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LB1946

Monolithic Digital IC

PWM Current Control Stepping Motor Driver

Overview

The LB1946 is stepping motor drive IC that implements PWM current control bipolar drive with a fixed off time. This IC features 15-current setting levels using a fixed VREF voltage and supports for microstepping drive from 1-2 phase excitation to 4W1-2 phase excitation drive. This device is optimal for driving stepping motors such as those used for carriage drive and paper feed in printers.

Applications

- PWM current control stepping motor drivers

Features

- PWM current control with a fixed off time
- Logic input serial-parallel converter (allows 1-2, W1-2, 2W1-2, and 4W1-2 phase excitation drive)
- Current attenuation switching function (with slow decay, fast decay, and mixed decay modes)
- Built-in upper and lower side output diodes
- Simultaneous on state prevention function (through current prevention)
- Noise canceller function
- Thermal shutdown circuit
- Shutoff on low logic system voltage circuit
- Low-power mode control pin

Specifications

Absolute Maximum Ratings at $T_a = 25^\circ\text{C}$

Parameter	Symbol	Conditions	Ratings	Unit
Motor supply voltage	VBB		50	V
Peak output current	I_O PEAK	$t_w \leq 20\mu\text{s}$	1.75	A
Maximum continuous output current	I_O max		1.5	A
Logic system supply voltage	VCC		7.0	V
Logic input voltage range	VIN		-0.3 to VCC	V
Emitter output voltage	VE		1.0	V
Operating temperature	Topr		-20 to +85	°C
Storage temperature	Tstg		-55 to +150	°C
Allowable power dissipation (IC internal)	Pd max	$T_a = 25^\circ\text{C}$, independent IC	3.0	W

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

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Allowable Operating Ranges at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Motor supply voltage	VBB		10 to 45	V
Logic supply voltage	V _{CC}		4.5 to 5.5	V
Reference voltage	VREF		0.0 to 3.0	V

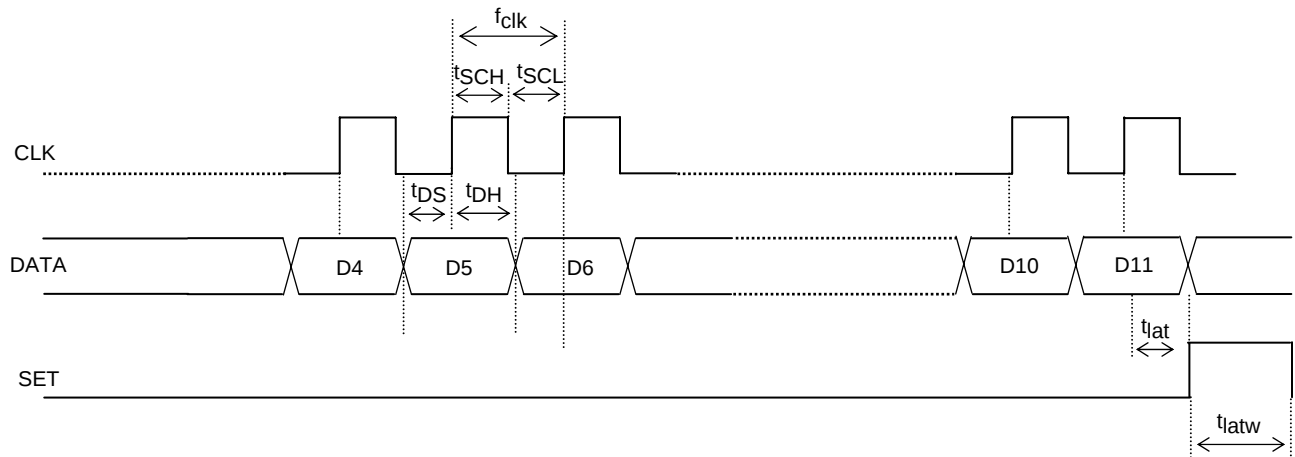
Electrical Characteristics at Ta = 25°C, V_{CC} = 5V, VBB = 45V, VRES = 1.52V

Parameter	Symbol	Conditions	Ratings			unit
			min	typ	max	
Output Block						
Output stage supply current	IBB ON		1.6	2.4	3.5	mA
	IBB OFF		1.3	1.9	2.5	mA
Output saturation voltage 1	V _{OSat1}	I _O =+1.0A (sink)		1.2	1.6	V
Output saturation voltage 2	V _{OSat2}	I _O =+1.5 A (sink)		1.5	1.9	V
Output saturation voltage 3	V _{OSat3}	I _O =-1.0 A (source)		1.9	2.2	V
Output saturation voltage 4	V _{OSat4}	I _O =-1.5 A (source)		2.2	2.4	V
Output leakage current	I _{O1} (leak)	V _O =VBB (sink)			50	μA
	I _{O2} (leak)	V _O =0V (source)	-50			μA
Output sustain voltage	V _{O sus}	L=15mH I _O =1.5A *	45			V
Logic Block						
Logic system supply current	I _{CC} ON	D0=1,D1=1,D2=1,D3=1 When these data values are set	25.5	37	48.5	mA
	I _{CC} OFF1	D0=0,D1=0,D2=0,D3=0	18	26	34	mA
	I _{CC} OFF2	ST=LOW	0.01	0.05	0.1	mA
Input voltage	V _{IH}		2			V
	V _{IL}				0.8	V
Input current	I _{IH}	V _{IH} =2V			35	μA
	I _{IL}	V _{IL} =0.8V	6			μA
Sense voltages	VE	D0=1,D1=1,D2=1,D3=1 When these data values are set	0.470	0.50	0.525	V
		D0=1,D1=1,D2=1,D3=0	0.445	0.48	0.505	V
		D0=1,D1=1,D2=0,D3=1	0.425	0.46	0.485	V
		D0=1,D1=1,D2=0,D3=0	0.410	0.43	0.465	V
		D0=1,D1=0,D2=1,D3=1	0.385	0.41	0.435	V
		D0=1,D1=0,D2=1,D3=0	0.365	0.39	0.415	V
		D0=1,D1=0,D2=0,D3=1	0.345	0.37	0.385	V
		D0=1,D1=0,D2=0,D3=0	0.325	0.35	0.365	V
		D0=0,D1=1,D2=1,D3=1	0.280	0.30	0.325	V
		D0=0,D1=1,D2=1,D3=0	0.240	0.26	0.285	V
		D0=0,D1=1,D2=0,D3=1	0.195	0.22	0.235	V
		D0=0,D1=1,D2=0,D3=0	0.155	0.17	0.190	V
		D0=0,D1=0,D2=1,D3=1	0.115	0.13	0.145	V
		D0=0,D1=0,D2=1,D3=0	0.075	0.09	0.100	V
Reference current	IREF	VREF=1.5V	-0.5			μA
CR pin current	ICR	CR=1.0V	-1.7	-1.25	-0.9	mA
MD pin current	IMD	MD=1.0V, CR=4.0V	-5.0			μA
Logic system on voltage	VLSDON		2.6	2.8	3.0	V
Logic system off voltage	VLSDOFF		2.45	2.65	2.85	V
LVSD hysteresis	VLHIS		0.03	0.15	0.35	V
Thermal shutdown temperature	Ts			170		°C

*Design guaranteed value

AC Electrical Characteristics at $V_{CC} = 5V$

Parameter	Symbol	Conditions	Ratings			unit
			min	typ	max	
Clock frequency	f_{clk}	$V_{CC}=5.0V$		200	550	kHz
Data setup time	t_{DS}	$V_{CC}=5.0V$	0.9	2.5		μs
Data hold time	t_{DH}	$V_{CC}=5.0V$	0.9	2.5		μs
Minimum clock high-level pulse width	t_{SCH}	$V_{CC}=5.0V$	0.9	2.5		μs
Minimum clock low-level pulse width	t_{SCL}	$V_{CC}=5.0V$	0.9	2.5		μs
SET pin stipulated time	t_{lat}	$V_{CC}=5.0V$	0.9	2.5		μs
SET pin signal pulse width	t_{latw}	$V_{CC}=5.0V$	1.9	5.0		μs

 **$V_{CC}=3.3V$ Specification****Absolute Maximum Ratings**

Parameter	Symbol	Conditions	Ratings	Unit
Emitter output voltage	V_E		0.5	V

Allowable Operating Ranges at $T_a = 25^\circ C$

Parameter	Symbol	Conditions	Ratings	Unit
Motor system supply voltage	V_{BB}		10 to 45	V
Logic system supply voltage	V_{CC}		3.0 to 3.6	V
Reference voltage	V_{REF}		0.0 to 1.0	V

Electrical Characteristics at $T_a = 25^\circ C$, $V_{CC} = 3.3V$, $V_{BB} = 45V$, $V_{REF} = 1.0V$

Parameter	Symbol	Conditions	Ratings			unit
			min	typ	max	
Output Block						
Output stage supply current	IBB ON		1.6	2.4	3.5	mA
	IBB OFF		1.3	1.9	2.5	mA
Output saturation voltage 1	V _O sat1	I _O =+1.0A (sink)		1.3	1.7	V
Output saturation voltage 2	V _O sat2	I _O =+1.5 A (sink)		1.6	2.0	V
Output saturation voltage 3	V _O sat3	I _O =-1.0 A (source)		1.9	2.2	V
Output saturation voltage 4	V _O sat4	I _O =-1.5 A (source)		2.2	2.4	V
Output leakage current	I _O 1 (leak)	V _O =V _{BB} (sink)			50	μA
	I _O 2 (leak)	V _O =0V (source)	-50			μA
Output sustain voltage	V _O sus	L=15mH I _O =-1.5A *	45			V

*Design guaranteed value

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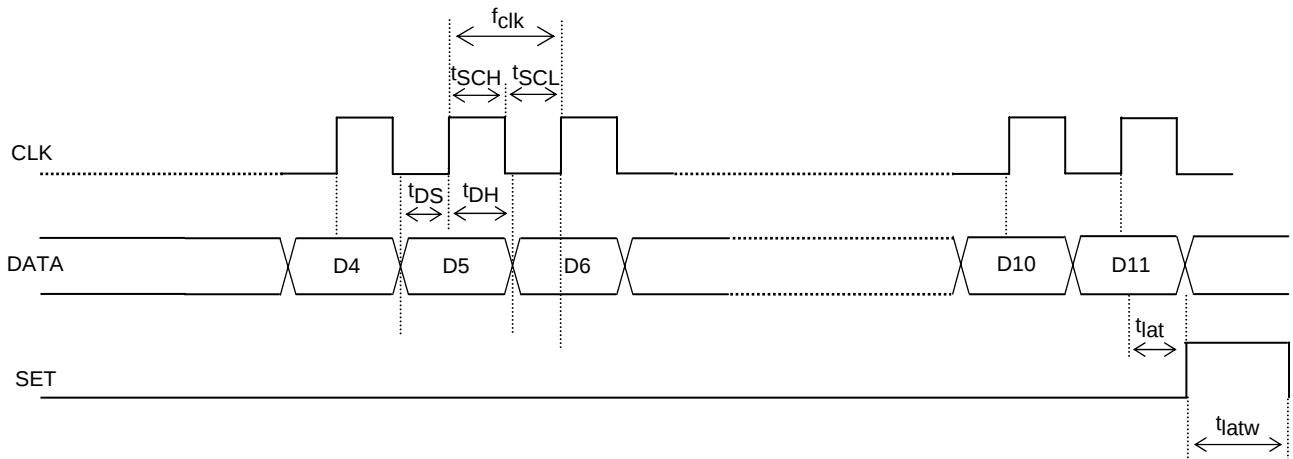
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Parameter	Symbol	Conditions	Ratings			unit
			min	typ	max	
Logic Block						
Logic system supply current	I _{CC ON}	D0=1,D1=1,D2=1,D3=1 When these data values are set	23.5	34	44.5	mA
	I _{CC OFF1}	D0=0,D1=0,D2=0,D3=0	16	23	30	mA
	I _{CC OFF2}	ST=0.8V	0.005	0.03	0.1	mA
Input voltage	V _{IH}		2			V
	V _{IL}				0.8	V
Input current	I _{IH}	V _{IH} =2V			35	μA
	I _{IL}	V _{IL} =0.8V	6			μA
Sense voltages	VE	D0=1,D1=1,D2=1,D3=1 When these data values are set	0.303	0.330	0.356	V
		D0=1,D1=1,D2=1,D3=0	0.290	0.315	0.341	V
		D0=1,D1=1,D2=0,D3=1	0.276	0.300	0.324	V
		D0=1,D1=1,D2=0,D3=0	0.263	0.286	0.309	V
		D0=1,D1=0,D2=1,D3=1	0.250	0.272	0.294	V
		D0=1,D1=0,D2=1,D3=0	0.236	0.257	0.278	V
		D0=1,D1=0,D2=0,D3=1	0.223	0.243	0.263	V
		D0=1,D1=0,D2=0,D3=0	0.209	0.228	0.247	V
		D0=0,D1=1,D2=1,D3=1	0.183	0.200	0.217	V
		D0=0,D1=1,D2=1,D3=0	0.155	0.170	0.185	V
		D0=0,D1=1,D2=0,D3=1	0.128	0.143	0.158	V
		D0=0,D1=1,D2=0,D3=0	0.102	0.114	0.126	V
		D0=0,D1=0,D2=1,D3=1	0.074	0.085	0.096	V
		D0=0,D1=0,D2=1,D3=0	0.047	0.057	0.067	V
Reference current	I _{REF}	V _{REF} =1.5V	-0.5			μA
CR pin current	I _{CR}	CR=1.0V	-0.91	-0.7	-0.49	mA
MD pin current	I _{MD}	MD=1.0V, CR=4.0V	-5.0			μA
Logic system on voltage	V _{LSDON}		2.6	2.8	3.0	V
Logic system off voltage	V _{LSDOFF}		2.45	2.65	2.85	V
LVSD hysteresis	V _{LHIS}		0.03	0.15	0.35	V
Thermal shutdown temperature	T _s			170		°C

AC Electrical Characteristics at V_{CC} = 3.3V

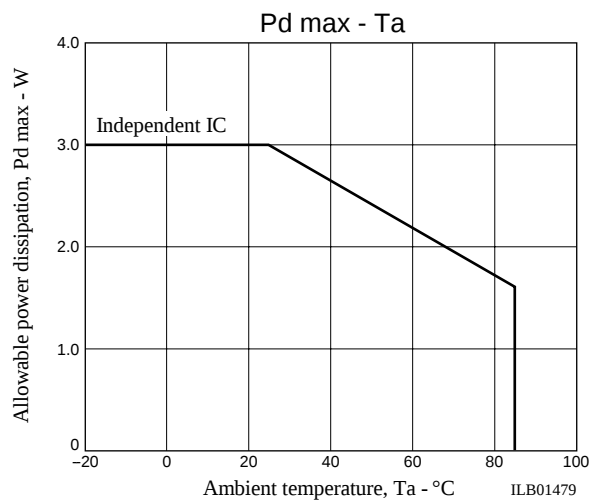
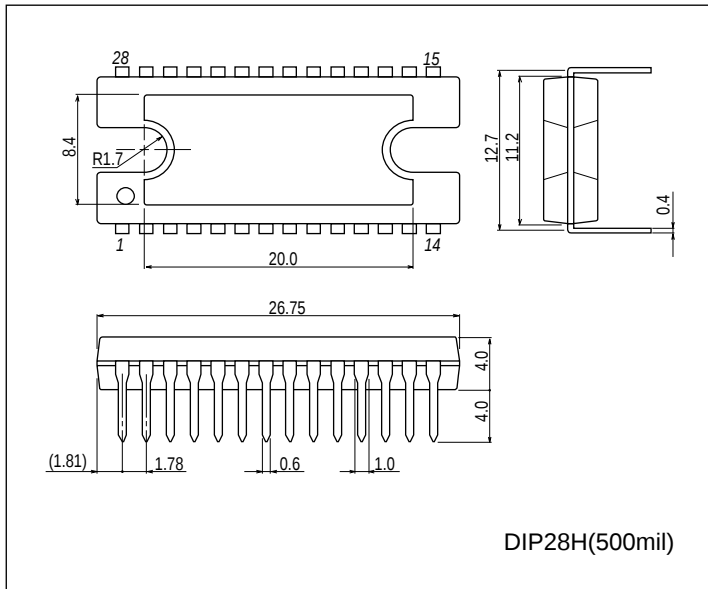
Parameter	Symbol	Conditions	Ratings			unit
			min	typ	max	
Clock frequency	f _{clk}	V _{CC} =3.3V		200	550	kHz
Data setup time	t _{DS}	V _{CC} =3.3V	0.9	2.5		μs
Data hold time	t _{DH}	V _{CC} =3.3V	0.9	2.5		μs
Minimum clock high-level pulse width	t _{SCH}	V _{CC} =3.3V	0.9	2.5		μs
Minimum clock low-level pulse width	t _{SCL}	V _{CC} =3.3V	0.9	2.5		μs
SET pin stipulated time	t _{lat}	V _{CC} =3.3V	0.9	2.5		μs
SET pin signal pulse width	t _{latw}	V _{CC} =3.3V	1.9	5.0		μs



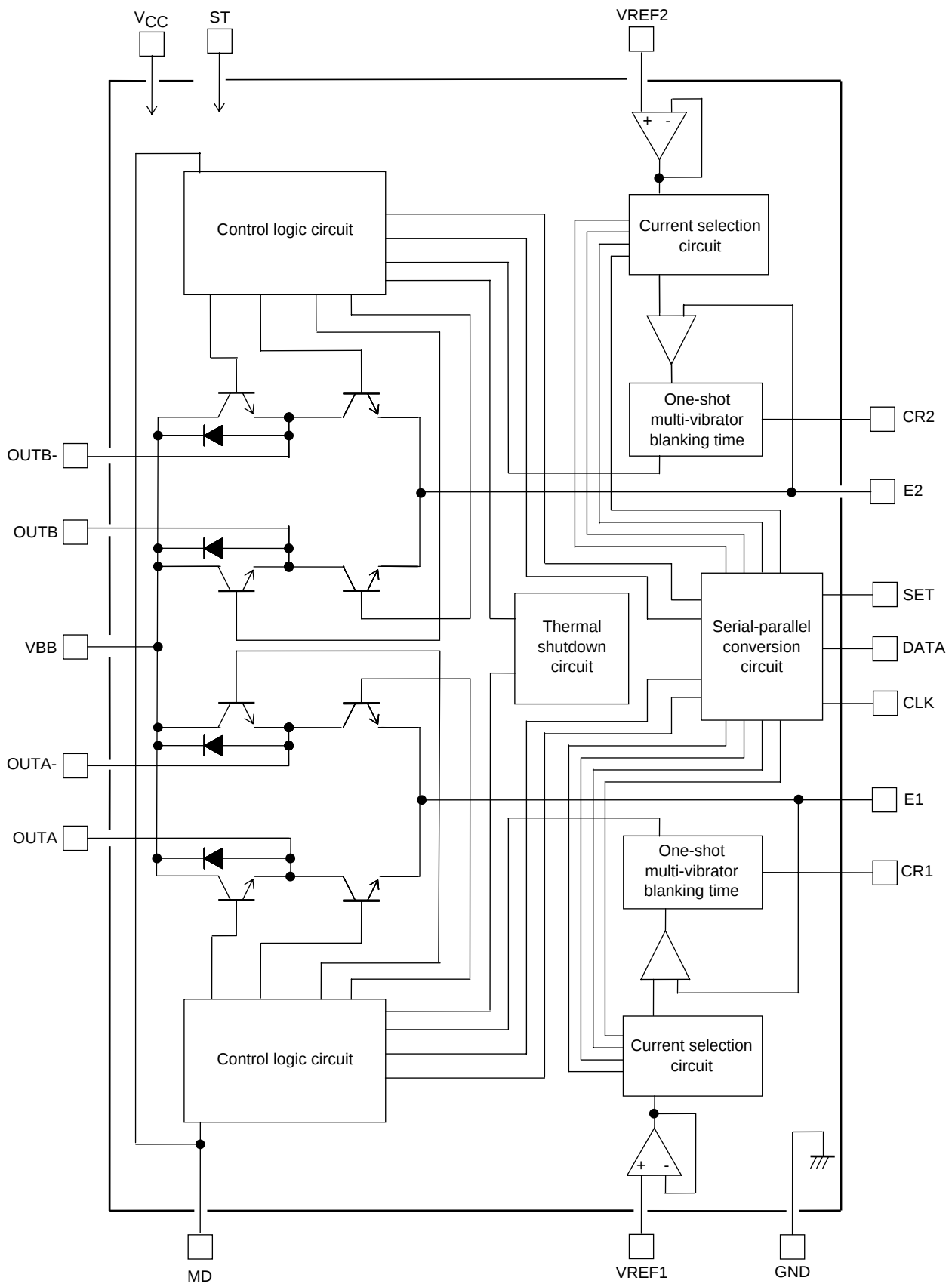
Package Dimensions

unit:mm (typ)

3147C

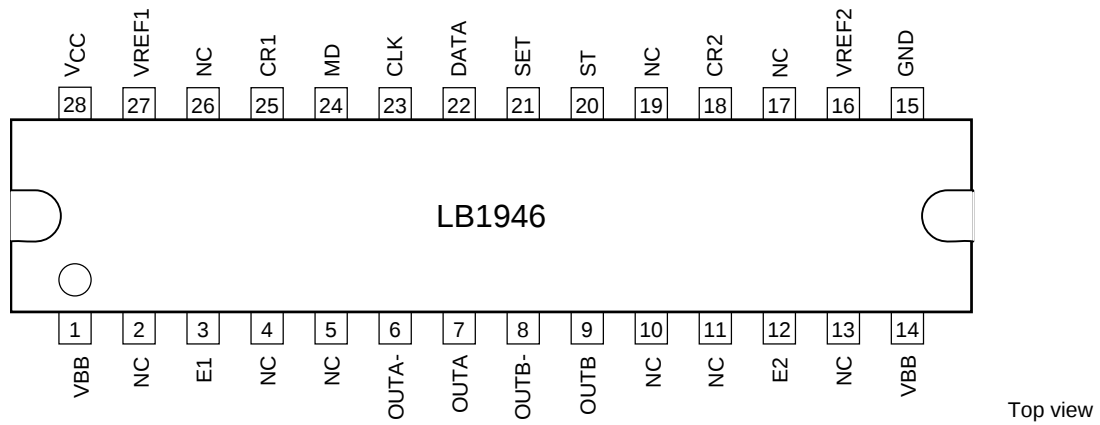


Block Diagram

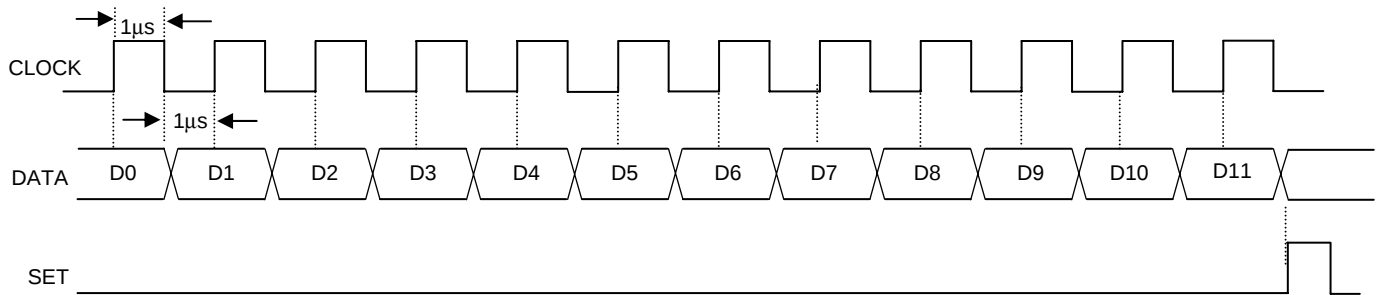


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Pin Assignment



Timing Chart



Serial Transmission Data Definitions

No.	IA4	IA3	IA2	IA1	DE1	PH1	IB4	IB3	IB2	IB1	DE2	PH2	Output mode				I/O ratio	DEC MODE
	D0	D1	D2	D3	D4	D5	D6	D7	D8	D9	D10	D11	OUTA	OUTA-	OUTB	OUTB-		
0	1	1	1	1	1	1	1	1	1	1	1	1	H	L	H	L	100%	SLOW
1	1	1	1	0	1	1	1	1	1	0	1	1	H	L	H	L	96	SLOW
2	1	1	0	1	1	1	1	1	0	1	1	1	H	L	H	L	91	SLOW
3	1	1	0	0	1	1	1	1	0	0	1	1	H	L	H	L	87	SLOW
4	1	0	1	1	1	1	1	0	1	1	1	1	H	L	H	L	83	SLOW
5	1	0	1	0	1	1	1	0	1	0	1	1	H	L	H	L	78	SLOW
6	1	0	0	1	1	1	1	0	0	1	1	1	H	L	H	L	74	SLOW
7	1	0	0	0	1	1	1	0	0	0	1	1	H	L	H	L	70	SLOW
8	0	1	1	1	1	1	0	1	1	1	1	1	H	L	H	L	61	SLOW
9	0	1	1	0	1	1	0	1	1	0	1	1	H	L	H	L	52	SLOW
10	0	1	0	1	1	1	0	1	0	1	1	1	H	L	H	L	44	SLOW
11	0	1	0	0	1	1	0	1	0	0	1	1	H	L	H	L	35	SLOW
12	0	0	1	1	1	1	0	0	1	1	1	1	H	L	H	L	26	SLOW
13	0	0	1	0	1	1	0	0	1	0	1	1	H	L	H	L	17	SLOW
14	1	1	1	1	0	0	1	1	1	1	0	0	L	H	L	H	100	FAST
15	1	1	1	0	0	0	1	1	1	0	0	0	L	H	L	H	96	FAST
16	1	1	0	1	0	0	1	1	0	1	0	0	L	H	L	H	91	FAST
17	1	1	0	0	0	0	1	1	0	0	0	0	L	H	L	H	87	FAST
18	1	0	1	1	0	0	1	0	1	1	0	0	L	H	L	H	83	FAST
19	1	0	1	0	0	0	1	0	1	0	0	0	L	H	L	H	78	FAST
20	1	0	0	1	0	0	1	0	0	1	0	0	L	H	L	H	74	FAST
21	1	0	0	0	0	0	1	0	0	0	0	0	L	H	L	H	70	FAST
22	0	1	1	1	0	0	0	1	1	1	0	0	L	H	L	H	61	FAST
23	0	1	1	0	0	0	0	1	1	0	0	0	L	H	L	H	52	FAST
24	0	1	0	1	0	0	0	1	0	1	0	0	L	H	L	H	44	FAST
25	0	1	0	0	0	0	0	1	0	0	0	0	L	H	L	H	35	FAST
26	0	0	1	1	0	0	0	0	1	1	0	0	L	H	L	H	26	FAST
27	0	0	1	0	0	0	0	0	1	0	0	0	L	H	L	H	17	FAST
28	0	0	0	0	*	*	0	0	0	0	*	*	OFF	OFF	OFF	OFF	0	-

Note *: Don't care (0 or 1)

Note 1: In the mixed decay mode, set D4 and D10 to 0 and set the MD pin to a level shown below.

Programmable MD voltage range

V_{CC}=5V specifications: 1.6 to 3.9V

V_{CC}=3.3V specifications: 1.2 to 2.5V

Current Settings Truth Table

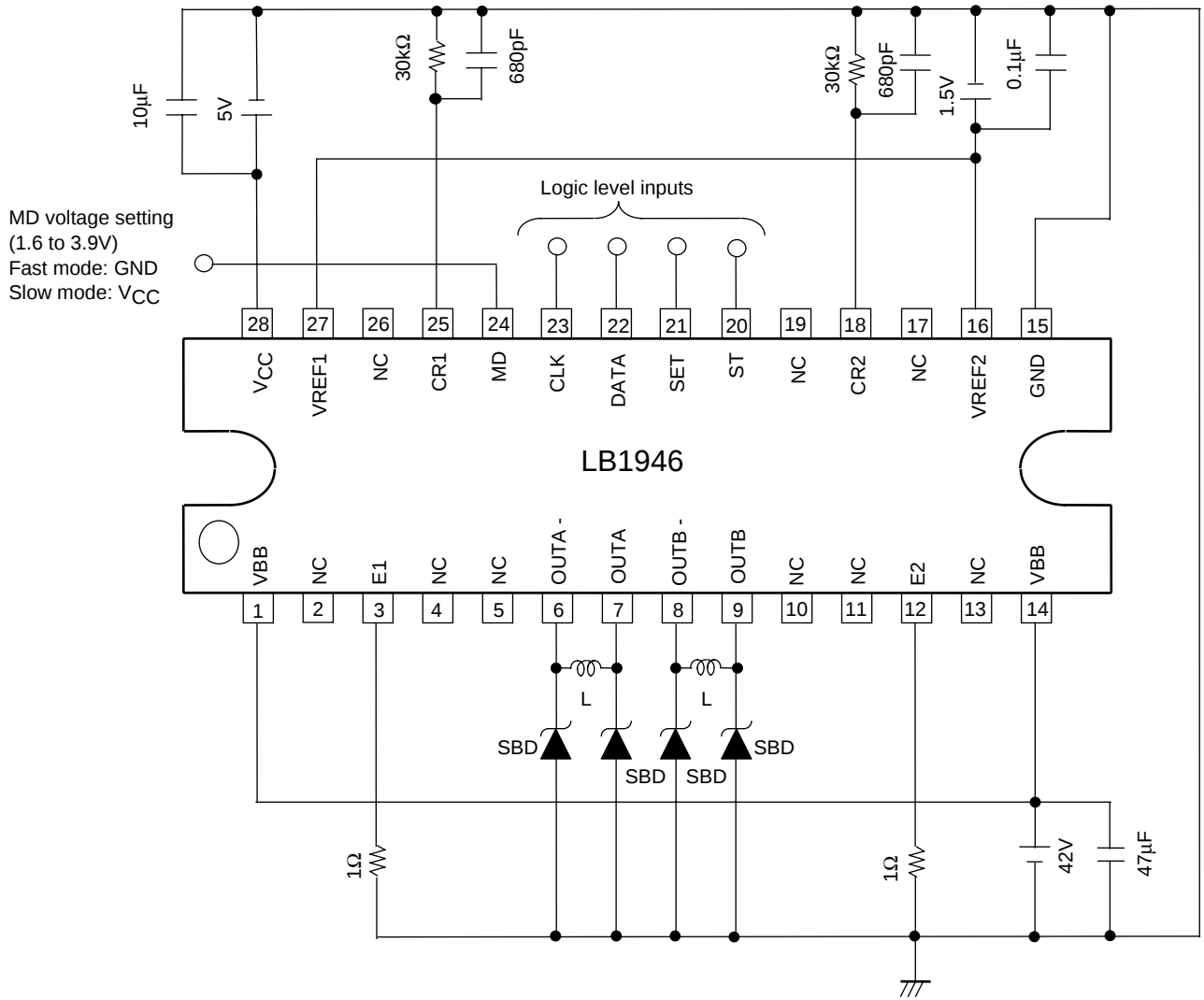
* Items in parentheses are defined by the serial data.

IA4 (D0)	IA3 (D1)	IA2 (D2)	IA1 (D3)	Set Current I _{OUT}	Current Ratio (%)
1	1	1	1	$11.5/11.5 \times V_{REF}/3.04RE = I_{OUT}$	100
1	1	1	0	$11.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	95.65
1	1	0	1	$10.5/11.5 \times V_{REF}/3.04RE = I_{OUT}$	91.30
1	1	0	0	$10.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	86.95
1	0	1	1	$9.5/11.5 \times V_{REF}/3.04RE = I_{OUT}$	82.61
1	0	1	0	$9.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	78.26
1	0	0	1	$8.5/11.5 \times V_{REF}/3.04RE = I_{OUT}$	73.91
1	0	0	0	$8.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	69.56
0	1	1	1	$7.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	60.87
0	1	1	0	$6.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	52.17
0	1	0	1	$5.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	43.48
0	1	0	0	$4.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	34.78
0	0	1	1	$3.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	26.08
0	0	1	0	$2.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	17.39

Note 1: The current ratios shown are calculated values.

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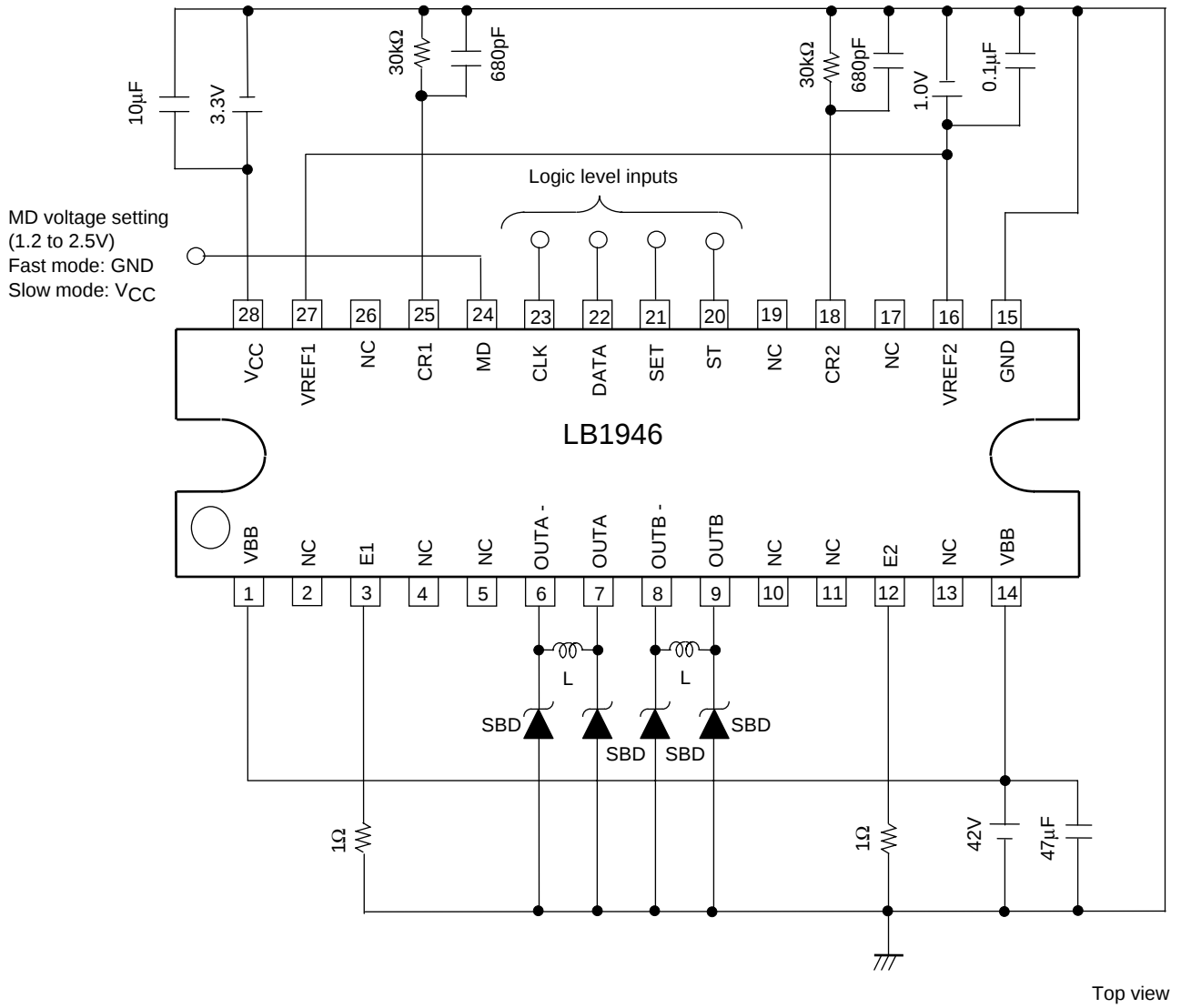
Sample Application Circuit at $V_{CC}=5V$



Top view

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Sample Application Circuit at $V_{CC}=3.3V$



Current Path in Slow Decay Mode

Regenerative current during upper-side transistor switching operation

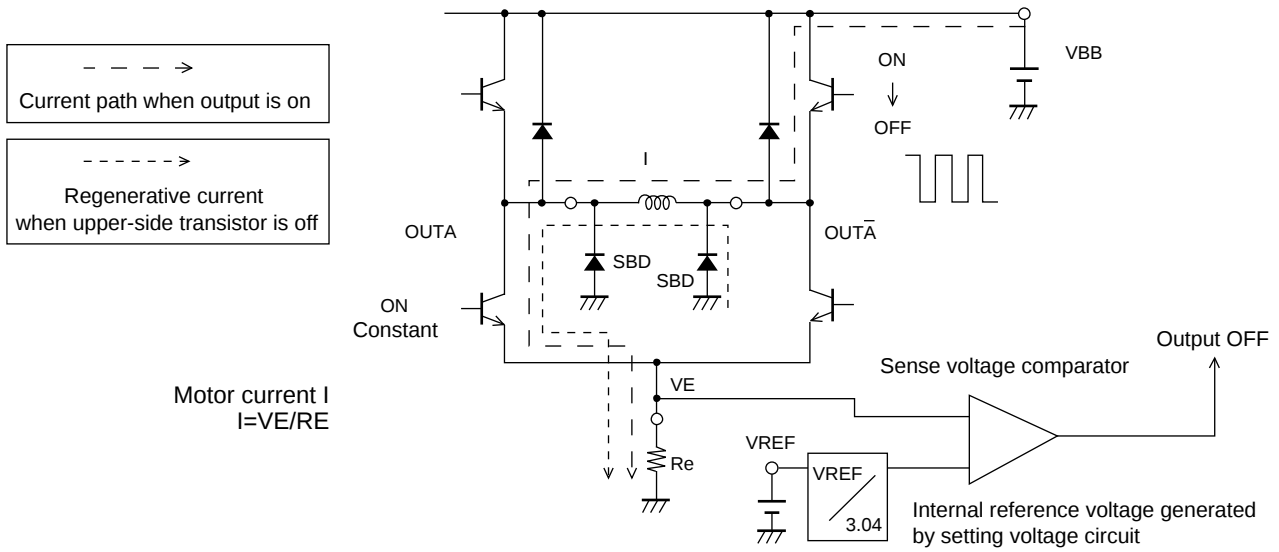
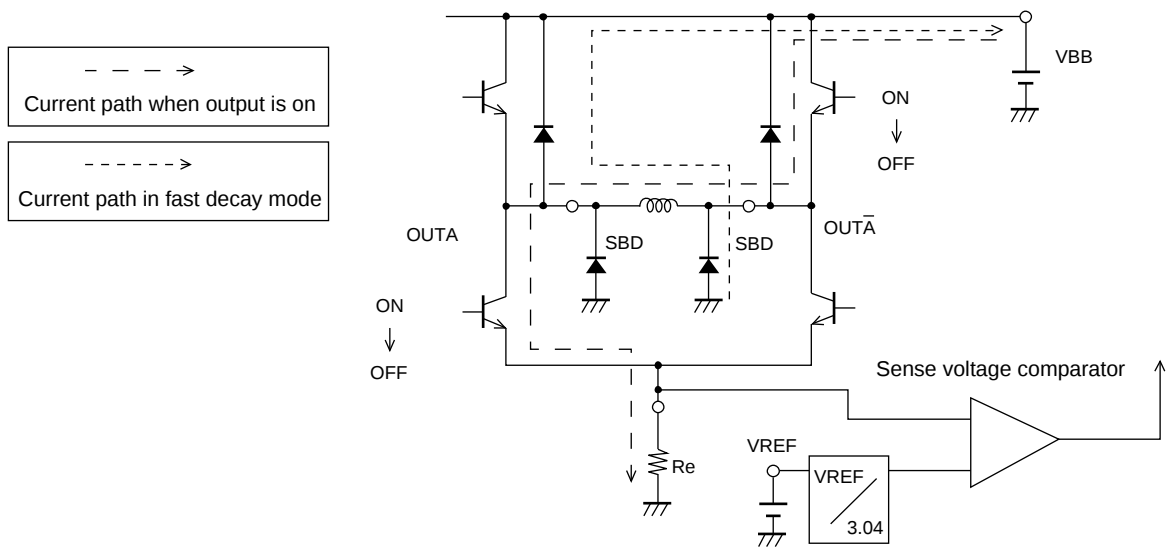


Figure 1

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Current Path in Fast Decay Mode

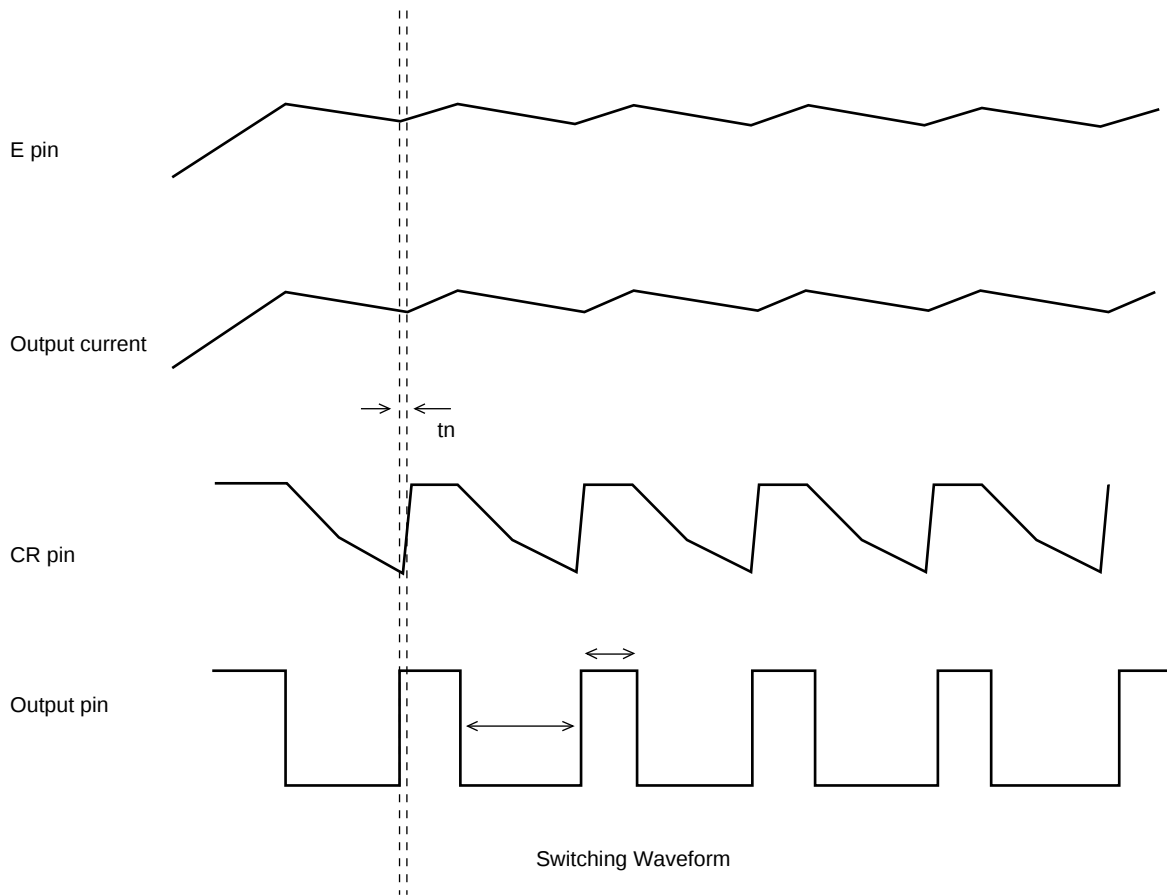


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Switching Timing Chart During PWM Drive Mode

Slow decay (upper-side chopping)

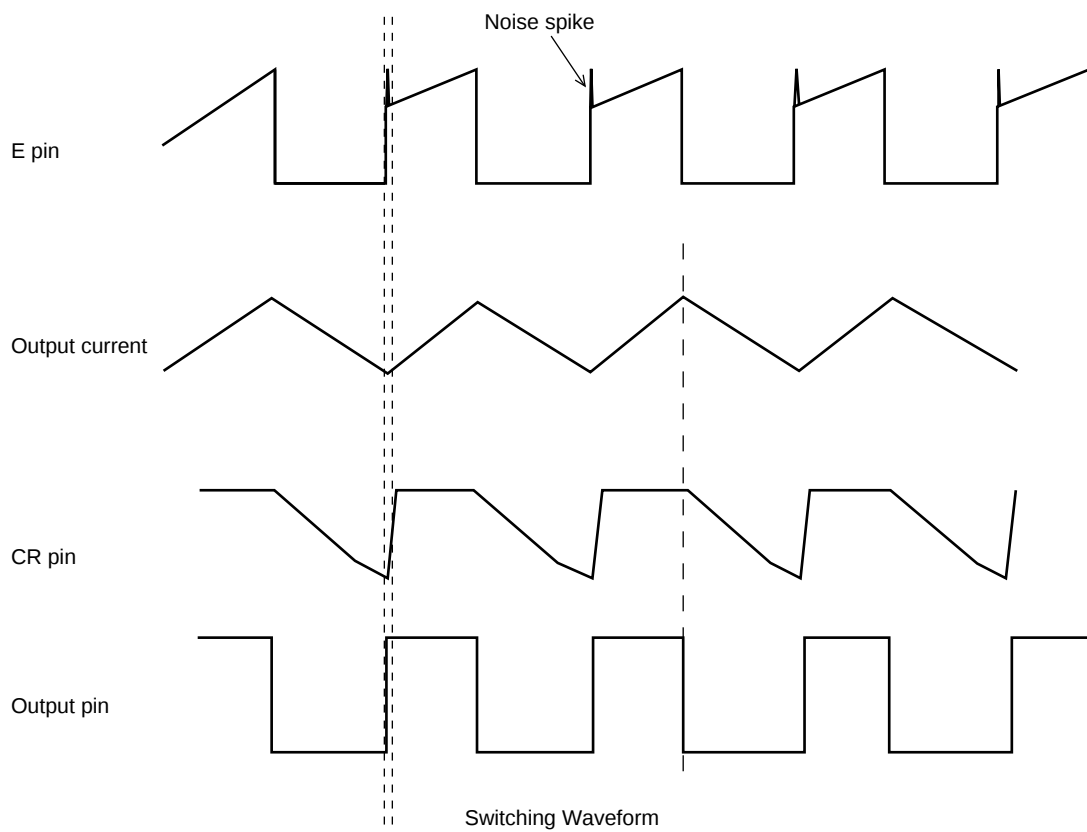
Serial transmission data (D4, D10) = High MD pin: Low



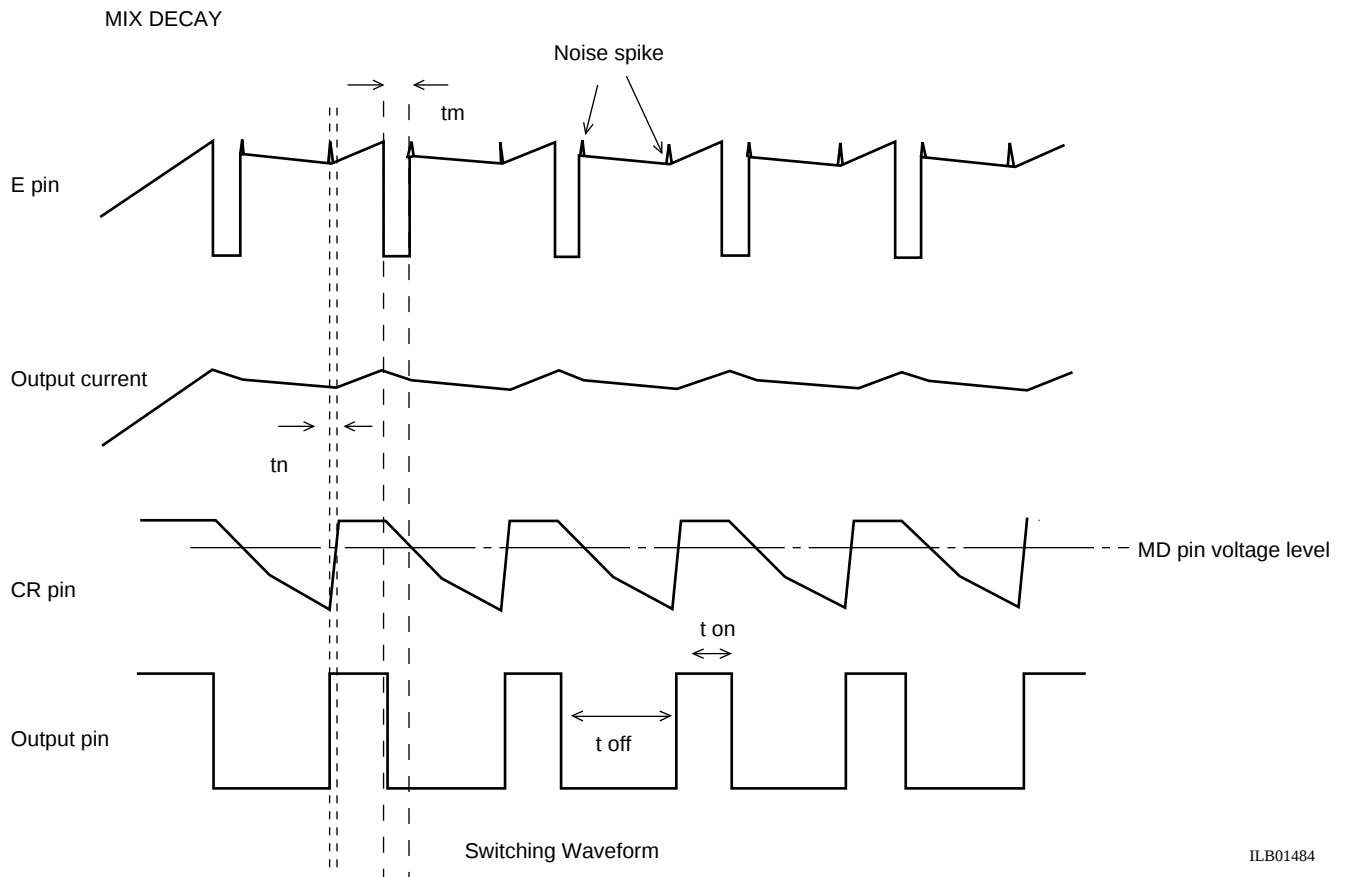
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FAST DECAY

Serial transmission data (D4, D10) = Low MD pin: Low



ILB01483



Mix decay logic setting

When serial transmission data (D4, D10) is Low

MD pin setting:

5V V_{CC} type: 1.6 to 3.9V

3.3V V_{CC} type: 1.2 to 2.5V

CR voltage and MD pin voltage are compared to select dual-side chopping or upper-side chopping.

CR voltage > MD pin voltage: dual-side chopping

CR voltage < MD pin voltage: upper-side chopping

t_{on} : Output on time

t_{off} : Output off time

t_m : Fast decay time in mix decay mode

t_n : Noise cancellation time

1. Switching OFF time and noise cancellation time calculations

Notes on the CR pin setting (switching off time and noise canceller time)

The noise canceller time (T_n) and the switching off time (T_{off}) are set using the following formulas.

- When $V_{CC}=5V$

Noise canceller time (T_n)

$$T_n \approx C \cdot R \cdot \ln \left\{ \frac{(1.5 - R I)}{(4.0 - R I)} \right\} [s]$$

CR pin charge current: 1.25mA

Switching off time (T_{off})

$$T_{off} \approx -C \cdot R \cdot \ln (1.5/4.8) [s]$$

Component value ranges

R: 5.6k Ω to 100k Ω

C: 470pF to 2000pF

- When $V_{CC}=3.3V$

Noise canceller time (T_n)

$$T_n \approx C \cdot R \cdot \ln \left\{ \frac{(1.06 - R I)}{(2.66 - R I)} \right\} [s]$$

CR pin charge current: 0.7mA

Switching off time (T_{off})

$$T_{off} \approx -C \cdot R \cdot \ln (1.06/3.1) [s]$$

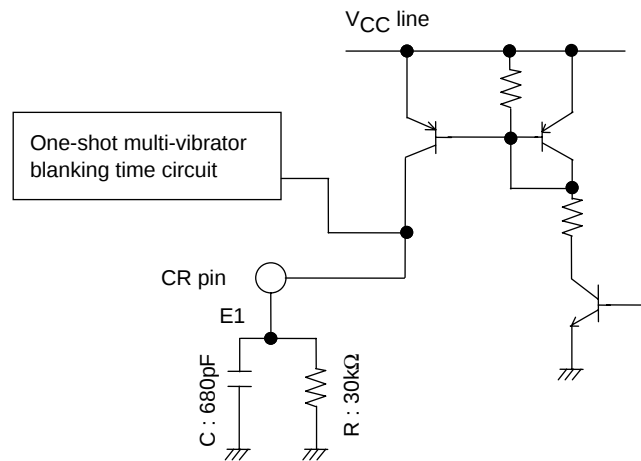


Figure 2 CR Pin Internal Circuit Structure

2. Notes on the MD pin

- If slow decay mode is set up by setting the D4 and D10 bits in the input serial data to 1, the MD pin must be shorted to GND.
- If the decay mode is set up by setting the D4 and D10 bits in the input serial data to 0, decay mode can be set with the MD pin.
When the $V_{CC}=5V$ specifications are used, the setting voltage range for mixed decay mode is 1.6 to 3.9V.
When the $V_{CC}=3.3V$ specifications are used, the setting voltage range for mixed decay mode is 1.2 to 2.5V.
If mixed decay mode will not be used with the fast decay mode setting, either:
Short the MD pin to GND to select fast decay mode, or
Short the MD pin to V_{CC} to select slow decay mode.

3. Usage Notes

- Notes on the VREF pin
Since the VREF pin inputs the reference voltage used to set the current, applications must be designed so that noise does not occur at this pin.
- Notes on the GND pins
Since this IC switches large currents, care is required with respect to the GND pins.
The PCB pattern in sections where large currents flow must be designed with low impedances and must be kept separate from the small-signal system.
In particular, the GND terminals of the E pin sense resistor (RE) and external Schottky barrier diode GND terminals must be located as close as possible to the IC GND. The capacitor between V_{CC} and ground and between VBB and GND must be as close as possible to the corresponding V_{CC} and VBB pin in the pattern.
- Power on sequence
When turning the power systems on
 $V_{CC} \rightarrow$ logic level inputs (CLK, DATA, SET, and ST) $\rightarrow$ VREF $\rightarrow$ VBB

When turning the power systems off
 $VBB \rightarrow$ VREF $\rightarrow$ logic level inputs (CLK, DATA, SET, and ST) $\rightarrow$ V_{CC}

Note that if the power supply for the logic level inputs is on when the V_{CC} power supply is off, a bias with an unstable state will be applied to the protection diodes at the V_{CC} pins, and this can cause incorrect operation.

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