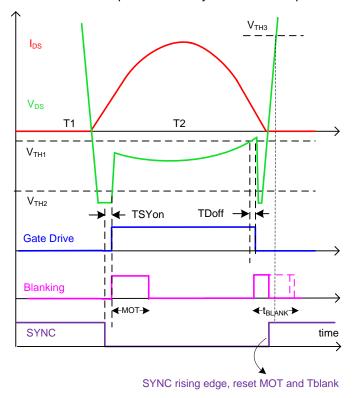


Figure 12: Resonant half-bridge with SYNC control

MOT Protection Mode

The MOT protection prevents reverse current in SR MOSFET. This function works in all three topologies. Figure 13 is an example in Flyback converter.

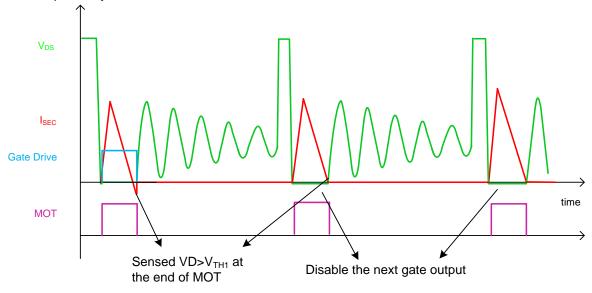


Figure 13: MOT Protection Mode



SYNC Reset Function

The SYNC pin resets MOT and Blanking time when SYNC switches from low to high. This function is useful for very low output voltage condition (such as overload or short circuit) where the VD voltage is too low to reach Vth3 threshold to reset the timers.

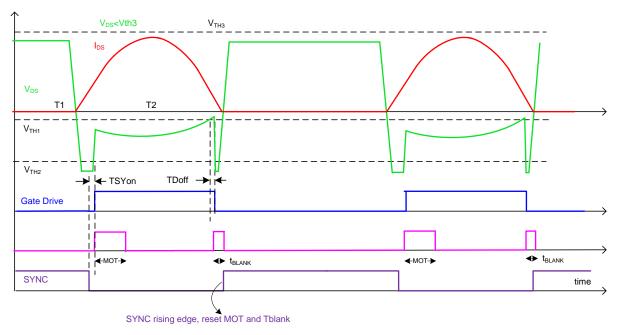


Figure 14: Reset by SYNC when VD<Vth3

General Timing Waveform

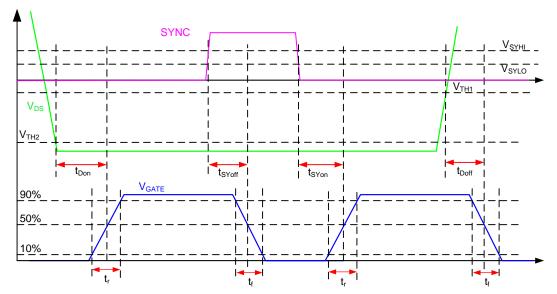


Figure 15A: Timing waveform

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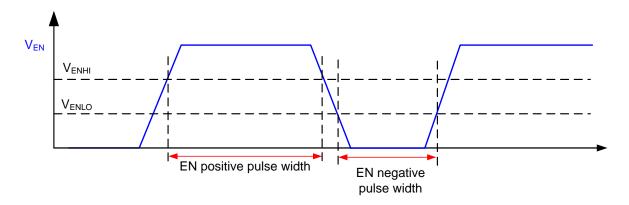


Figure 15B: Enable timing waveform



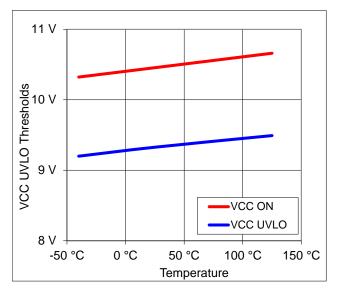


Figure 16: Undervoltage Lockout vs. Temperature

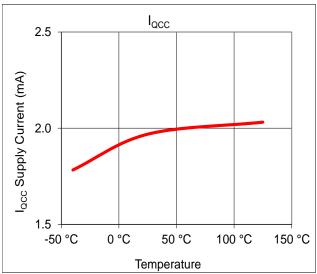


Figure 17: Icc Quiescent Current vs. Temperature

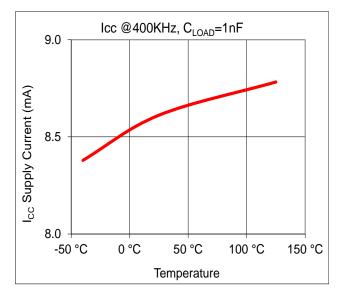


Figure 18: Icc Supply Currrent @1nF Load vs. Temperature

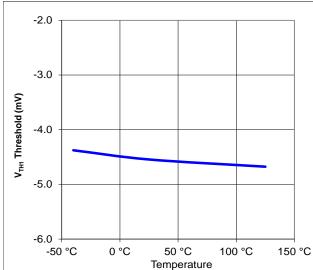
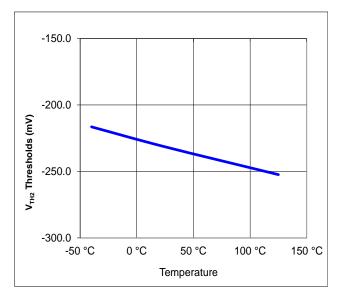
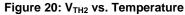


Figure 19: V_{TH1} vs. Temperature







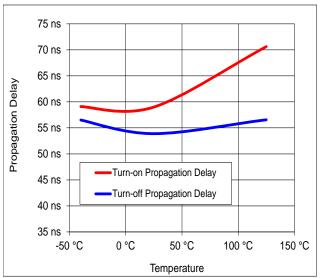


Figure 21: Turn-on and Turn-off Propagation Delay vs. Temperature

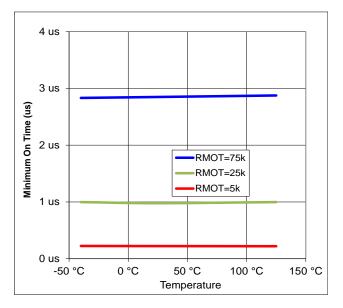


Figure 22: MOT vs Temperature

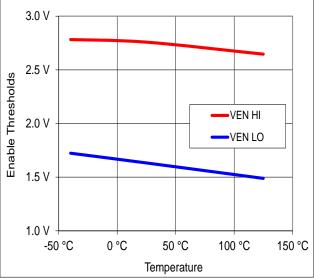
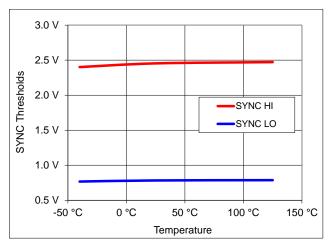


Figure 23: Enable Threshold vs. Temperature





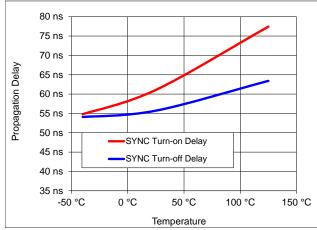
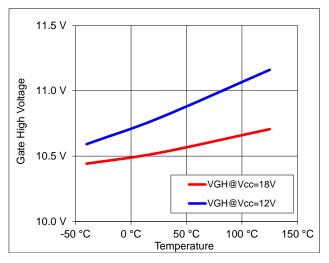


Figure 24: SYNC Thresholds vs. Temperature

Figure 25: SYNC Turn-on and Turn-off Propagation Delay vs. Temperature



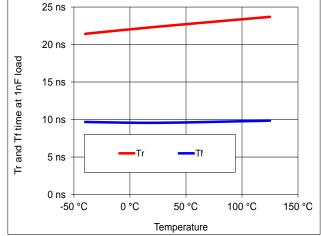
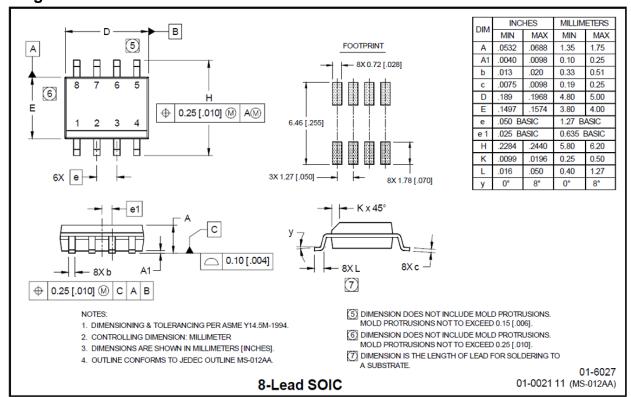


Figure 26: Gate Clamping Voltage vs. Temperature

Figure 27: Rise and Fall time vs. Temperature

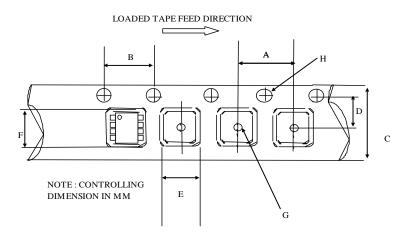


Package Details: SOIC8N



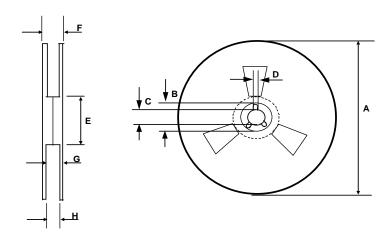


Tape and Reel Details: SOIC8N



CARRIER TAPE DIMENSION FOR 8SOICN

| STATE OF THE BIME TO STATE OF THE STATE OF T | | | | | | |
|--|--------|-------|----------|-------|--|--|
| | Metric | | Imperial | | | |
| Code | Min | Max | Min | Max | | |
| Α | 7.90 | 8.10 | 0.311 | 0.318 | | |
| B C | 3.90 | 4.10 | 0.153 | 0.161 | | |
| | 11.70 | 12.30 | 0.46 | 0.484 | | |
| D | 5.45 | 5.55 | 0.214 | 0.218 | | |
| E | 6.30 | 6.50 | 0.248 | 0.255 | | |
| F | 5.10 | 5.30 | 0.200 | 0.208 | | |
| G | 1.50 | n/a | 0.059 | n/a | | |
| Н | 1.50 | 1.60 | 0.059 | 0.062 | | |

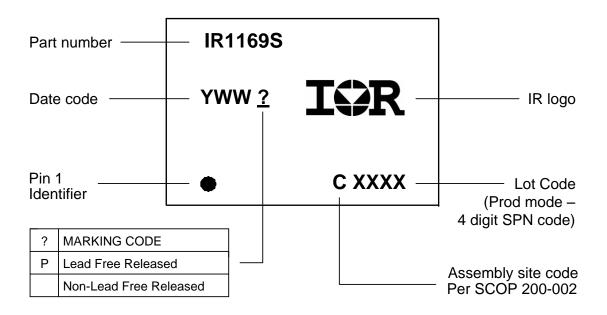


REEL DIMENSIONS FOR 8SOICN

| The state of the s | | | | | | |
|--|--------|--------|----------|--------|--|--|
| | Metric | | Imperial | | | |
| Code | Min | Max | Min | Max | | |
| Α | 329.60 | 330.25 | 12.976 | 13.001 | | |
| В | 20.95 | 21.45 | 0.824 | 0.844 | | |
| С | 12.80 | 13.20 | 0.503 | 0.519 | | |
| D | 1.95 | 2.45 | 0.767 | 0.096 | | |
| E | 98.00 | 102.00 | 3.858 | 4.015 | | |
| F | n/a | 18.40 | n/a | 0.724 | | |
| G | 14.50 | 17.10 | 0.570 | 0.673 | | |
| Н | 12.40 | 14.40 | 0.488 | 0.566 | | |



Part Marking Information





Qualification Information[†]

| | | Industrial ^{††} | | |
|----------------------------|------------------|--|---------------------------|--|
| Qualification Level | | Comments: This family of ICs has passed JEDEC's | | |
| Quamication 2010 | | Industrial qualification. IR's Consumer qualification level is | | |
| | | granted by extension of the higher Industrial level. | | |
| Majatura Canajtivity Lavel | | SOIC8N | MSL2 ^{†††} 260°C | |
| Moisture Sensitivity Level | | | (per IPC/JEDEC J-STD-020) | |
| | Machine Model | Class A | | |
| ESD | | (per JEDEC standard JESD22-A115) | | |
| ESD | Human Body Model | Class 1C | | |
| | | (per EIA/JEDEC standard EIA/JESD22-A114) | | |
| IC Lotob Lin Toot | | Class I, Level A | | |
| IC Latch-Up Test | | (per JESD78) | | |
| RoHS Compliant | | Yes | | |

- † Qualification standards can be found at International Rectifier's web site http://www.irf.com/
- †† Higher qualification ratings may be available should the user have such requirements. Please contact your International Rectifier sales representative for further information.
- ††† Higher MSL ratings may be available for the specific package types listed here. Please contact your International Rectifier sales representative for further information.

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