




HS Series Remote Control Decoder Data Guide

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NO OEM LINX REMOTE CONTROL OR FUNCTION MODULE SHOULD EVER BE USED IN LIFE AND PROPERTY SAFETY SITUATIONS. No OEM Linx Remote Control or Function Module should be modified for Life and Property Safety Situations. Such modification cannot provide sufficient safety and will void the product’s regulatory certification and warranty.

Customers may use our (non-Function) Modules, Antenna and Connectors as part of other systems in Life Safety Situations, but only with necessary and industry appropriate redundancies and in compliance with applicable safety standards, including without limitation, ANSI and NFPA standards. It is solely the responsibility of any Linx customer who uses one or more of these products to incorporate appropriate redundancies and safety standards for the Life and Property Safety Situation application.

Do not use this or any Linx product to trigger an action directly from the data line or RSSI lines without a protocol or encoder/decoder to validate the data. Without validation, any signal from another unrelated transmitter in the environment received by the module could inadvertently trigger the action.

All RF products are susceptible to RF interference that can prevent communication. RF products without frequency agility or hopping implemented are more subject to interference. This module does not have a frequency hopping protocol built in.

Do not use any Linx product over the limits in this data guide. Excessive voltage or extended operation at the maximum voltage could cause product failure. Exceeding the reflow temperature profile could cause product failure which is not immediately evident.

Do not make any physical or electrical modifications to any Linx product. This will void the warranty and regulatory and UL certifications and may cause product failure which is not immediately evident.

Table of Contents

1	Description
1	Features
1	Applications
2	Ordering Information
2	Absolute Maximum Ratings
2	Timings
3	Electrical Specifications
4	Pin Assignments
6	Remote Control Overview
8	HS Series Overview
10	HS Series Security Overview
12	Decoder Power-Up
12	Decoder Receive Mode
13	Decoder Create Key Mode
14	Decoder Learn Mode
15	Decoder TX ID
16	Send Copy Mode
16	Get Copy Mode
17	Decoder MODE_IND Definitions
20	Typical Applications
21	Typical System Setup
22	Design Steps to Using the HS Series
25	System Expansion
27	Recommended Pad Layout
27	Production Considerations

HS Series Remote Control Decoder

Data Guide



Description

HS Series encoders and decoders are designed for maximum security remote control applications. Together, they allow the status of up to eight buttons or contacts to be transferred via a highly secure encrypted transmission intended for wireless links. The HS Series uses CipherLinX™ technology, which is based on the Skipjack algorithm developed by the U.S. National Security Agency (NSA) and has been independently evaluated by ISE. CipherLinX™ never sends or accepts the same data twice, never loses sync, and changes codes on every packet, not just every button press. In addition to state-of-the-art security, the tiny 20-pin SSOP packaged parts also offer innovative features, including up to 8 data lines, multiple baud rates, individual "button level" permissions, keypad user PIN, encoder identity output at the decoder, low power consumption, and easy setup.

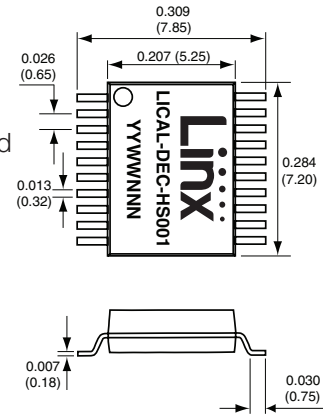


Figure 1: Package Dimensions



Features

- CipherLinX™ security technology
- ISE evaluated
- Never sends the same packet twice
- Never loses sync
- PIN-protected encoder access
- 8 selectable data lines
- "Button level" permissions
- Encoder ID available at decoder
- Wide 2.0 to 5.5V operating voltage
- Low supply current (370µA @ 3V)
- Ultra-low 0.1µA sleep current
- Selectable baud rates
- No programmer required
- Small SMD package

Applications

- Keyless entry / access control
- Door and gate openers
- Security systems
- Remote device control
- Car alarms / starters
- Home / industrial automation
- Remote status monitoring

Ordering Information

Ordering Information	
Part Number	Description
LICAL-ENC-HS001	HS Encoder
LICAL-DEC-HS001	HS Decoder
MDEV-LICAL-HS	HS Master Development System
HS decoders are shipped in reels of 1,600	

Figure 2: Ordering Information

Absolute Maximum Ratings

Absolute Maximum Ratings				
Supply Voltage V_{CC}	-0.3	to	+6.5	VDC
Any Input or Output Pin	-0.3	to	$V_{CC} + 0.3$	VDC
Max. Current Sourced by Output Pins		25		mA
Max. Current Sunk by Input Pins		25		mA
Max. Current Into V_{CC}		250		mA
Max. Current Out Of GND		300		mA
Operating Temperature	-40	to	+85	°C
Storage Temperature	-65	to	+150	°C
Exceeding any of the limits of this section may lead to permanent damage to the device. Furthermore, extended operation at these maximum ratings may reduce the life of this device.				

Figure 3: Absolute Maximum Ratings

Timings

Encoder SEND to Decoder Activation Times (ms)	
Baud Rate	Decoder Activation Time
4,800	67
28,800	36

Figure 4: Encoder SEND to Decoder Activation Times (ms)

Electrical Specifications

HS Series Decoder Specifications						
Parameter	Symbol	Min.	Typ.	Max.	Units	Notes
Power Supply						
Operating Voltage	V_{CC}	2.0		5.5	VDC	
Supply Current	I_{CC}					
At 2.0V V_{CC}			240	300	μA	1
At 3.0V V_{CC}			370	470	μA	1
At 5.0V V_{CC}			670	780	μA	1
Power Down Current	I_{PDN}					
At 2.0V V_{CC}			0.10	0.80	μA	
At 3.0V V_{CC}			0.10	0.85	μA	
At 5.0V V_{CC}			0.20	0.95	μA	
Decoder Section						
Input Low	V_{IL}	0.0		$0.15 \times V_{CC}$	V	2
Input High	V_{IH}	$0.8 \times V_{CC}$		V_{CC}	V	3
Output Low	V_{OL}			0.6	V	
Output High	V_{OH}	$V_{CC} - 0.7$			V	
Input Sink Current				25	mA	
Output Drive Current				25	mA	
Environmental						
Operating Temperature Range		-40		+85	°C	
<ol style="list-style-type: none"> Current consumption with no active loads. For 3V supply, $(0.15 \times 3.0) = 0.45V$ max. For 3V supply, $(0.8 \times 3.0) = 2.4V$ min. 						

Figure 5: Electrical Specifications



Warning: This product incorporates numerous static-sensitive components. Always wear an ESD wrist strap and observe proper ESD handling procedures when working with this device. Failure to observe this precaution may result in module damage or failure.

Pin Assignments

1	D6	LICAL-DEC-HS001	D5	20
2	D7		D4	19
3	SEL_BAUD		D3	18
4	SEND_COPY		D2	17
5	GND	VCC	D1	16
6	GND	VCC	D0	15
7	COPY_IN		D1	14
8	CREATE_KEY		D0	13
9	KEY_OUT	DATA_IN		12
10	MODE_IND	LEARN		11

Figure 6: HS Series Decoder Pin Assignments

Pin Descriptions			
Pin Number	Name	I/O	Description
1, 2, 13, 14, 17–20	D0–D7	O	Data Output Lines. These lines reproduce the state of the encoder's data lines upon reception of a valid packet.
3	SEL_BAUD	I	Baud Rate Selection Line. This line is used to select the baud rate of the serial data stream. If the line is high, the baud rate is 28,800bps, if it is low, the baud rate is 4,800bps. The baud rate must be set before power up. The transcoder will not recognize any change in the baud rate setting after it is on.
4	SEND_COPY	I	Send Copy Activation Line. When this line is taken high while the LEARN line is high, the decoder enters Send Copy Mode and outputs the User Data on the KEY_OUT line. When taken high while the CREATE_KEY line is high at power-up, Send Copy Mode is disabled.
5, 6	GND		Ground
7	COPY_IN	I	Copy Input Line. This line is used to input the User Data from another decoder.
8	CREATE_KEY	I	Create Key Activation Line. When this line is taken high while the LEARN line is high, the decoder enters Create Mode and creates a key and encoder ID. It then sends these to the encoder through the KEY_OUT line. When taken high while the SEND_COPY line is high at power-up, Send Copy Mode is disabled.
9	KEY_OUT	O	Key and Transmitter ID Output Line. When the SEND_COPY line is high when the LEARN line is taken high, the decoder outputs the User Data on this line. This line also outputs the transmitter identity upon reception of the first valid packet of each session.

10	MODE_IND	O	Mode Indicator Output. This line activates when a valid transmission is received, when the decoder enters Learn Mode, Get Key Mode, Create Key Mode, or Send Copy Mode, and when the memory is cleared. This allows for the connection of an LED to indicate to the user that these events are taking place.
11	LEARN	I	Learn Mode Activation Line. When this line goes high and is then pulled low, the decoder enters Learn Mode to accept permissions from an encoder and store it in memory. If it is held high for ten seconds, the decoder clears all User Data from memory. If it goes high while the SEND_COPY or CREATE_KEY lines are high, then the decoder enters Send Copy Mode or Create Key Mode, respectively.
12	DATA_IN	I	Data Input Line. This line accepts the encoded serial data stream from a receiver.
15, 16	V _{CC}		Supply Voltage

None of the input lines have internal pull-up or pull-down resistors. The input lines must always be in a known state (either GND or V_{CC}) at all times or the operation may not be predictable. The designer must ensure that the input lines are never floating, either by using external resistors, by tying the lines directly to GND or V_{CC}, or by use of other circuits to control the line state.

Figure 7: Pin Descriptions

Remote Control Overview

Wireless remote control is growing in popularity and finding its way into more unique applications. Remote Keyless Entry (RKE) systems for unlocking cars or opening garage doors quickly come to mind, but how about a trash container that signals the maintenance office when it needs to be emptied? The idea behind remote control is simple: a button press or contact closure on one end causes some action to be taken at the other. Implementation of the wireless RF stage has traditionally been complicated, but with the advent of simpler discrete solutions and modular products, such as those from Linx, implementation has become significantly easier.

Encoder and decoder ICs are generally employed to maintain the security and uniqueness of a wireless RF or IR link. These devices encode the status of inputs, usually button or contact closures, into a data stream suitable for wireless transmission. Upon successful recovery and validation, the decoder's outputs are set to replicate the states of the encoder's inputs. These outputs can then be used to control the circuitry required by the application.

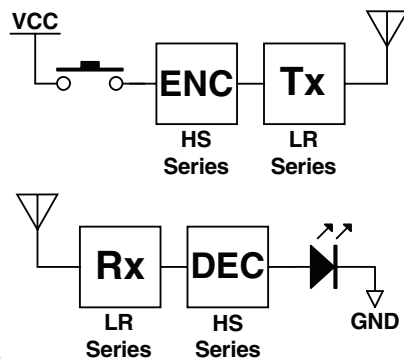


Figure 8: Remote Control Block Diagram

Prior to the arrival of the Linx HS Series, encoders and decoders typically fell into one of two categories. First were older generation, low-security devices that transmitted a fixed address code, usually set manually with a DIP switch. These products were easy to use, but had significant security vulnerabilities. Since they sent the same code in every transmission, they were subject to code grabbing. This is where an attacker records the transmission from an authorized transmitter and then replays the transmission to gain access to the system. Since the same code is transmitted every time, the decoder has no way to validate the transmission.

These concerns resulted in the development of a second type of encoder and decoder that focused on security and utilized a changing code to guard against code grabbing. Typically, the contents of each transmission changes based on complex mathematical algorithms to prevent someone from reusing a transmission. These devices gained rapid popularity due to their security and the elimination of manual switches; however,

they imposed some limitations of their own. Such devices typically offer a limited number of inputs, the transmitter and receiver can become desynchronized, and creating relationships and associations among groups of transmitters and receivers is difficult.

The HS Series offers the best of all worlds. The HS Series uses an advanced high security encryption algorithm called CipherLinx™ that never becomes desynchronized or sends the same packet twice. It is easily configured without production programming and allows for “button level” permissions and unique encoder and decoder relationships. Eight inputs are available, allowing a large number of buttons or contacts to be connected.

To learn more about different encoder and decoder methodologies, please refer to Application Note AN-00310.

HS Series Overview

The HS Series encoder encrypts the status of up to eight buttons or contacts into highly secure encrypted serial data stream intended for wireless transmission via an RF or infrared link. The series uses CipherLinX™ technology, which is based on the Skipjack algorithm developed by the United States National Security Agency (NSA). The CipherLinX™ protocol in the HS Series has been independently evaluated by Independent Security Evaluators (ISE). A full evaluation white paper is available at www.linxtechnologies.com/cipherlinx.

The encoder combines eight bits representing the states of the eight data lines with counter bits and integrity bits to form a 128-bit message. To prevent unauthorized access, this message is encrypted with CipherLinX™ in a mode of operation that provides data integrity as well as secrecy. CipherLinX™ never sends or accepts the same data twice, never loses sync, and changes codes with every packet, not just every button press.

Decoding of the received data signal is accomplished by a corresponding Linx HS Series decoder. When the decoder receives a valid command from an encoder, it activates its logic-level outputs, which can be used to control external circuitry. The encoder sends data continuously as long as the SEND line is held high. Each time the algorithm is executed, the counter is decremented, causing the code to be changed for each packet. This, combined with the large counter value and the timing associated with the protocol, ensures that the same transmission is never sent twice.

An 80-bit key used to encrypt the data is created in the decoder by the user. The decoder is placed into Create Key Mode, and a line is toggled 10 times, usually by a button. This is required to gather entropy to ensure that the key is random and chosen from all 2^{80} possible keys. A high-speed timer is triggered by each rise and fall of voltage, recording the time that the line is high and low. The 80-bit key is generated by combining the low-order bits of the twenty timer values. To create an association, the key, a 40-bit counter, and a decoder-generated ID are sent to the encoder via a wire, contacts, IR, or other secure serial connection.

The HS Series allows the end user or manufacturer to create associations between the encoder and decoder. If the encoder and decoder have been associated through a successful key exchange, then the decoder responds to the encoder's commands based on its permissions. If an encoder has not been associated with a decoder, its commands are not recognized.

The user or manufacturer may also set "button level" permissions. Permission settings control how the decoder responds to the reception of a valid command, either allowing the activation of an individual data line or not. The decoder is programmed with the permission settings during set-up, and those permissions are retained in the decoder's non-volatile memory.

The HS decoder has the ability to identify and output a decoder-assigned identification number for a specific encoder. An encoder's key, a 40-bit counter, and permissions are stored in one of fifteen memory locations within the decoder. The decoder is able to output an 8-bit binary number that corresponds to the memory location of the encoder's information. This provides the ability to identify the specific encoder from which a signal originated. This identification can be used in various ways, including systems that record access attempts or in applications where the originating user needs to be known.

HS Series Security Overview

Encryption algorithms are complex mathematical equations that use a number, called a key, to encrypt data before transmission. This is done so that unauthorized persons who may intercept the transmission cannot access the data. In order to decrypt the transmission, the decoder must use the same key that was used to encrypt it. The decoder performs the same calculations as the encoder and, if the key is the same, the data is recovered.

The HS Series uses the CipherLinX™ algorithm, which is based on Skipjack, a cipher designed by the U.S. National Security Agency (NSA). At the time of this writing, there are no known cryptographic attacks on the full Skipjack algorithm. Skipjack uses 80-bit keys to encipher 64-bit data blocks. The CipherLinX™ algorithm uses Skipjack in a provably secure authenticated encryption mode both to protect the secrecy of the data and ensure that it is not modified by an adversary. 8 bits of data are combined with a 40-bit counter and 80 bits of integrity protection before being encrypted to produce each 128-bit packet.

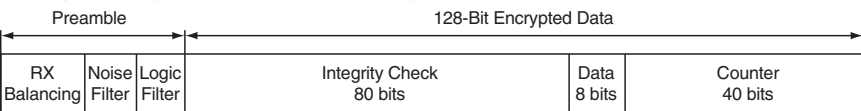


Figure 9: HS Series Data Structure

There are several methods an attacker may use to try to gain access to the data or the secured area. Because a key is used to interpret an encrypted message, trying to find the key is one way to attack the protected message. The attacker would either try using random numbers or go through all possible numbers sequentially to try to get the key and access the data. Because of this, it is sometimes believed that a larger key size determines the strength of the encryption. This is not entirely true. Although it is a factor in the equation, there are many other factors that need to be included to maintain secure encryption.

One factor is the way that the underlying cipher (in the case of the CipherLinX™ algorithm, Skipjack) is used to encrypt the data. This is referred to as the cipher’s “mode of operation.” If a highly secure cipher is used in an insecure mode, the resulting encryption is insecure. For example, some encryption modes allow an adversary to combine parts of legitimate encrypted messages together to create a new (and possibly malicious) encrypted message. This is known as a “cut-and-paste” attack. The mode of operation used by the CipherLinX™ algorithm is proven to prevent this type of attack.

Another critical factor is how often the message changes. To prevent code grabbing, most high-security systems send different data with each transmission. Some remote control systems encrypt the message once per activation and repeat the same message until it is deactivated. This gives an attacker the opportunity to copy the message and retransmit it to maintain the state of the protected device and “hold the door open”, or worse yet, be able to come back later and gain access. The HS Series goes a step further and sends different data with EACH PACKET, so the data changes continuously during each transmission. This means that at 28,800bps, there is a completely new 128-bit message sent every 25.5ms.

Another factor is how often the message is repeated and the intervals between repeats. Some applications use a counter to change the appearance of the message. This is good, but at some point, the counter rolls over and the message is repeated. For example, if attackers were to copy an encrypted message and save it, they could potentially gain access to the protected device at a later time. Depending on the size of the counter, this vulnerability could occur frequently. The HS Series uses a 40-bit decrementing counter to keep this from ever happening. If the SEND line is held high continuously at the high baud rate (28,800bps), it would take 889 years before the counter would reach zero, at which point the key would be erased and the encoder would have to get a new key. The math used is: $[(240 * 25.5ms) / (1000ms*60s*60m*24h*365d)] = 889 \text{ years}$. This large counter prevents a packet from ever being sent twice and prevents the encoder from ever losing sync with the decoder.

The key is generated with the decoder by the user through multiple button presses. This ensures that the key is random and chosen from all 2^{80} possible keys. Since all of the keys are created by the user and are internal to the part, there is no list of numbers anywhere that could be accessed to compromise the system.

Encryption of the transmitted data is only one factor in the security of a system. With most systems, once an encoder is authorized to access a decoder, it can activate all of the decoder data lines. With the HS Series, each encoder can be set to only activate certain lines. This means that the same hardware can be set up with multiple levels of control, all at the press of a button.

Another factor in system security is the control of the encoder. If attackers gain control of the encoder, typically they can access the system. The HS offers the option of adding a Personal Identification Number (PIN) to the

encoder that must be entered before the encoder activates. Furthermore, since each encoder has its own key and the Control Permissions are stored in the decoder, all the attackers would be able to do is duplicate the device that they have already taken. They will not be able to grant themselves greater authority, create a new controller, or replicate another encoder.

Before the encoder sends a packet, it calculates the Hamming Weight (the number of '1's in the string) of the packet to determine the duty cycle. If the duty cycle is greater than 50% (more '1's than '0's), the encoder logically inverts all of the bits. This ensures that every packet always contains 50% or less '1's. Since the FCC allows transmitter output power to be averaged over 100ms, this allows a legal improvement in link range and performance for many devices using an ASK / OOK transmitter. A 50% duty cycle is generally the best compromise between data volume and output power.

Some other manufacturers may use a Pulse Width Modulation (PWM) scheme or Manchester Encoding scheme to maintain a 50% duty cycle. Both of these methods work, but are inefficient and do not make use of the full link budget. The HS Series uses true serial data while maintaining a 50% duty cycle. Application Note AN-00310 covers these issues in detail.

Decoder Power-Up

When the decoder first powers up, it sets the baud rate and goes to sleep until: 1) the LEARN line is taken high, placing the decoder into Learn Mode, 2) a rising edge (low to high transition) on the COPY_IN line puts it into Get Copy Mode, or 3) a rising edge on the DATA_IN line puts it into Receive Mode.

Decoder Receive Mode

When a rising edge is seen on the DATA_IN line, the decoder enters Receive Mode. It begins by looking for a valid packet (meaning one that can be decrypted with the saved key) that has no errors. If the packet is valid, then the decoder replicates the Data byte on its data lines and pulls the MODE_IND line high. It also outputs a number that represents the ID of the encoder once when the first valid packet is received. The decoder then looks for the next valid packet. If an error is detected at any time, or if the transmission cannot be decrypted with the saved key, then the decoder ignores the packet and looks for the next one.

If no valid packet is detected within 262ms, the decoder goes back to sleep.

Decoder Create Key Mode

Create Key Mode is entered when the CREATE_KEY line is high when the LEARN line is taken high. When this happens, the MODE_IND line goes high as an indication that the decoder is ready to create the key. The CREATE_KEY line needs to go high ten times to set the key. Each edge on the line starts a timer that is used to populate a part of the key. This method is used to gather entropy so that the key is truly random and is chosen from among all 2^{80} possible keys.

Following the tenth press, the decoder begins to send the key to the encoder on the KEY_OUT line. This is output as a serial data stream, so it can be sent to the encoder by any method suitable for serial data transfer. This can include the use of a wire, contact points on an enclosure, or infrared. The HS Series Master Development System demonstrates wire and infrared transfer methods. Please refer to the development system User's Guide for circuit schematics and further details.

Once the encoder receives the key on its KEY_IN line, it sends a confirmation to the decoder through its DATA_OUT line. This means that the standard mode of communication, whether a wire, RF, or infrared, must be active. When the decoder receives this confirmation, it sends a final confirmation through the KEY_OUT line. The MODE_IND LED lines on the encoder and the decoder turn on for one second. This indicates that the encoder and decoder are now ready to be used. The decoder outputs the key information for seventeen seconds or until it receives a valid confirmation from the encoder. If Control Permissions are going to be used, they may now be set as described in the Decoder Learn Mode section.

Note that the CREATE_KEY line should be connected to a button or another contact that will give random times between presses. Connecting this line to a deterministic source, such as a microprocessor clock, does not produce a secure key and could compromise the system.

Decoder Learn Mode

Learn Mode serves several functions in the HS decoder. First, it provides the access point for other modes, such as Send Copy, Create Key, and Clear Memory. It also enables the decoder to learn the Control Permissions for an encoder. One of the most innovative features of the HS Series is its ability to establish a unique user identity and profile for the device containing the encoder. In other products, all encoded transmissions are either recognized or denied based on the address. In cases where encoder and decoder addresses match, the state of all data lines is recognized and output. The HS Series uniquely allows a user or manufacturer to define which encoder inputs are acknowledged by each decoder.

Consider this practical example: a three door garage houses Dad's Corvette, Mom's Mercedes, and Son's Yugo. With most competitive products, any user's keyfob could open any garage door as long as the addresses match. In a Linx HS-based system, the keyfobs could easily be configured to open only certain doors (guess which one Son gets to open!)

The decoder is placed into Learn Mode by pulling the LEARN line high and then taking it low within ten seconds. The decoder begins toggling the MODE_IND line to indicate that the decoder is ready to learn the Control Permissions for a specific encoder. On the encoder end, simply activate each data line that it should be allowed to access and the decoder records the lines that were activated as the Control Permissions. Pull the LEARN line high again or let the decoder timeout after 17 seconds, after which it automatically exits Learn Mode and returns to sleep.

The decoder can store up to 15 encoder IDs in memory. When the 15th encoder is learned, the decoder flashes the MODE_IND line five times as an indication that the memory is full. The next address learned overwrites the first address in memory. This must be clearly conveyed to the end user, since system users' access would be affected by the overwrites. The memory retains all of the learned encoders if power is removed.

If the LEARN line is held high for ten seconds, the decoder erases all of the saved User Data from memory. The MODE_IND line is high for as long as the LEARN line is high, but after ten seconds, it goes low. Once the LEARN line is pulled low again, the MODE_IND line goes high for two seconds to indicate that the memory has been cleared.

If the SEND_COPY line is high when the LEARN line goes high, the decoder enters Send Copy Mode. Once in this mode, the state of the LEARN line is not checked again, so it can be held high or pulled to ground, whichever is more convenient for the application.

If the CREATE_KEY line is high when the LEARN line goes high, the decoder enters Create Key Mode.

Decoder TX ID

Upon receipt of the first valid packet, the decoder outputs a binary number on the KEY_OUT line that corresponds to one of the learned transmitters. It outputs the number only once, as soon as the first packet is accepted. An encoder's key, a 40-bit counter, and permissions are stored in one of 15 memory locations within the decoder. The decoder is able to output an 8-bit binary number that corresponds to the memory location of the encoder's information. The first encoder that is learned is assigned 1, the second is assigned 2 and so on. Once assigned, it is an easy task for a software program to read that number and associate it with a particular encoder. This makes applications such as logging access attempts simple.

The ID is output asynchronously as an eight-bit binary number at the baud rate selected by the SEL_BAUD line. For example, if the SEL_BAUD line is grounded and the first encoder that the decoder learned sends a signal, then once the first packet is received, the decoder outputs '0000 0001' (binary 1) at 2,400bps on the KEY_OUT line.

Application Note AN-00156 shows an example program that reads this number and displays it on an LCD screen. The code is written in C and is well documented so that it can be easily modified for a specific application. The code and include files can be downloaded as a .zip file from the Linx website.

Send Copy Mode

The HS Series decoder has the ability to send a copy of all of the learned encoders to another decoder. This makes it possible to use the same transmitter, encoder, and Control Permissions in multiple locations. Send Copy Mode is entered when the SEND_COPY line is high when the LEARN line is taken high. Once in this mode, the decoder outputs all of its User Data on the KEY_OUT line for asynchronous transfer to another HS Series decoder. The decoder that receives the User Data becomes a copy and loses the ability to create a key and send a copy. It can only set Control Permissions until its memory is erased, at which point it regains full functionality.

The two decoders need to be connected together with some method of transferring asynchronous serial data, such as a wire or short-range infrared. RF is not recommended for this transfer because it can represent a security risk, since RF is broadcast in all directions. A wire is the most secure method of transfer. Simply connect the KEY_OUT of the originating decoder to the COPY_IN line of the receiving decoder and connect the COPY_IN of the originating decoder to the KEY_OUT of the receiving decoder. Then connect the ground lines together and send the data (refer to Figure 15).

The Send Copy feature can be disabled by setting the SEND_COPY and CREATE_KEY lines high when the decoder is powered on. The MODE_IND line blinks three times to indicate that this has taken place. The decoder cannot send a copy of its User Data again until its memory is cleared.

Get Copy Mode

Get Copy Mode is entered when valid data is present on the COPY_IN line. The decoder reads the User Data from another decoder and saves it in non-volatile memory. If the decoder is made into a copy of another decoder, it cannot send the copy or to create new keys. All of the User Data needs to be erased before the decoder can create new keys. This is done by holding the LEARN line high for ten seconds.

Decoder MODE_IND Definitions

The MODE_IND line is the primary means of indicating the state of the decoder to the user. The table below gives the definitions of the MODE_IND signals.

HS Series Decoder MODE_IND Definitions	
MODE_IND	Definitions
Create Key Mode	ON during the key generation process and OFF when created. Then ON for 1 second after the key has been successfully transferred and the user profile is saved. After the 15th user profile has been saved, it blinks* 5 times. The next user profile overwrites the first.
Learn Mode	ON while the LEARN line is HIGH until taken LOW to enter Learn Mode, then it flashes* for 15 seconds until time-out or until the LEARN line goes HIGH again.
Erase Mode	ON while the LEARN line is held HIGH for 10 seconds and Erase Mode is entered, then it turns OFF. It turns back ON again for 2 seconds when erase is completed.
Send Copy Mode	ON for the duration of this mode.
Get Copy Mode	Blinks* each time a user profile has been successfully transferred and saved. If all user profiles have been successfully received, it blinks* twice.
Disable Send Copy	Blinks* three times when Send Copy is disabled.
*Blink = ON for 1sec and OFF 1/2sec	
*Flash = ON for 200ms and OFF for 200ms	

Figure 10: HS Series Decoder MODE_IND Definitions

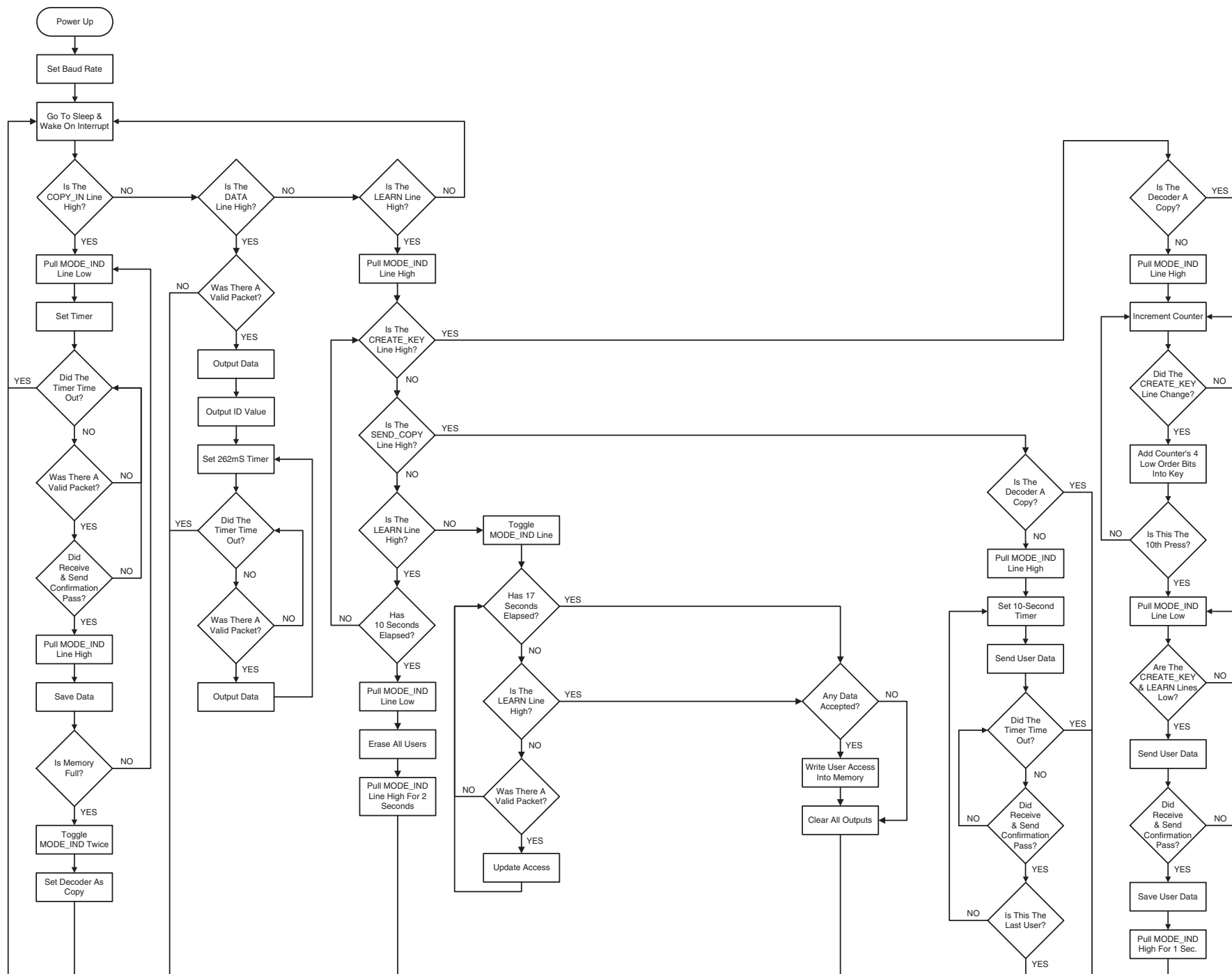


Figure 11: HS Series Decoder Flowchart

Typical Applications

The HS Series is ideal for registering button presses in secure remote control applications. An example application circuit of the decoder side is shown in Figure 12.

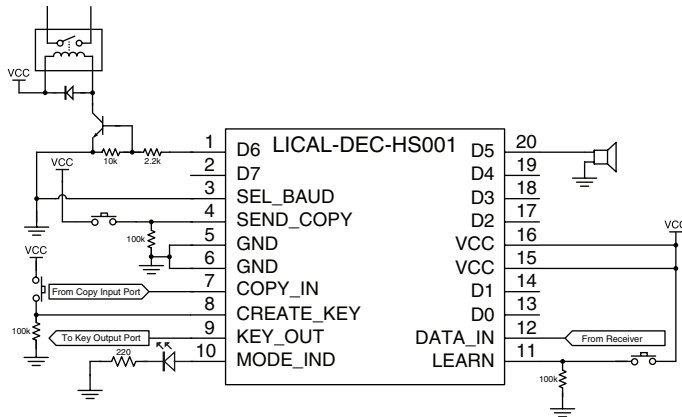


Figure 12: HS Series Decoder Application Circuit

In this circuit, the baud has been set for 2,400bps by pulling the SEL_BAUD line to ground.

SEND_COPY, CREATE_KEY, and LEARN are all connected to buttons that pull the line high when pressed. Since the lines do not have internal resistors, 100k Ω resistors are used to pull the lines to ground when the buttons are not pressed.

COPY_IN is connected to a port that allows the transfer of the User Data from another decoder. This port can be a simple wire, an infrared receiver, or any other circuit that transfers asynchronous serial data.

The KEY_OUT line is connected to a port that allows the transfer of the key to an encoder or another decoder. This port can be a simple wire, an infrared diode, or any other device that transfers asynchronous serial data.

The KEY_OUT line can also be connected to a microprocessor or a PC to record the transmitter identity. Application Note AN-00156 has sample C code that reads the transmitter ID and displays it on an LCD screen.

An LED indicator is attached to the MODE_IND line to provide visual feedback that an operation is taking place. This line sources a maximum of 25mA.

The DATA_IN line is connected directly to the data output of the receiver.

Data Lines D0 through D7 can be connected directly to the external circuitry that is to be activated remotely. In this example, D5 is connected directly to a piezoelectric buzzer, which causes the buzzer to sound when the D5 line on the encoder goes high. Line D6 activates a relay through a transistor buffer when it goes high. A buffer like this may be needed if the decoder cannot source enough current or voltage to energize the relay coil. The decoder turns on the transistor, which provides the appropriate drive levels to the relay.

Typical System Setup

The HS Series offers an unmatched combination of features and security, yet is easy for system designers and end users to operate. To demonstrate this, let's take a brief look at a typical user setup followed by more detailed design information. The Typical Applications sections of the encoder and decoder data guides show the circuit schematics on which these examples are based.

1. Create and exchange a key from a decoder to an encoder.

The high security key is created and exchanged by placing the decoder in the Create Key Mode. The decoder's MODE_IND line LED lights to indicate that the decoder has entered Create Key Mode. The decoder's CREATE_KEY button is then pressed ten times to create the key. After the tenth press, the MODE_IND LED turns off and the decoder sends the key out of the KEY_OUT line. The MODE_IND LED on the encoder lights to indicate that the key has been successfully transferred.

2. Establish Control Permissions

The user establishes what buttons on the encoder are recognized by pressing the decoder's LEARN button. The decoder's MODE_IND LED starts flashing and the user presses the encoder buttons that should be allowed access. Control Permissions are stored when the LEARN button is pressed again or automatically after 17 seconds.

There are other powerful options such as programming a user PIN or copying a decoder but these simple steps are all that is required for a typical setup. It is really that simple for a manufacturer or end user to setup the product!

Design Steps to Using the HS Series

Key Creation and Exchange from a Decoder to an Encoder.

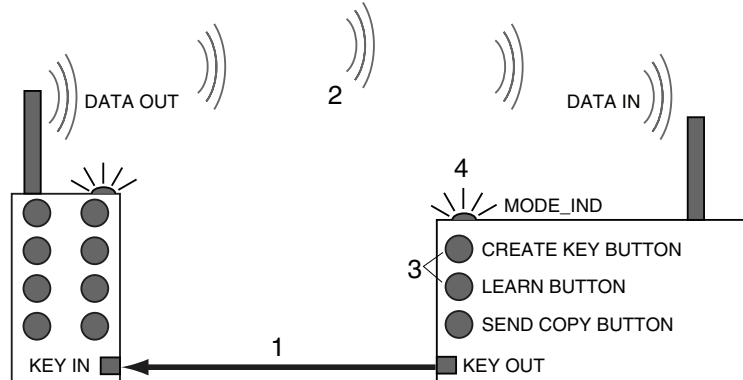


Figure 13: Steps to Exchange a Key

1. Provide a serial data connection from the decoder's KEY_OUT line to the encoder's KEY_IN line. Typically this would be a wire, contact, or infrared.
2. Provide a serial data connection from the encoder's DATA_OUT line to the decoder's DATA_IN line. Typically, this would be a wireless connection using a transmitter and receiver combination.
3. On the decoder, set the CREATE_KEY line high and then the LEARN line high to enter Create Key Mode. Take the LEARN line low and toggle the CREATE_KEY line high and low ten times to generate the key.
4. The encoder and decoder automatically exchange the key using the DATA_OUT / DATA_IN and KEY_OUT / KEY_IN lines. If the key exchange is successful, the decoder and encoder MODE_IND lines go high for 1 second.

Creation of Control Permissions

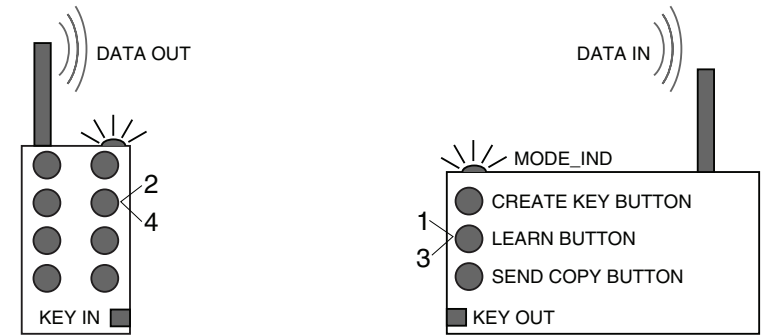


Figure 14: Steps to Create Control Permissions

1. On the decoder, set the LEARN line high, then take it low to enter Learn Mode.
2. While the decoder's MODE_IND line is toggling high / low, set a data line on the encoder high, then low. Repeat for each line that should be granted permission to activate the decoder.
3. After all the desired data lines have been selected, set the LEARN line high, then low again, or wait until the 17-second time-out occurs. The permissions are now be saved in the decoder.
4. Select the data lines during an actual transmission to confirm that the permissions have been successfully created.

Send a Copy of Decoder A User Data to Decoder B

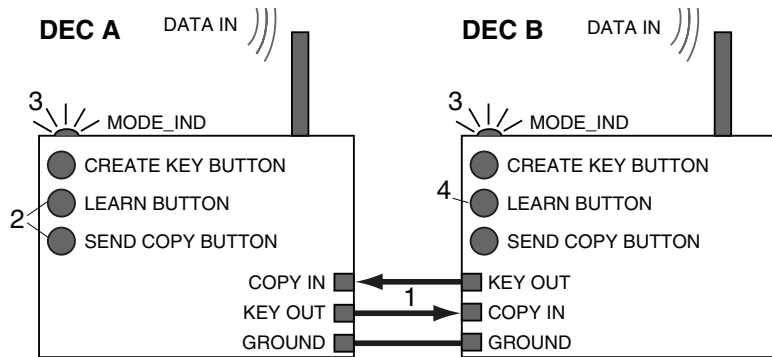


Figure 15: Steps to Send a Copy

1. Provide a serial data connection from decoder A's KEY_OUT line to decoder B's COPY_IN line, and decoder B's KEY_OUT line to decoder A's COPY_IN line.
2. On decoder A, set the SEND_COPY line high and then set the LEARN line high to enter Send Copy Mode. Next, take both lines low.
3. The MODE_IND line on decoder A is set high while data is being exchanged. The MODE_IND line on decoder B toggles as each user profile is being received from decoder A. If a successful copy has been made, the MODE_IND on decoder B blinks twice.
4. The copied decoder B is only allowed to learn new permissions from the copied set of users and activate data lines accordingly. All other features are removed from decoder B until its memory is successfully erased.

System Expansion

A system based on the HS Series can be expanded in several ways. One of the simplest is to add users by adding more decoders to the receiver output. With each decoder added to the chain, another 15 encoders can be used within the system. The associated decoder data line outputs can be connected together so that any decoder activates the circuit. So, if Data Line D1 is being used to activate a relay, then the D1 lines of Decoders A, B, and C can all be connected to the input of the relay. Diodes are needed to isolate the active line from the inactive lines, preventing a short circuit.

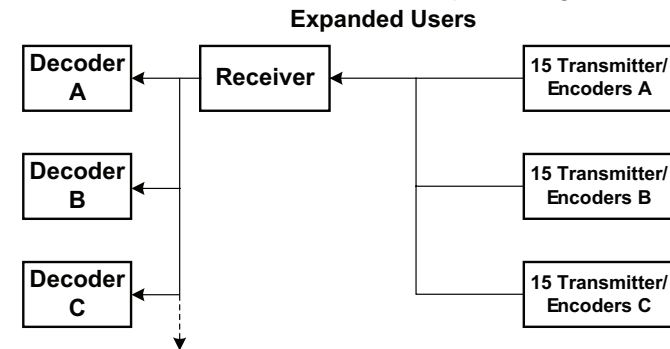


Figure 16: Expanding Users with the HS Series

The ability of the HS Series decoder to create copies of itself allows for the expansion of access points within a system. This means that the same encoder can access multiple locations without any hardware changes. An example of this would be a single keyfob transmitter that can open the front door of a building and the supply room. A master decoder is first set up with all of the users for the system. It is then connected to other HS Series decoders to transfer its User Data. These copies are then deployed in other locations and will respond to an encoder the same way the master system will. For greater security, these copies cannot make other copies or add new users, just change Control Permissions. Because of this, it is recommended that only copies are used in the system while the original is stored in a secure location. This is particularly useful in settings where access to the decoder cannot be strictly limited.

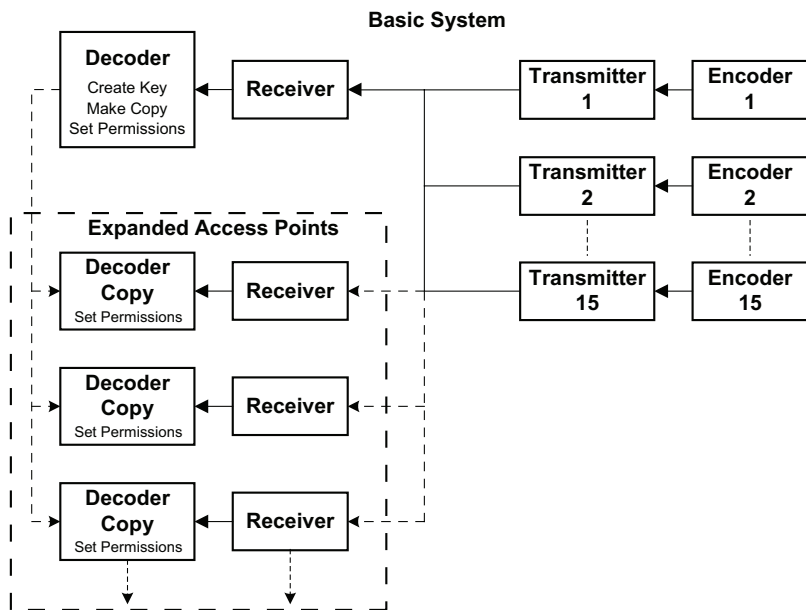


Figure 17: Expanding Access Points with the HS Series

Recommended Pad Layout

The HS Series encoders and decoders are implemented in an industry standard 20-pin Shrink Small Outline Package (20-SSOP). The recommended layout dimensions are shown in Figure 18.

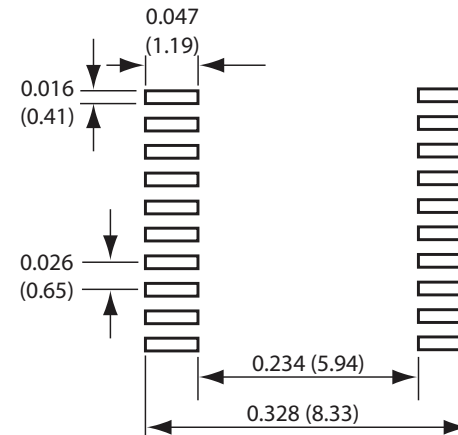


Figure 18: PCB Layout Dimensions

Production Considerations

These surface-mount components are designed to comply with standard reflow production methods. The recommended reflow profile is shown in Figure 19 and should not be exceeded, as permanent damage to the part may result.

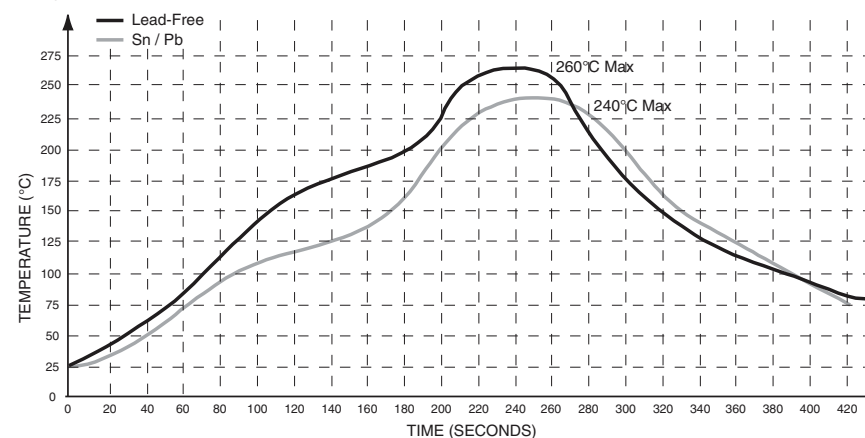


Figure 19: HS Series Reflow Profile



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