

PCA9522

Fast dual bidirectional bus buffer with hot insertion logic

Rev. 1 — 28 September 2011

Product data sheet

1. General description

The PCA9522 is a monolithic bipolar integrated circuit for bus buffering in applications including I²C-bus, SMBus, etc. It includes hot insertion logic for detecting stop and idle conditions, making it ideal for live insertion into backplanes. The buffer extends the bus load limit by buffering both the SCL and SDA lines. The PCA9522 is a drop-in replacement for the IES5502, with only the maximum bus voltage reduced from 15 V to 10 V.

Hot insertion logic allows the IC to be plugged into live backplanes without causing data corruption on the bus. The open-collector ready signal (RDY) indicates when the connection has been made. Precharging of the backplane ports minimizes disruptions to the bus during hot insertion.

The enable function allows sections of the bus to be isolated. Individual parts of the system can be brought on-line successively. Bus level translation between a very wide range of bus voltages, from 1.8 V to 10 V, is supported. These features provide enormous flexibility in interfacing systems of different technologies, operating speeds and loads.

The unique operation of the PCA9522 provides one of the fastest response times of such bidirectional buffers. It does this without the need for rise-time accelerators which, combined with low noise margins, may cause glitches outside of the I²C-bus specification.

2. Features and benefits

- Dual, bidirectional unity gain isolating buffer
- Hot insertion logic prevents data and clock bus corruption for live backplane applications
- Pre-charge minimizes data corruption on live insertion
- Supports I²C-bus (Standard-mode and Fast-mode), SMBus (standard and high power modes) and PMBus
- Open-collector ready output (RDY)
- Fast switching times allow operation in excess of 1 MHz
- Enable (EN) allows bus segments to be disconnected
- Low current standby mode when not enabled
- High-impedance ports when IC unpowered
- 6 mA (static) pull-down capability
- Low noise susceptibility
- Supports the connection of several buffers in series
- Level shift bus voltages from 1.8 V to 10 V



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3. Applications

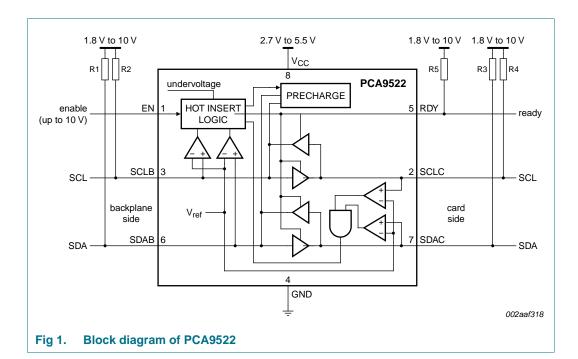
- Backplane management/interconnect
- Telecommunications systems including ATCA
- Desktop and portable computers including RAID

4. Ordering information

Table 1. Ordering information

Type number	Topside	Package		
	mark	Name	Description	Version
PCA9522D	PCA9522	SO8	plastic small outline package; 8 leads; body width 3.9 mm	SOT96-1
PCA9522DP	9522	TSSOP8	plastic thin shrink small outline package; 8 leads; body width 3 mm	SOT505-1

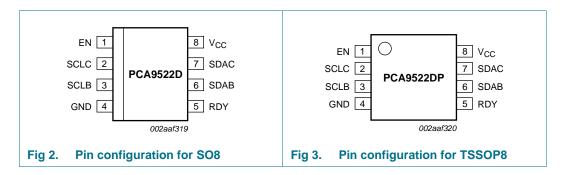
5. Block diagram



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6. Pinning information

6.1 Pinning



6.2 Pin description

Table 2. Pin description

Symbol	Pin	Description
EN	1	enable
SCLC	2	SCL buffer, card side[1]
SCLB	3	SCL buffer, backplane side ^[2]
GND	4	supply ground
RDY	5	ready
SDAB	6	SDA buffer, backplane side[2]
SDAC	7	SDA buffer, card side[1]
V _{CC}	8	positive supply

^[1] Card side is equivalent to SCL_OUT / SDA_OUT.

^[2] Backplane side is equivalent to SCL_IN / SDA_IN.

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7. Functional description

Refer to Figure 1 "Block diagram of PCA9522".

7.1 V_{CC} , GND — supply pins

The PCA9522 can be driven from voltage supplies ranging from 2.7 V to 5.5 V. The threshold level below which the output will begin to match the input is 33 % of V_{CC} . Hence, the operating voltage should be chosen with the required bus voltage, switching threshold, and noise margins in mind.

7.2 SCLB, SCLC, SDAB, SDAC — buffer inputs/outputs

The two open-collector buffers (SCL and SDA) are identical and symmetrical. The buffers can be driven from either direction, with the same buffering response. However, the hot insertion logic is determined from the 'backplane' (SxxB) sides of the buffers. When the one side (e.g., SxxB) of the buffer is being driven LOW (<0.3 V_{CC}) by another device on the bus, the other side (e.g., SxxC) will be driven LOW by the IC to provide the buffered output.

The 'control' or 'input' side is determined by the lowest externally driven signal. Therefore if the 'input' is externally pulled to $V_{SxxB} = 250$ mV, and the 'output' is externally pulled to $V_{SxxC} = 500$ mV, the buffer will pull the 'output' down further such that it becomes $V_{SxxC} = V_{SxxB} + V_{offset}$. Should the 'output' subsequently become lower than the 'input' by means of an external device pulling it LOW ($V_{SxxC} < V_{SxxB}$), control of the buffering operation will switch sides. The voltage at the 'input' will then become $V_{SxxB} = V_{SxxC} + V_{offset}$. Many bus buffers are prone to causing glitches during control transition, but the PCA9522 shows negligible glitching even under the worst operating conditions.

7.3 Enable (EN) — activate buffer operations

The enable input (EN) is used to disable the buffer, for the purpose of isolating sections of the bus. The IC should only be disabled when the bus is idle, to prevent truncation of commands which may confuse other devices on the bus.

Upon receiving a valid enable (EN) signal, the IC will wait to detect either a bus STOP condition, or an IDLE condition as described in the I²C-bus [Ref. 1] and SMBus [Ref. 2] specifications. This ensures that truncated transmissions are not communicated along the newly enabled bus segment.

Enable may be used to progressively activate sections of the bus during system start-up. Bus sections slow to respond on power-up can be kept isolated from the main system to avoid interference and collisions.

The EN pin may be pulled up higher than the V_{CC} of the buffer, further enhancing the capability of the PCA9522 in a level shifting role. For example, a microprocessor could drive EN, SCLB and SDAB at 5 V, while the buffer V_{CC} , SCLC and SDAC ports are at 3.3 V.

Similarly, the threshold level of the EN pin allows a 1.8 V device to enable an PCA9522 with a V_{CC} of 3.3 V.

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7.4 Ready (RDY) — buffer connected indicator

The ready output (RDY) indicates that the buffer has met its enable conditions, and that communication will now occur. This is an open-collector transistor which is switched off when ready, allowing the voltage at the pin to be pulled HIGH by a pull-up resistor.

7.5 Start-up

During power-up or live insertion into backplanes, the PCA9522 will start-up in an UnderVoltage LockOut (UVLO) state where any activity on the input/output ports will be ignored. This is to ensure that the PCA9522 does not try to operate when there is not enough voltage on the supply.

During this time, the precharge circuit will charge all SCLB/SDAB backplane ports to typically 0.92 V. This will minimize any voltage difference between the ports and hence minimizes disruptions to the bus during hot insertion into backplanes.

When the supply increases above the UVLO state the PCA9522 will then monitor the bus for either stop bit or bus idle condition. When a stop bit condition is detected and SCLC/SDAC are both idle or when all SCL/SDA ports idle for a time period of typically 95 μs , then the PCA9522 will activate the input-output connection circuitry. The precharge circuitry is switched off. The voltage at the RDY pin is pulled HIGH by an external pull-up resistor to indicate the input/output connection has been made.

8. Limiting values

Table 3. Limiting values
In accordance with the Absolute Maximum Rating System (IEC 60134).

P_{tot} total power dissipation - 300 mV T_{stg} storage temperature -55 +125 °C	Symbol	Parameter	Conditions	Min	Max	Unit
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	V_{CC}	supply voltage		<u>[1]</u> -0.3	+7	V
I _{IO} input/output current DC; any pin - 20 mA P _{tot} total power dissipation - 300 mV T _{stg} storage temperature -55 +125 °C	V _n	voltage on any other pin	, ,	[1] -0.3	+12	V
P_{tot} total power dissipation - 300 mV T_{stg} storage temperature -55 +125 °C	V _{I(EN)}	input voltage on pin EN		<u>[1]</u> –0.3	+12	V
T_{stg} storage temperature -55 +125 °C	I _{IO}	input/output current	DC; any pin	-	20	mA
	P _{tot}	total power dissipation		-	300	mW
T ambient terrenesture energias 40 cm	T _{stg}	storage temperature		-55	+125	°C
T _{amb} ambient temperature operating -40 +85 °C	T _{amb}	ambient temperature	operating	-40	+85	°C

^[1] Voltages are specified with respect to pin 4 (GND).

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9. Characteristics

Table 4. Characteristics

 T_{amb} = -40 °C to +85 °C; voltages are specified with respect to ground (GND).

Start-up circuity	Symbol	Parameter	Conditions	Min	Тур	Max	Unit
	Power supp	oly					
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	V _{CC}	supply voltage	operating	2.7	-	5.5	V
Various Var	I _{CC}	supply current	operating; $V_{CC} = V_{I(EN)} = 5.5 \text{ V}$	-	9	-	mA
Verticon Vorticon Vortic			standby; $V_{CC} = 5.5 \text{ V}$; $V_{I(EN)} = 0 \text{ V}$	-	520	-	μΑ
threshold voltage V _{Scott} floating; V _{CC} = 3.3 V; v _{V(EN)} > 1.2 V 0.92 v v _V I _{pch} precharge current V _{Scott} floating; V _{CC} = 3.3 V; v _{V(EN)} > 1.2 V - 11 v _V µ V _{th} threshold voltage logic input logic output - 0.5V _{CC} v _V - V Buffer ports (SCLB, SCLC, SDAB, SDAC) V _{th} bus voltage - - 10 v _V V V _{th} (IL) LOW-level input threshold voltage - - 0.3V _{CC} v _V V V _{th} (IH) HIGH-level input threshold voltage - - 10 v _V V V _{th} (IH) HIGH-level input current drive current; V _{bus} < V _{CC} - - 0.3V _{CC} v _V V V _{th} (IH) HIGH-level input current drive current; V _{bus} < V _{CC} - - - - 0.3V _{CC} v _V V V _{th} (IH) HIGH-level input current drive current; V _{bus} < V _{CC} - - - - - - m M V _{th} (IH) HIGH	Start-up cir	cuitry					
	$V_{th(UVLO)}$		$V_{CC} = V_{I(EN)} = 5.5 \text{ V}$	-	2.2	-	V
V _{IEND} > 1.2 V V _{Image} Interested voltage	V_{pch}	precharge voltage		-	0.92	-	V
Suffer ports (SCLB, SCLC, SDAB, SDAC) SUbus Subus voltage Subus volta	I _{pch}	precharge current		-	11	-	μΑ
Buffer ports (SCLB, SCLC, SDAB, SDAC) Vbus bus voltage - - 10 V Vth(IL) LOW-level input threshold voltage - - - 0.3V _{CC} V Vth(IH) HIGH-level input threshold voltage 0.41V _{CC} - - - - V It LOW-level input current drive current; V _{bus} < V _{CC} - - - - mA Volisink) output sink current LOW-level; V _{bus} (out) = 0.4 V 6 - - mA Volisink) output sink current LOW-level; V _{bus} (out) = 0.4 V 6 - - mA Volisink) output sink current LOW-level; V _{bus} (out) = 0.4 V 6 - - mA Volfiset offset voltage input/output; V _{CC} = 3.3 V - 165 200 mV Io_L = 4 mA; V _{bus} (in) = 50 mV - 165 200 mV Io_L = 1.2 mA; V _{bus} (in) = 50 mV - 60 100 mV Valisic <td< td=""><td>V_{th}</td><td>threshold voltage</td><td>logic input</td><td>-</td><td>$0.5V_{CC}$</td><td>-</td><td>V</td></td<>	V_{th}	threshold voltage	logic input	-	$0.5V_{CC}$	-	V
Vbus bus voltage - - 10 V Vb(h(IL) LOW-level input threshold voltage - - 10 V Vb(H(IH) HIGH-level input threshold voltage - - - - - V IIL LOW-level input current drive current; Vbus< Vcc - <th< td=""><td></td><td></td><td>logic output</td><td>-</td><td>$0.5V_{CC}$</td><td>-</td><td>V</td></th<>			logic output	-	$0.5V_{CC}$	-	V
$V_{th(IL)} \begin{array}{c} LOW-level input \\ threshold voltage \\ \end{array} \begin{array}{c} - \\ V_{th(IH)} \\ \end{array} \begin{array}{c} I_{IIC} \\ I_{IL} \\ I_{IL} \\ I_{O(sink)} \\ \end{array} \begin{array}{c} I_{OUS} \\ I_{OUS} \\ I_{OUS} \\ I_{OUS} \\ \end{array} \begin{array}{c} I_{OUS} \\ I_{OUS} \\ I_{OUS} \\ I_{OUS} \\ \end{array} \begin{array}{c} I_{OUS} \\ I_{OUS} \\$	Buffer ports	s (SCLB, SCLC, SDAB, SDA	AC)				
$V_{th(H)} \begin{tabular}{ll} HIGH-level input threshold voltage \\ V_{th(H)} \begin{tabular}{ll} HIGH-level input threshold voltage \\ I_{IL} \begin{tabular}{ll} LOW-level input current threshold voltage \\ I_{IL} \begin{tabular}{ll} LOW-level input current threshold voltage \\ I_{O(sink)} \begin{tabular}{ll} output sink current threshold voltage \\ I_{O(sink)} \begin{tabular}{ll} Other voltage \\ I_{O(sink)} \begin{tabular}{ll} Other voltage \\ I_{OL} = 4 mA; V_{bus(in)} = 50 mV \\ I_{OL} = 500 \ \mu A; V_{bus(in)} = 50 mV \\ I_{OL} = 500 \ \mu A; V_{bus(in)} = 50 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 50 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 50 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 50 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 50 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 50 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{OL} = 1.2 \ m A; V_{bus(in)} = 200 mV \\ I_{O$	V _{bus}	bus voltage		-	-	10	V
threshold voltage $I_{IL} \qquad LOW-level input current \\ I_{O(sink)} \qquad \text{output sink current} \qquad \text{drive current; } V_{\text{bus}} < V_{\text{CC}} \qquad - \qquad -10 \qquad -20 \qquad \mu\text{A} \\ I_{O(sink)} \qquad \text{output sink current} \qquad LOW-level; V_{\text{bus}(out)} = 0.4 \text{V} \qquad 6 \qquad - \qquad - \qquad \text{mA} \\ V_{\text{Offset}} \qquad \text{offset voltage} \qquad \qquad \begin{array}{c} \text{input/output; } V_{\text{CC}} = 3.3 \text{V} \\ \\ I_{OL} = 4 \text{mA; } V_{\text{bus}(in)} = 50 \text{mV} \qquad - \qquad 165 \qquad 200 \qquad \text{mV} \\ I_{OL} = 500 \mu\text{A; } V_{\text{bus}(in)} = 50 \text{mV} \qquad - \qquad 55 \qquad 100 \qquad \text{mV} \\ I_{OL} = 1.2 \text{mA; } V_{\text{bus}(in)} = 200 \text{mV} \qquad - \qquad 600 \qquad 100 \qquad \text{mV} \\ I_{OL} = 1.2 \text{mA; } V_{\text{bus}(in)} = 200 \text{mV} \qquad - \qquad 600 \qquad 100 \qquad \text{mV} \\ I_{OL} = 1.2 \text{mA; } V_{\text{bus}(in)} = 200 \text{mV} \qquad - \qquad - \qquad 5 \qquad \mu\text{A} \\ \hline \textbf{Enable (EN)} \\ V_{\text{Ven}} \qquad \text{enable voltage} \qquad \text{active} \qquad \qquad 1.2 \qquad - \qquad - \qquad V \\ V_{\text{dis}} \qquad \text{disable voltage} \qquad \text{standby} \qquad - \qquad - \qquad 0.7 V \\ V_{\text{I}} \qquad \text{input current} \qquad V_{\text{en}} > 1.2 V \qquad \qquad 1 \qquad - \qquad 5 \qquad \mu\text{A} \\ \hline \textbf{Ready (RDY)} \\ V_{\text{OL}(RDY)} \qquad LOW-level output voltage \qquad I_{\text{pu}} = 3 \text{mA} \qquad - \qquad - \qquad - \qquad 400 \qquad \text{mV} \\ I_{L} \qquad \text{leakage current} \qquad V_{\text{OL}(RDY)} = V_{\text{CC}} \qquad - \qquad - \qquad \pm 5 \qquad \mu\text{A} \\ \hline \textbf{Timing characteristics (I)} \\ \hline t_{\text{d}} \qquad \text{delay time} \qquad V_{\text{CC}} = 5 \text{V; } V_{\text{bus}} = 5 \text{V; } R_{\text{pu(bus)}} = 1 \text{k}\Omega; \qquad - \qquad 30 \qquad - \qquad \text{ns} \\ C_{\text{L(ext)}} = 120 \text{pF; } \overline{\text{Figure 4}} \\ \hline t_{\text{f}} \qquad \text{fall time} \qquad V_{\text{CC}} = 5 \text{V; } V_{\text{bus}} = 5 \text{V; } R_{\text{pu(bus)}} = 1 \text{k}\Omega; \qquad - \qquad 15 \qquad - \qquad \text{ns} \\ \hline \textbf{C}_{\text{L(ext)}} = 120 \text{pF; } \overline{\text{Figure 4}} \\ \hline \textbf{C}_{\text{L(ext)}} = 120 \text{pF; } \overline{\text{Figure 4}} \\ \hline \textbf{C}_{\text{L(ext)}} = 120 \text{pF; } \overline{\text{Figure 4}} \\ \hline \textbf{C}_{\text{L(ext)}} = 120 \text{pF; } \overline{\text{Figure 4}} \\ \hline \textbf{C}_{\text{L(ext)}} = 120 \text{pF; } \overline{\text{Figure 4}} \\ \hline \textbf{C}_{\text{L(ext)}} = 120 \text{pF; } \overline{\text{Figure 4}} \\ \hline \textbf{C}_{\text{L(ext)}} = 120 \text{pF; } \overline{\text{Figure 4}} \\ \hline \textbf{C}_{\text{L(ext)}} = 120 \text{pF; } \overline{\text{Figure 4}} \\ \hline \textbf{C}_{\text{L(ext)}} = 120 \text{pF; } \overline{\text{Figure 4}} \\ \hline \textbf{C}_{\text{L(ext)}} = 120 \text{pF; } \overline{\text{Figure 4}} \\ \hline \textbf{C}_{\text{L(ext)}} = 120 \text{pF; } \text{Figur$	$V_{th(IL)}$	•		-	-	0.3V _{CC}	V
$ \begin{array}{c} l_{O(sink)} \text{output sink current} \\ V_{Offset} \\ V_{Offset} \\ \end{array} \begin{array}{c} \text{offset voltage} \\ \text{offset voltage} \\ \end{array} \begin{array}{c} l_{OL} = 4 \text{ mA}; \ V_{bus(in)} = 50 \text{ mV} \\ \hline l_{OL} = 500 \ \mu\text{A}; \ V_{bus(in)} = 50 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 50 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 200 \text{ mV} \\ \hline l_{OL} = 1.2 \text{ mA}; \ V_{bus(in)} = 1 \text{ mA}; \ V_{bus(in)} = 1 \text{ mA}; \ V_{cl} = 1.2 \text{ mA}; \ V_{cl} = 1.2$	$V_{th(IH)}$	•		0.41V _{CC}	-	-	V
$V_{\text{offset}} \text{offset voltage} \begin{array}{lllllllllllllllllllllllllllllllllll$	I _{IL}	LOW-level input current	drive current; V _{bus} < V _{CC}	-	-10	-20	μΑ
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	I _{O(sink)}	output sink current	LOW-level; V _{bus(out)} = 0.4 V	6	-	-	mA
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	V _{offset}	offset voltage	input/output; $V_{CC} = 3.3 \text{ V}$				
$I_{OL} = 1.2 \text{ mA; } V_{bus(in)} = 200 \text{ mV} \qquad - \qquad 60 \qquad 100 \qquad \text{mV}$ $I_{L} \qquad \text{leakage current} \qquad V_{bus} = V_{CC} \qquad - \qquad - \qquad 5 \qquad \mu A$ $Enable (EN)$ $V_{en} \qquad \text{enable voltage} \qquad \text{active} \qquad \qquad 1.2 \qquad - \qquad - \qquad V$ $V_{dis} \qquad \text{disable voltage} \qquad \text{standby} \qquad - \qquad - \qquad 0.7 \qquad V$ $I_{I} \qquad \text{input current} \qquad V_{en} > 1.2 \text{ V} \qquad \qquad 1 \qquad - \qquad 5 \qquad \mu A$ $Ready (RDY)$ $V_{OL(RDY)} \qquad LOW-level output voltage \qquad I_{pu} = 3 \text{ mA} \qquad - \qquad - \qquad 400 \qquad \text{mV}$ $\text{on pin RDY} \qquad I_{L} \qquad \text{leakage current} \qquad V_{OL(RDY)} = V_{CC} \qquad - \qquad - \qquad \pm 5 \qquad \mu A$ $Timing characteristics 11$ $t_{d} \qquad \text{delay time} \qquad V_{CC} = 5 \text{ V; } V_{bus} = 5 \text{ V; } R_{pu(bus)} = 1 \text{ k}\Omega; \qquad - \qquad 30 \qquad - \qquad \text{ns}$ $C_{L(ext)} = 120 \text{ pF; } Figure 4$ $t_{f} \qquad \text{fall time} \qquad V_{CC} = 5 \text{ V; } V_{bus} = 5 \text{ V; } R_{pu(bus)} = 1 \text{ k}\Omega; \qquad - \qquad 15 \qquad - \qquad \text{ns}$			$I_{OL} = 4 \text{ mA}; V_{bus(in)} = 50 \text{ mV}$	-	165	200	mV
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$			$I_{OL} = 500 \mu A; V_{bus(in)} = 50 \text{ mV}$	-	55	100	mV
			$I_{OL} = 1.2 \text{ mA}; V_{bus(in)} = 200 \text{ mV}$	-	60	100	mV
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	IL	leakage current	$V_{bus} = V_{CC}$	-	-	5	μΑ
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	Enable (EN)					
$\begin{tabular}{l l l l l l l l l l l l l l l l l l l $	V _{en}	enable voltage	active	1.2	-	-	V
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	V _{dis}	disable voltage	standby	-	-	0.7	V
$\begin{array}{c} V_{OL(RDY)} & LOW\text{-level output voltage} & I_{pu} = 3 \text{ mA} & - & - & 400 & \text{mV} \\ I_L & leakage current & V_{OL(RDY)} = V_{CC} & - & - & \pm 5 & \mu A \\ \hline \textbf{Timing characteristics} \\ \textbf{t}_d & delay time & V_{CC} = 5 \text{ V; } V_{bus} = 5 \text{ V; } R_{pu(bus)} = 1 \text{ k}\Omega; & - & 30 & - & \text{ns} \\ C_{L(ext)} = 120 \text{ pF; } \underline{Figure 4} & & & - & 15 & - & \text{ns} \\ C_{L(ext)} = 120 \text{ pF; } \underline{Figure 4} & & & - & 15 & - & \text{ns} \\ \end{array}$	I _I	input current	V _{en} > 1.2 V	1	-	5	μΑ
on pin RDY on pin RDY $V_{OL(RDY)} = V_{CC}$ ± 5 μA Timing characteristics[1] $V_{CC} = 5 \text{ V}; V_{bus} = 5 \text{ V}; R_{pu(bus)} = 1 \text{ k}\Omega;$ - ± 5 μA delay time $V_{CC} = 5 \text{ V}; V_{bus} = 5 \text{ V}; R_{pu(bus)} = 1 \text{ k}\Omega;$ - ± 5 μA ± 5	Ready (RD)	Y)					
Timing characteristics $t_{d} \qquad \text{delay time} \qquad \qquad V_{CC} = 5 \text{ V; } V_{bus} = 5 \text{ V; } R_{pu(bus)} = 1 \text{ k}\Omega; \qquad - \qquad 30 \qquad - \qquad \text{ns}$ $C_{L(ext)} = 120 \text{ pF; } \underline{Figure 4}$ $t_{f} \qquad \text{fall time} \qquad \qquad V_{CC} = 5 \text{ V; } V_{bus} = 5 \text{ V; } R_{pu(bus)} = 1 \text{ k}\Omega; \qquad - \qquad 15 \qquad - \qquad \text{ns}$ $C_{L(ext)} = 120 \text{ pF; } \underline{Figure 4}$	$V_{OL(RDY)}$		$I_{pu} = 3 \text{ mA}$	-	-	400	mV
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	IL	leakage current	$V_{OL(RDY)} = V_{CC}$	-	-	±5	μА
$C_{L(ext)} = 120 \text{ pF; } \underline{\text{Figure 4}}$ $V_{CC} = 5 \text{ V; } V_{bus} = 5 \text{ V; } R_{pu(bus)} = 1 \text{ k}\Omega; \qquad - \qquad 15 \qquad - \qquad \text{ns}$ $C_{L(ext)} = 120 \text{ pF; } \underline{\text{Figure 4}}$	Timing cha						
$C_{L(ext)} = 120 pF; Figure 4$	t _d	delay time		-	30	-	ns
f _{oper} operating frequency 0 400 - kHz	t _f	fall time		-	15	-	ns
	f _{oper}	operating frequency		0	400	-	kHz

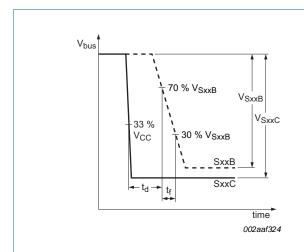
Fast dual bidirectional bus buffer with hot insertion logic

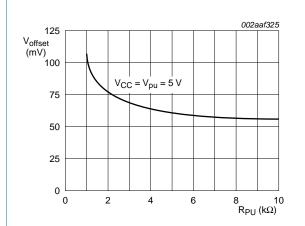
 Table 4.
 Characteristics ...continued

 $T_{amb} = -40$ °C to +85 °C; voltages are specified with respect to ground (GND).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
t _{idle}	idle time	$V_{bus} = V_{I(EN)} = V_{CC} = 3.3 \text{ V}$	50	95	150	μS
		$V_{bus} = V_{I(EN)} = V_{CC} = 5.5 \text{ V}$	50	75	120	μS
t _{d(ENH-RDYoff)}	delay time from EN HIGH to RDY off		-	95	-	μS
t _{d(ENL-RDYon)}	delay time from EN LOW to RDY on		-	1.1	-	μS
t _{d(RDYH-I2Con)}	delay time from RDY HIGH to I ² C on		-	1	-	μS
t _{d(RDYL-I2Coff)}	delay time from RDY LOW to I ² C off		-	-0.5	-	μS

[1] Guaranteed by design (not subject to test), except for t_{idle} at V_{CC} = 3.3 V.





 $T_{amb} = 25 \, ^{\circ}C; \, V_{bus(in)} = 200 \, \text{mV}.$

Fig 4. Timing parameters



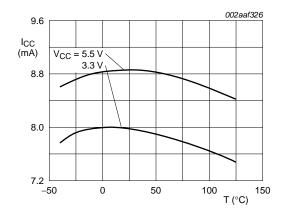


Fig 6. Supply current versus temperature

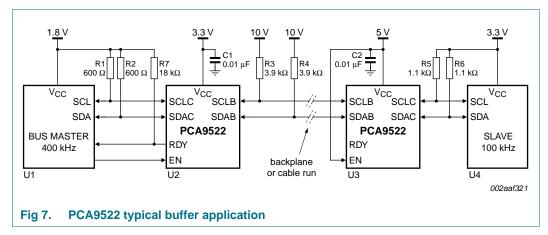
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10. Application information

10.1 Design considerations

<u>Figure 7</u> shows a typical application for the PCA9522. The IC can level shift between various bus voltages, without the need for additional external components. Higher bus voltages and currents outside the range of the standard I²C-bus specification can be catered for, providing a longer range capability and higher noise immunity.

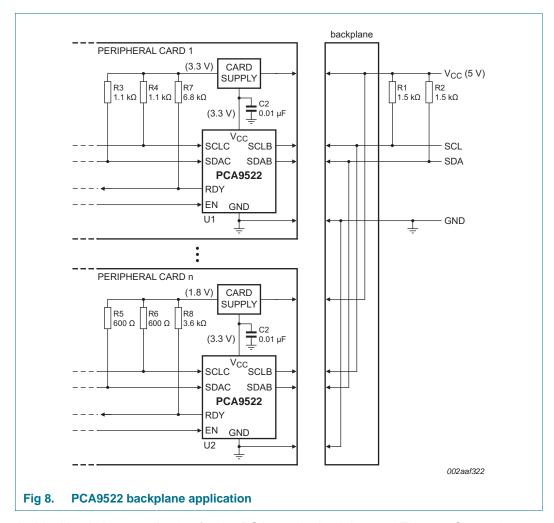
The enable pin (EN) can be used to interface buses of different operating frequencies. When enabled, the bus frequency is limited to the maximum 100 kHz of the slave device. When disabled, the slave is isolated, and the remaining bus can be run at 400 kHz. The timing performance and current sinking capability will allow it to run well in excess of the 400 kHz maximum limit of the Fast-mode I²C-bus.



<u>Figure 8</u> shows the PCA9522 used in a backplane application. Peripheral cards and backplanes operating at a range of voltages can be interfaced together using a minimum of components. In this example, cards are running at 1.8 V and 3.3 V, while the backplane is at 5 V. Cards operating buses between 1.8 V and 10 V can be catered for in the same system.

Each card can be safely isolated from the system by disabling the PCA9522 at the interface to the backplane. The hot insertion logic on the PCA9522 protects against corrupted or truncated data transmissions on start-up of buffer operations.

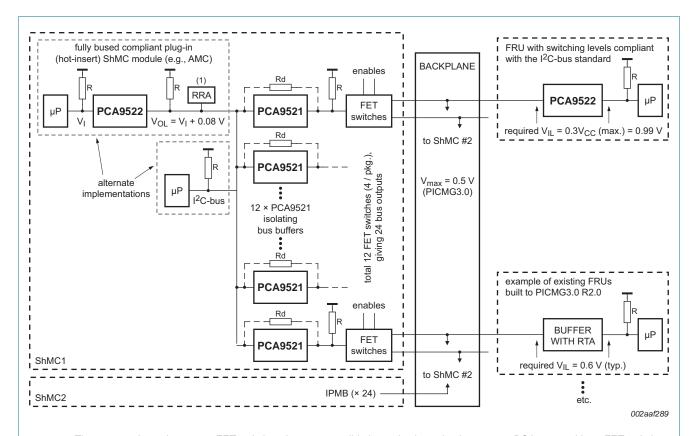
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An ideal backplane application for the PCA9522 is the Advanced Telecom Computing Architecture (AdvancedTCA) as shown in Figure 9. The PCA9522 is well-suited to placement on 'Field Replaceable Units' (FRUs) used in either a conventional fully-bused arrangement (not shown) or in the low cost, high noise margin radial architecture example as shown in Figure 10. It is fully interoperable with existing systems and components. If required, Figure 10 shows a simple low-cost circuit for use at the Shelf Manager for accelerating the rise in bused systems.

In each of these examples, the buffers are intended to extend total system capacitance above 400 pF, so anticipate high capacitance on each side. When loading on one side is small, adding 47 pF is suggested to avoid any waveform ripple, should it occur.

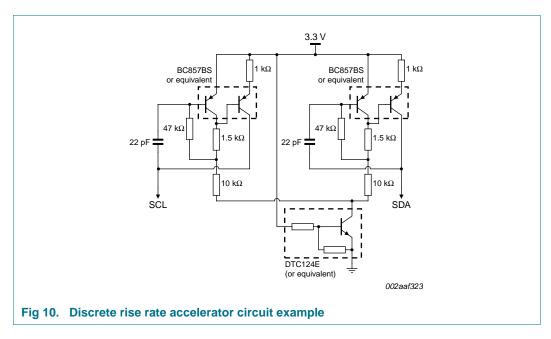
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The system shown here uses FET switches, however a valid alternative is to simply use $24 \times PCA9521s$ without FET switches. Long track runs on the ShMC board and backplane can sometimes result in high frequency tuned circuits on either side of the PCA9521. If your layout is prone to forming such tuned circuits, it is perfectly acceptable to use a 'traditional' damping resistor (Rd) across the PCA9521.

(1) RRA = Rise Rate Accelerator.

Fig 9. PCA9522 used in an AdvancedTCA application in conjunction with the PCA9521



PCA9522

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10.2 Input to output offset voltage calculation

The offset voltage between the side acting as the output (Sxxx(out)) and the side acting as the input (Sxxx(in)) of the PCA9522 can be calculated using the relationship given in Equation 1:

$$V_{offset} = V_i + 50 \ mV + \left(\frac{V_{BUS}}{R}\right) \times 11 \tag{1}$$

This calculation is valid for $V_{Sxxx(in)} \ge 200$ mV, as below this point the saturation voltage of the open-collector output drive transistor will begin to affect the characteristic. Input and output voltages are shown in millivolts, V_{BUS} (the supply voltage to the bus) is in volts, and R is in ohms.

An example calculation for V_{BUS} = 3.3 V, V_{SxxC} = 200 mV, the resistance R pulling up SxxB is 2 k Ω , then the voltage on SxxB is typically:

$$V_{SxxB} = 200 \ mV + 50 \ mV + \left(\frac{3.3}{2000}\right) \times 11 = 268 \ mV$$
 (2)

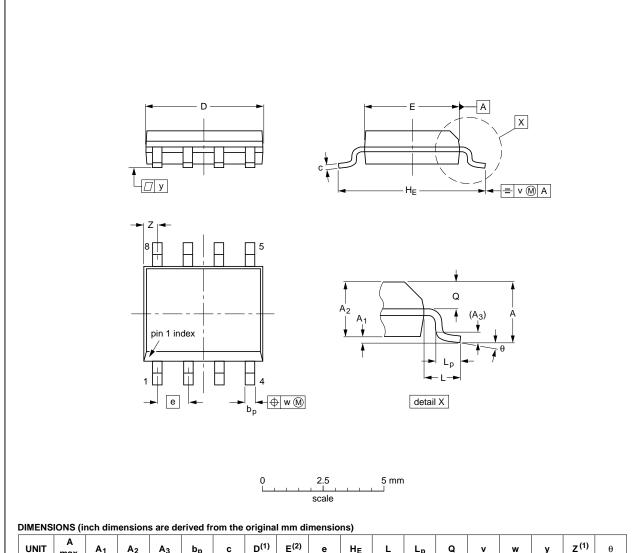
This can be compared with the offset characteristic shown in Figure 5.

Fast dual bidirectional bus buffer with hot insertion logic

11. Package outline

SO8: plastic small outline package; 8 leads; body width 3.9 mm

SOT96-1



UNIT	A max.	A ₁	A ₂	A ₃	bp	С	D ⁽¹⁾	E ⁽²⁾	е	HE	L	Lp	ø	٧	w	у	z ⁽¹⁾	θ
mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	5.0 4.8	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8°
inches	0.069	0.010 0.004	0.057 0.049	0.01		0.0100 0.0075	0.20 0.19	0.16 0.15	0.05	0.244 0.228	0.041	0.039 0.016	0.028 0.024	0.01	0.01	0.004	0.028 0.012	0°

Notes

- 1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.
- 2. Plastic or metal protrusions of 0.25 mm (0.01 inch) maximum per side are not included.

OUTLINE		REFER	RENCES	EUROPEAN	ISSUE DATE	
VERSION	IEC	JEDEC	JEITA	PROJECTION	ISSUE DATE	
SOT96-1	076E03	MS-012			99-12-27 03-02-18	
001001	070200	WIG 012			(

Fig 11. Package outline SOT96-1 (SO8)

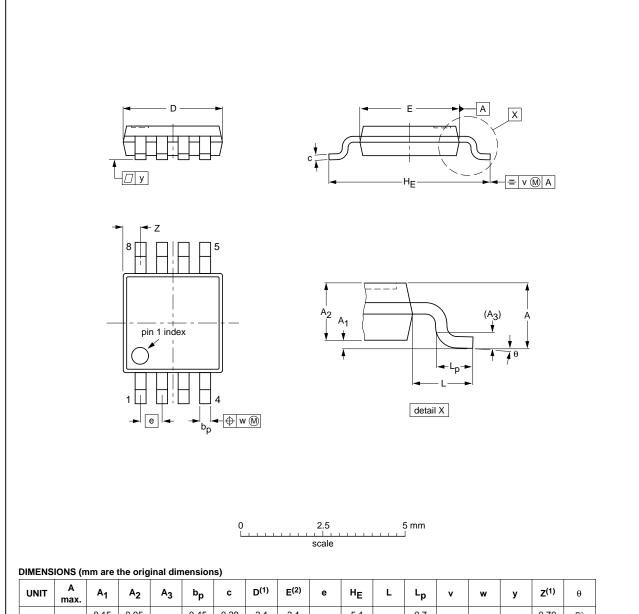
PCA952

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TSSOP8: plastic thin shrink small outline package; 8 leads; body width 3 mm

SOT505-1



UNIT	A max.	A ₁	A ₂	А3	bp	С	D ⁽¹⁾	E ⁽²⁾	е	HE	L	Lp	v	w	у	Z ⁽¹⁾	θ
mm	1.1	0.15 0.05	0.95 0.80	0.25	0.45 0.25	0.28 0.15	3.1 2.9	3.1 2.9	0.65	5.1 4.7	0.94	0.7 0.4	0.1	0.1	0.1	0.70 0.35	6° 0°

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

	REFER	EUROPEAN ISSUE DATE			
IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE
					-99-04-09- 03-02-18
	IEC				IEC JEDEC JEITA PROJECTION

Fig 12. Package outline SOT505-1 (TSSOP8)

Fast dual bidirectional bus buffer with hot insertion logic

12. Handling information

CAUTION



This device is sensitive to ElectroStatic Discharge (ESD). Observe precautions for handling electrostatic sensitive devices.

Such precautions are described in the ANSI/ESD S20.20, IEC/ST 61340-5, JESD625-A or equivalent standards.

13. Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365* "Surface mount reflow soldering description".

13.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

13.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- · Board specifications, including the board finish, solder masks and vias
- · Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

PCA9522

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13.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

13.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see <u>Figure 13</u>) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with Table 5 and 6

Table 5. SnPb eutectic process (from J-STD-020C)

Package thickness (mm)	Package reflow temperature (°C)					
	Volume (mm³)					
	< 350	≥ 350				
< 2.5	235	220				
≥ 2.5	220	220				

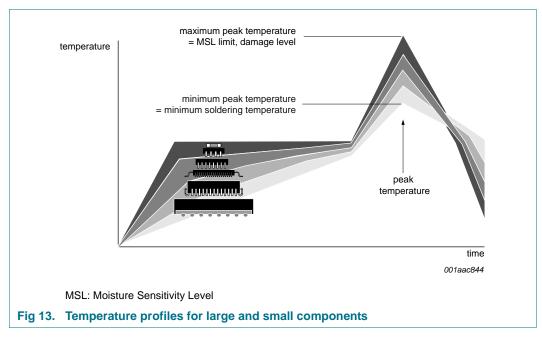
Table 6. Lead-free process (from J-STD-020C)

Package thickness (mm)	Package reflow temperature (°C)							
	Volume (mm³)							
	< 350	350 to 2000	> 2000					
< 1.6	260	260	260					
1.6 to 2.5	260	250	245					
> 2.5	250	245	245					

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see Figure 13.

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For further information on temperature profiles, refer to Application Note *AN10365* "Surface mount reflow soldering description".

14. Abbreviations

Table 7. Abbreviations

Acronym	Description
AMC	Advanced Mezzanine Cards
ATCA	Advanced Telecommunications Computing Architecture
ESD	ElectroStatic Discharge
FRU	Field Replaceable Unit
I ² C-bus	Inter-Integrated Circuit bus
IC	Integrated Circuit
IPMB	Intelligent Platform Management Bus
PICMG	PCI Industrial Computer Manufacturers Group
PMBus	Power Management Bus
RAID	Redundant Array of Independent Discs
RTA	Rise Time Accelerator
ShMC	Shelf Management Controller
SMBus	System Management Bus

Fast dual bidirectional bus buffer with hot insertion logic

15. References

- [1] UM10204, l²C-bus specification and user manual , Rev 03, 19 June 2007; NXP B.V. www.nxp.com/documents/user_manual/UM10204.pdf
- [2] System Management Bus (SMBus) Specification Version 2.0, August 3, 2000; SBS Implementers Forum.

16. Revision history

Table 8. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
PCA9522 v.1	20110928	Product data sheet	-	-

Fast dual bidirectional bus buffer with hot insertion logic

17. Legal information

17.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
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- [2] The term 'short data sheet' is explained in section "Definitions"
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