

Future Technology Devices International Ltd. FT4222H (USB2.0 to QuadSPI/I²C Bridge IC)



FT4222H is a USB2.0 to Quad-SPI/I²C • interface Device Controller with the following advanced features:

- Single chip USB2.0 Hi-speed to SPI/I²C bridge
 with a variety of configrations
- Entire USB protocol handled on the chip.
- On-chip OTP memory for USB Vendor ID (VID), Product ID (PID), device serial number, product description string and various other vender specific data.
- Configurable industry standard SPI Master/Slave interface controller
- Support configureable data width with single, dual, quad data width transfer mode in SPI master
- SCK can support up to 30MHz in SPI master
- Up to 28Mbps data transfer rate in SPI master with guad mode transfer
- Support single bit data transfer with full-duplex transfer in SPI Slave
- Support up to 4 channels slave selection control pins in SPI master application
- Configurable I²C Master/Slave interface controller conforming to I²C v2.1 and v3.0 specification.
- Support 100kbit/s standard mode (SM), 400 kbit/s fast mode (FM), 1 Mbit/s Fast mode plus (FM+), and 3.4 Mbit/s High Speed mode (HS)
- Configurable GPIOs can be easily controlled by software applications via USB bus

- USB Battery Charger Detection. Allows for USB peripheral devices to detect the presence of a higher current power source to enable faster charging.
- Device supplied pre-programmed with unique USB serial number.
- USB Power Configurations; supports buspowered, self-powered and bus-powered with power switching.
- +5V USB VBUS detection engine
- Integrated 5V-3.3V-1.8V level converter for USB I/O.
- True 3.3V CMOS drive output and TTL input. (operates down to 1V8 with external pull-ups)
- Configurable I/O pin output drive strength; 4 mA(min) and 16 mA(max)
- Integrated power-on-reset circuit.
- USB2.0 Low operating and suspend current; 68mA (active-typ) and 375µA (suspend-typ).
- UHCI / OHCI / EHCI / XHCI host controller compatible.
- FTDI's royalty-free Direct (D2XX) drivers for Windows eliminate the requirement for USB driver development in most cases.
- Extended operating temperature range; -40 to 85°C.
- Available in compact Pb-free 32 Pin VQFN packages (RoHS compliant).

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1 Typical Applications

- USB to single mode SPI master controller
- USB to dual mode SPI master controller
- USB to quad mode SPI master controller
- USB to single SPI slave controller
- USB to I²C master interface controller
- USB to I²C slave interface controller
- Utilising USB to add system modularity
- Incorporate USB interface to enable PC transfers for development system communication

- USB Industrial Control
- USB Data Acquisition
- Accessory connectivity solutions for mobiles and tablets
- USB dongle implementations for Software/ Hardware Encryption and Wireless Modules
- Detect USB dedicated charging ports, to allow for high current battery charging in portable devices.

1.1 Driver Support

Royalty free D2XX Direct Drivers (USB Drivers + DLL S/W Interface)

- Windows 8.1 32, 64-bit
- Windows 8 32, 64-bit
- Windows 7 32, 64-bit
- Server 2008 R2
- Server 2012 R2

For driver installation, please refer to http://www.ftdichip.com/Documents/InstallGuides.htm

1.2 Part Numbers

| Part Number | Package |
|-------------|-------------|
| FT4222HQ-x | 32 Pin VQFN |

Note: Packing codes for x is:

- R: Taped and Reel, 5,000pcs per reel

- T: Tray packing, 490pcs per tray

For example: FT4222HQ-R is 5,000pcs taped and reel packing



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1.3 USB Compliant

The FT4222H is fully compliant with the USB 2.0 specification and has been given the USB-IF Test-ID (TID) 40001599.





2 FT4222H Block Diagram

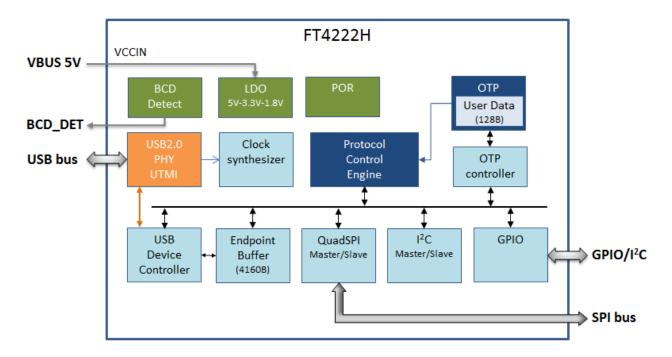


Figure 2.1 FT4222H Block Diagram

For a description of each function please refer to Section 4.

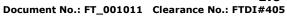
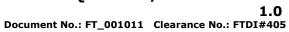




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3 Device Pin Out and Signal Description

3.1 VQFN-32 Package Pin Out

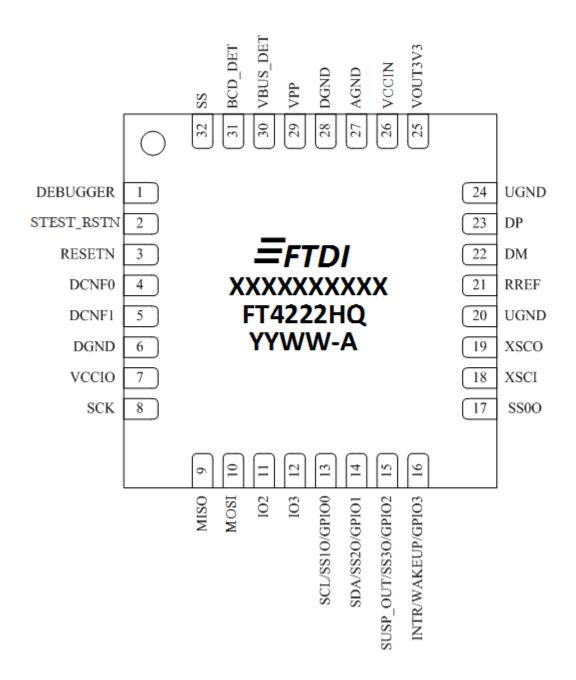


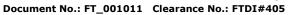
Figure 3.1 Pin Configuration VQFN-32 (top-down view)



3.2 Pin Description

| FT4222H Pin No. | Pin Name | Туре | Description |
|--------------------|---------------------|---------|---|
| 1 | DEBUGGER | I/O | Debugging pin. Should be reserved and tied to high |
| 2 | STEST_RSTN | I | Chip reset input for test mode. Active low. Should be reserved and tied to high. |
| 3 | RESETN | I | Chip reset input for non-test mode operation. Active low. |
| 4 | DCNF0 | I | USB endpoint configuration selections bit 0. Refer to Section 5.1 |
| 5 | DCNF1 | I | USB endpoint configuration selections bit 1. Refer to Section 5.1 |
| 6 | DGND | Р | Digital Ground |
| 7 | VCCIO | ** P | +3.3V/2.5V/1.8V supply voltage. This is the supply voltage for all the I/O ports. This pin shall be connected to pin 25 when I/O ports are working at 3.3V |
| 8 | SCK | I/O | SPI interface clock. Serial clock output for SPI master; serial clock input for SPI slave mode |
| 9 | MISO | I/O | In SPI master single mode, it is master serial data input. In SPI mater dual/quad mode, it's SPI data bus bit 1. In SPI slave mode, it is slave serial data output. |
| 10 | MOSI | I/O | In SPI master single mode, it is master serial data output. In SPI mater dual/quad mode, it's SPI data bus bit 0. In SPI slave mode, it is slave serial data input. |
| 11 | IO2 | I/O | Quad SPI data bus bit 2 |
| 12 | 103 | I/O | Quad SPI data bus bit 3 |
| 13 | GPIO0/SS1O/SCL | I/O | GPIO 0 (default) can be configured as slave selection 1, output pin for SPI master mode or serial clock for ${\rm I}^2{\rm C}$ mode |
| 14 | GPIO1/SS2O/SDA | I/O | GPIO 1 (default) can be configured as slave selection 2, output pin for SPI master mode or serial data for ${\rm I}^2{\rm C}$ mode |
| 15 | GPIO2/SS3O/SUSP_OUT | I/O | GPIO 2 (default) can be configured as slave selection 3, output pin for SPI master mode or USB suspend output indicator |
| 16 | GPIO3/WAKEUP/INTR | I/O | GPIO 3 (default) and can be configured as USB remote wakeup input pin or interrupt input |
| 17 | SS00 | 0 | Slave selection 0, output pin for SPI master mode. |
| 18 | XSCI | AI | Crystal oscillator input, 12MHz only. Related application circuit can be referred to Section7.4 |
| 19 | XSCO | АО | Crystal oscillator output, 12MHz only. Related application |







| FT4222H Pin No. | Pin Name | Туре | Description |
|--------------------|----------|---------|--|
| | | | circuit can be referred to Section7.4 |
| 20 | UGND | Р | USB Analog Ground |
| 21 | RREF | AI | USB peripheral reference voltage input. Connect 12Kohm +/- 1% resistor to GND. |
| 22 | DM | AI/O | USB peripheral bidirectional DM line. |
| 23 | DP | AI/O | USB peripheral bidirectional DP line. |
| 24 | UGND | Р | USB Analog Ground |
| 25 | VOUT3V3 | ** P | +3.3V voltage Out May be used to power VCCIO. When VCCIN is supplied with 3.3V, this pin is a power input pin. Connect to pin 26. |
| 26 | VCCIN | ** P | +5.0V(or 3.3V) supply voltage In Power source-in to embedded regulator. |
| 27 | AGND | Р | Analog Ground |
| 28 | DGND | Р | Digital Ground |
| 29 | VPP | Р | +6.5V supply voltage In Power source for Programming embedded OTP. It should be kept floating or 0V when not in programming mode |
| 30 | VBUS_DET | I | VBUS detection input. It's +5.0V tolerance pin |
| 31 | BCD_DET | 0 | Battery charger detection indicator out when the device is connected to a dedicated battery charger port. Polarity can be defined |
| 32 | SS | I | SPI slave selection indicator from SPI master. This pin is active in SPI slave mode. It must be tied to high when SPI master mode enabled. |

Table 3.1 FT4222H Pin Description

^{**}If VCCIN is supplied with 3.3V power input, then VOUT3V3 and VCCIO must also be driven with this 3.3V power source



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4 Function Description

The FT4222H is a Hi-Speed USB2.0-to-Quad SPI/ I^2C device controller in a compact 32-pin VQFN package. The FT4222H requires an external Crystal (12Mhz) for the internal PLL to operate. It supports multi-voltage IO, 3.3V, 2.5V or 1.8V. It also provides 128 bytes one-time-programmable(OTP) memory space for storing vendor specific information.

The FT4222H contains SPI/ I^2C configurable interfaces. The SPI interface can be configured as master mode with single, dual, or quad bits data width transfer or in slave mode with single bit data width transfer. The I^2C interface can be configured as master or slave mode.

4.1 Key Features

Functional Integration. The FT4222H is a USB 2.0 Hi-Speed (480Mbits/s) to flexible and configurable SPI/ I^2 C interfaces IC. The FT4222H includes an integrated +1.8V and +3.3V Low Drop-Out (LDO) regulator and 12MHz to 480MHz PLL. It also includes Power-On-Reset (POR), VBUS detection with 5V-tolerance and 128 bytes one-time-programmable(OTP) memory which simplify external circuit design and reduce external component count.

USB2.0 Hi-Speed Device Controller. The FT4222H integrates a USB protocol engine which controls the physical Universal Transceiver Macrocell Interface (UTMI) and handles all aspects of the USB 2.0 Hi-Speed interface. It contains one control endpoint, and 4-pairs of IN and OUT endpoints. These endpoints can implement upto 4 independent interfaces/applications mapped to combined $\rm I^2C$, GPIO, SPI interfaces.

Highly Integrated USB2.0 to Configurable SPI Bridge. The FT4222H provides the bridge function between a USB2.0 device, upstream port and SPI Master/Slave.

A support library, LibFT4222, based on FTDI's D2XX driver, enables easy configuration of the SPI as a master or slave. Operating clock frequency on the SPI bus, clock phase and polarity, transfer data bit width mode, and the number of slave selection controls are also configurable.

The max SPI interface operating clock can be set up to 30MHz in master mode, and 20MHz in slave mode. With guad mode(4-bits) data bus width, the max data transfer throughput can be up to 28Mbps.

USB to Configurable I 2 **C Controller.** The FT4222H also provides the bridge function between a USB2.0 device upstream port and an I 2 C Master/Slave interface.

A support library, LibFT4222, based on FTDI's D2XX driver, enables easy configuration of the I^2C as either a master or slave, including target operating speed and bus protocol on I^2C bus.

The device can run at common I^2C bus speeds, 100kbit/s standard mode (SM), 400 kbit/s fast mode (FM), 1 Mbit/s Fast mode plus (FM+), and 3.4 Mbit/s High Speed mode (HS). Clock stretching is also supported to conform to v2.1 and v3.0 of the I^2C specification.

Configurable GPIOs. There are 4 GPIO pins in the FT4222H that can be configured for different purposes, such as a suspend indicator output, remote wake up input, an interrupt input or general purpose Input/Output. These GPIOs can be easily initialized and fully controlled at the USB host side by the application programming interface(API) defined in LibFT4222.

Signal drive strength and slew rate of these GPIOs can be configured via the utility FT_Prog for different design needs.

Embedded OTP memory. The internal OTP memory in the FT4222H is used to store USB Vendor ID (VID), Product ID (PID), device serial number, product description string and various other USB configuration descriptors. With this embedded OTP memory, the device can store vendor specific information and save the cost on BOM. The descriptors can be programmed using the FTDI utility software called FT_PROG, which can be downloaded from the FTDI Utilities page on the FTDI website (http://www.ftdichip.com/Support/Utilities.htm#FT_Prog).

Power management. USB 2.0 suspend/resume and remote wakeup are fully supported. The PHY will be put to a power saving mode and the clock to most of the digital circuits will be stopped when the device is suspended.

Source Power and Power Consumption. The FT4222H is capable of operating at a voltage supply of +3.3V or +5.0V with a nominal operational mode current of 68mA and a nominal USB suspend mode current of $375\mu A$. This allows greater margin for peripheral designs to meet the USB suspend mode current limit of 2.5mA. An integrated level converter within the FT4222H allows the interface to logic running at +1.8V, 2.5V or +3.3V. (Note: External pull-ups are recommended for IO <3V3).



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4.2 Functional Block Descriptions

The following paragraphs detail each function within the FT4222H. Please refer to the block diagram shown in Figure 2.1

USB2.0 UTMI PHY. The Universal Transceiver Macrocell Interface (UTMI) is a physical interface cell. This block handles the full speed and high speed SERDES (serialise - deserialise) function for the USB TX/RX data. It also provides the clocks for the rest of the chip. A 12 MHz crystal should be connected to the XSCI and XSCO pins. A 12k Ohm resistor should be connected between REF and GND on the PCB.

The UTMI PHY functions include:

- Supports 480 Mbit/s "Hi-Speed" (HS) and 12 Mbit/s "Full Speed" (FS).
- SYNC/EOP generation and checking.
- Data and clock recovery from serial stream on the USB.
- Bit-stuffing/unstuffing; bit stuff error detection.
- Manages USB Resume, Wake Up and Suspend functions.

Single parallel data clock output with on-chip PLL to generate higher speed serial data clocks

USB Device Controller. The USB Device controller in the FT4222H controls and manages the interface between the UTMI PHY and the interfaces of the chip. It provides 9 endpoints to fit into the FT4222H applications.

The USB Device Controller functions includes:

- Endpoint-0 for control pipe with max packet size 64 Bytes
- 4 endpoints for bulk-in pipe with configurable max packet size up to 512 Bytes
- 4 endpoints for bulk-out pipe with configurable max packet size up to 512 Bytes
- Multiple interfaces configuration support
- Suspend detection and power management
- Remote wake-up support
- Fully compatible to USB2.0 specification requirement

Endpoint Buffer. For fulfilling the max packet size requirement and high performance data transfer throughput, the Endpoint Buffer is 4160 bytes SRAM with configurable size management to each endpoint. It can be configured as single or double buffers and adjustable size for each endpoint.

QuadSPI Master/Slave Controller. The QuadSPI is a fully configurable SPI master/slave device, which allows the user to configure polarity and phase of the serial clock signal SCK. When SPI is configured as a master, it can be configured automatically to drive slave select outputs (SS30 – SS00), and address the SPI slave device to exchange serially shifted data. The data bus can be configured as single(1bit), dual(2-bits) and quad(4-bits) mode for different transfer request and application. The interface operating clock can be easily configured up to 30MHz. When SPI is configured as a slave, the SPI engine can support one slave port and operate a single data mode transfer. The max acceptable operating clock can be up to 20MHz. The QuadSPI controller can be easily configured via a support library, LibFT4222. For details refer to the <u>User Guide For LibFT4222</u>.

QuadSPI as master functions include:

- Single Mode (1-bit) data transfer with full duplex serial data transfer
- Dual Mode (2-bits) data transfer
- Quad Mode (4-bits) data transfer
- Up to 4 SPI slave channels can be addressed via pins SS30~SS00
- Shared data bus to minimize related pin counts
- 4 types of transfer format can be selected by Phase and Polarity
- Configurable interface clock on SCK as 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256 of 80MHz, 60MHz,48MHz and 24MHz



| SCK I | req. (Hz) | SCK = Operating Clock * the following ratio | | | | | | | |
|--------------------|--------------------------------|---|-----|------|-------|--------|--------|---------|----------|
| Operating Clock | Max Throughput can be expected | 1/2 | 1/4 | 1/8 | 1/16 | 1/32 | 1/64 | 1/128 | 1/256 |
| 80MHz | 28.1Mbps* | Not support | 20M | 10M | 5M | 2.5M | 1.25M | 625K | 312.5K |
| 60MHz | 20.5Mbps* | 30M | 15M | 7.5M | 3.75M | 1.875M | 937.5K | 468.75K | 234.375K |
| 48MHz | 16.3Mbps* | 24M | 12M | 6M | 3M | 1.5M | 750K | 375K | 187.5K |
| 24MHz | 8.0Mbps* | 12M | 6M | 3M | 1.5M | 750K | 375K | 187.5K | 93.75K |

Table 4.1 SCK Operating Frequency in SPI Master Mode

QuadSPI as slave functions include:

- Single Mode (1-bit) data transfer with full duplex serial data transfer
- Can accept SCK operating frequency up to 20 MHz

| Operating Clock Frequency | Max Acceptable Frequency on SCK |
|---------------------------|---------------------------------|
| 80MHz | <= 20MHz |
| 60MHz | <= 15MHz |
| 48MHz | <= 12MHz |
| 24MHz | <= 6MHz |

Table 4.2 Max. Acceptable Operating Frequency on SCK in SPI Slave Mode

 ${f I^2C}$ Master/Slave Controller. ${f I^2C}$ (Inter Integrated Circuit) is a multi-master serial bus invented by Philips. ${f I^2C}$ uses two bi-directional open-drain wires called serial data (SDA) and serial clock (SCL). Common ${f I^2C}$ bus speeds are the 100 kbit/s standard mode (SM), 400 kbit/s fast mode (FM), 1 Mbit/s Fast mode plus (FM+), and 3.4 Mbit/s High Speed mode (HS). Please refer to the ${f I^2C}$ specification for more information on the protocol.

The FT4222H device can operates as master or slave, and the major functions include:

- Master or slave mode configurable
- Fully compatible to v2.1 and v3 specification
- 7-bits address support
- Support 4 speed configurations: 100KHz(SM), 400KHz(FM), 1MHz(FM+), and 3.4MHz(HS)
- Clock stretching support in master and slave mode

GPIOs. FT4222H contains 4 GPIO pins for various functions. The drive strength, slew rate control and pull high/low resistors can be configured in the vendor configureable area of the OTP via FT_PROG. When the USB GPIO interface is enabled and supported, GPIOs can be directly controlled by APIs(Application Programming Interface) which are defined in the support library, LibFT4222, to match the requirement.

GPIOs in the FT4222H functions include:

- GPIO0 can be configured as GPIO0 or I²C SCL or SPIM slave selection SS10
- GPIO1 can be configured as GPIO1 or I²C SDA or SPIM slave selection SS2O

^{*}The max. throughput can be expected under the condition of quad mode transferring and high operating frequency on SCK. It aslo depends on the USB bus transfer condition. For example, the max throughput that can be expected is up to 28.1Mbps when operating the clock equal to 80MHz, SCK setting as 20MHz, data bus operating at quad mode and USB bus operating at high speed with sufficient bandwidth.



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- GPIO2 can be configured as GPIO2 or USB suspend status output(SUSP) or SPIM slave selection SS30
- GPIO3 can be configured as GPIO3 or USB remote wake-up input(WAKE) or external interrupt input(INTR)
- Adjustable Driving Strength: 4mA/8mA/12mA/16mA
- · Slew Rate, Pull High/Low resistor, open drain configurable
- WAKE can be configured as rising or falling edge triggered
- SUSP trigger mode can be configured as rising edge, falling edge, high level and low level trigger

For configuration details refer to Section 9.1.

Built-in Clock Synthesizer. With an on-chip clock synthesizer, the FT4222H may operate with a low-cost 12 MHz crystal (or oscillator) by connecting to XSCI and XSCO, and generates a standard internal 480 MHz clock for the USB interface. The Clock Synthesizer takes the 480MHz clock from the embedded UTMI PHY and generates the 80MHz, 60MHz, 48MHz and 24MHz as reference clocks. User can select one of these reference clocks via API, FT4222_SetClock which is defined in LibFT4222, as the system operating clock. The system operating clock will be the base and used by the embedded functions to generate the required interface clock.

Protocol Control Engine. The FT4222H is embedded with a robust control engine. It deals with the USB enumeration commands and flow control between driver and function such as SPI or I^2C devices. It can serve the bridge function initialization and enable an exceptional data transfer performance through the USB bus. It collects and summarizes the SPI and I^2C bus protocol and simplify the protocol as command set via USB Bulk transfer pipe. A support library, LibFT4222, is defined for FT4222H and responsible for communicating with this protocol engine. With related APIs(Application Programming Interface) defined in LibFT4222, user can easily implement their own application via SPI or I^2C bus prototcol with FT4222H. This control engine provides a very flexible programmability to ease the operations for SPI and I^2C bus access. With user area which is provided for user configuration and settlings, this protocol engine makes the FT4222H suitable for a wide range of applications.

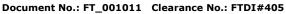
OTP Controller + Internal OTP Memory. The internal OTP memory provides storage for vendor configuration data. This vendor configuration area, named as user area, is used to store USB Vendor ID (VID), Product ID (PID), device serial number, product description string and various other USB configuration descriptors. It is also used to configure the function pins capability. For further details refer to Section 0. This user area in the internal OTP memory is available to system designers to allow storing additional data from the user application over USB. The internal OTP memory can be programmed in circuit, over USB with an external voltage requirement on VPP pin (6.5V). The descriptors can be programmed using the FTDI utility software called FT_PROG, which can be downloaded from FTDI Utilities on the FTDI website (http://www.ftdichip.com/Support/Utilities.htm#FT Proq).

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5V-3.3V-1.8V LDO regulator. The LDO will regulate out 2 reference voltages for the use within the FT4222H. The +3.3V LDO regulator generates the +3.3V reference voltage for driving the USB transceiver cell output buffers. It requires an external decoupling capacitor to be attached to the VOUT3V3 regulator output pin. Another +1.8V LDO regulator generates the +1.8V reference voltage for driving the internal core of the IC.

POR RESET Generator. POR is the integrated Power on Reset Generator Cell providing a reliable power-on reset to the device internal circuitry at power up. There is also a RESETN input pin allowing an external device to reset the FT4222H. RESETN can be tied to VCCIO (+3.3v) if not being used.

Embedded BCD Detection. Supports Battery Charger Detection. The BCD_DET pin will be active if the device is connected to a dedicated charger instead of a standard USB Host. Refer to section 7.5 for an example application circuit.





5 FT4222H Chip Mode Configuration and SPI/I²C Interface

5.1 Chip Mode Configuration

The FT4222H has 4 configuration modes selected by {DCNF1, DCNF0}. The chip configuration mode will determine the number of USB interfaces for data streams and for GPIOs control. The data stream interface is for data transfer between the USB2.0 host and the SPI/ $\rm I^2C$ device. The purpose of the GPIO interface is for fully controlling the GPIOs. The following table shows the pin functions corresponding to the chip configuration mode.

| Pin Functions | CNFMODEO {DCNF1, DCNF0} = 00 | CNFMODE1 {DCNF1, DCNF0} = 01 | CNFMOD2 {DCNF1, DCNF0} = 10 | CNFMODE3 {DCNF1, DCNF0} = 11 |
|--|----------------------------------|----------------------------------|--------------------------------|------------------------------|
| USB interface number | 1 for data stream 1 for GPIOs | 3 for data stream 1 for GPIOs | 4 for data stream | 1 for data stream |
| SPI Master(SPIM) related pins (SCK, MISO, SIMO, IO2,IO3, SSOO) | SPIM* | Active USB interface-0 | Active USB interface-0 | SPIM* |
| SPI Slave(SPIS) related pins (SCK, MISO, SIMO, SS) | SPIS* | Disable | Disable | SPIS* |
| GPIO0 | GPIO/SCL* | SS10 USB interface-1 | SS10 USB interface-1 | SCL* |
| GPIO1 | GPIO/SDA* | SS2O USB interface-2 | SS2O USB interface-2 | SDA* |
| GPIO2 | GPIO/SUSP | GPIO/SUSP | SS3O USB interface-3 | SUSP |
| GPIO3 | GPIO/WAKE/INTR | GPIO/WAKE/INTR | WAKE | WAKE |

Table 5.1 FT4222H Pin Functions on Chip Configuration Mode

*One of the SPIM, SPIS, I²C function is selected, the other 2 functions will be disabled

Note that GPIOx pins cannot be controlled by the software driver when GPIOx pins play the role as SPIM SSxO, I^2C SCL/SDA, SUSP or WAKE.

Chip Configuration only determines the number of interface/function supported but do not decide which bus interface (SPI/ $\rm I^2C$ /GPIO) or which role(master/slave) that the FT4222H will take. The user can use the initial APIs provided by the support library, LibFT4222, to configure which interface and role will be taken.

The support library for FT4222H, LibFT4222, which is based on D2XX, provides high-level and convenient APIs(Application Programming Interface) to speed up user application development. Details can be referred to the User Guide For LibFT4222.



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5.2 SPI Bus Interface

5.2.1 SPI Pin Definition

The QSPI function in the FT4222H is a fully configurable SPI master/slave device. Users can ultilize the API in LibFT4222, FT4222_SPIMaster_Init or FT4222_SPISlave_Init, to select in which mode (master or slave) the FT4222H will function. When the FT4222H is set as a USB-to-SPI bridge function, and chip configuration is set as 1 or 3 or 4 data streams, the pins of the FT4222H will be mapped accordingly. The SPI related pins are

- Clock SCK (pin-8), 4 types of transfer formats supported, details refer to Section5.2.2
- Data MISO (pin-9), data transfer from slave to master for single mode, or data bus bit-1 for dual and quad mode
 - MOSI (pin-10), data transfer from master to slave for single mode, or data bus bit-0 for dual and quad mode
 - IO2 (pin-11), data bus bit-2 for quad mode
 - IO3 (pin-12), data bus bit-3 for quad mode
- · Slave Selection when QSPI acts as SPI master
 - SS00 (pin-17), slave selection to slave device-0
 - SS10 (pin-13), slave selection to slave device-1
 - SS20 (pin-14), slave selection to slave device-2
 - SS30 (pin-15), slave selection to slave device-3
- Slave Selection when QSPI acts as SPI slave
 - SS (pin-32), slave selection for SPI master control. Must tie high when QuadSPI acts as SPI master

5.2.2 SPI Bus Protocol

The QuadSPI allows SPI data transfers in three types of bit width:

- Single SPI transfer Standard data transfer format data is read and written simultaneously
- DUAL SPI Transfer/Receive Data is transferred out or received in ont 2 SPI lines simultaneously
- QUAD SPI Transfer/Receive Data is transferred out or received in on 4 SPI lines simultaneously

The operating bit width in single, dual or quad mode can be also be determined by these 2 APIs , FT4222_SPIMaster_Init and FT4222_SPISlave_Init, which are defined in LibFT4222 when the SPI function is enabled and selected.



When the FT4222H is operating as an SPI master or slave device, QuadSPI can transfer data in single bit mode with full-duplex transmission. Figure 5.1 shows the basic protocol in single transfer mode

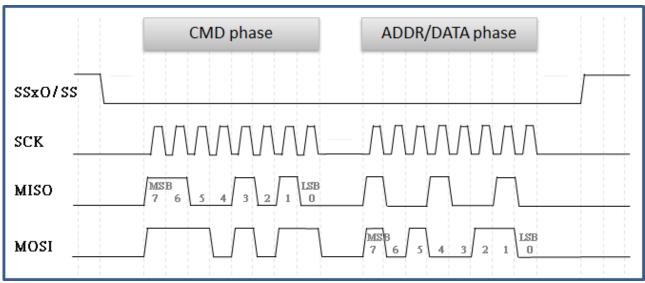


Figure 5.1 QuadSPI Bus Protocol when Transferring in Single Mode

QSPI can operate in dual or quad transfer mode when QSPI is programmed as an SPI master. These multi-bit transfer modes can speed up the data transfer rate between QSPI and the SPI slave device supporting the multi-bit transfer. Figure 5.2 shows the bus protocol in dual or quad mode

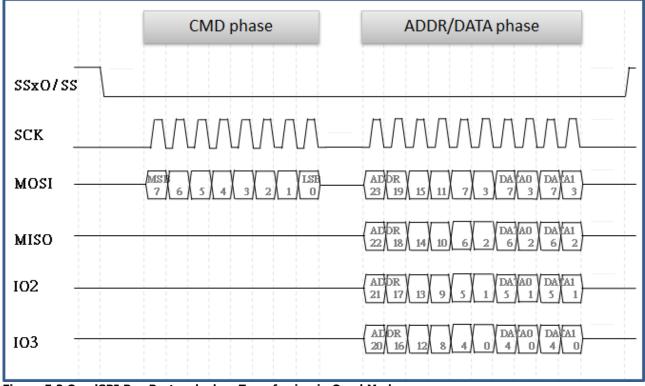


Figure 5.2 QuadSPI Bus Protocol when Transferring in Quad Mode



5.2.3 SCK Format

Software can select any of four combinations of serial clock (SCK) phase and polarity. The clock polarity is specified by the CPOL control bit, which selects an active high or active low clock and has no significant effect on the transfer format. The clock phase (CPHA) control bit selects one of two fundamentally different transfer formats. The clock phase and polarity should be identical for the master SPI device and the communicating slave device. In some cases, the phase and polarity are changed between transfers to allow a master device to communicate with peripheral slaves having different requirements. The flexibility of the SPI system on the QSPI allows direct interface to almost any existing synchronous serial peripheral. Users can also use the FT4222_SPIMaster_Init API which is defined in the support library LibFT4222 to select the operating phase and polarity of SCK.

5.2.3.1 CPHA=0 Transfer Format

Figure 5.3 shows a timing diagram of an SPI transfer where CPHA is equal to 0. Two waveforms are shown for SCK: one for CPOL equal to 0 and another for CPOL equal to 1. The diagram may be interpreted as a master or slave timing diagram since the SCK, master in/slave out (MISO), and master out/slave in (MOSI) pins are directly connected between the master and the slave. The MISO signal is the output from the slave, and the MOSI signal is the output from the master.

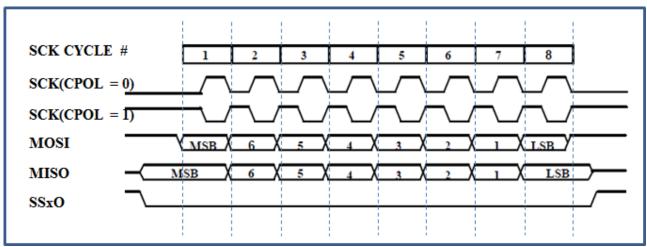


Figure 5.3 SCK Transfer Format when CPHA=0

5.2.3.2 CPHA=1 Transfer Format

Figure 5.4 is a timing diagram of an SPI transfer where CPHA equal to 1. Two waveforms are shown for SCK: one for CPOL equal to 0 and another for CPOL equal to 1. The diagram may be interpreted as a master or slave timing diagram since the SCK, MISO, and MOSI pins are directly connected between the master and the slave. The MISO signal is the output from the slave, and the MOSI signal is the output from the master. The SS line is the slave select input to the slave; the SS pin of the master is not shown but is assumed to be inactive.

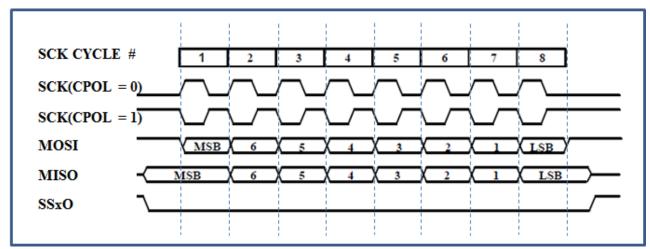


Figure 5.4 SCK Transfer Format when CPHA=1



5.2.4 SPI Timing

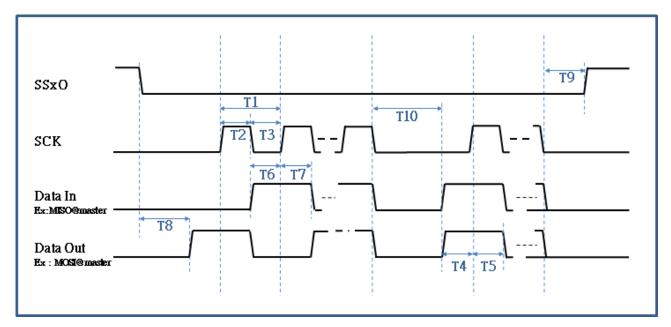


Figure 5.5 SPI Timing

| Parameter | Min (ns) | Typ(ns) | Max(ns) | Description |
|------------|----------|---------|---------|--|
| T1@master | T2+T3 | | | SCK Period when QSPI as master |
| T1@slave | 50 | | | Acceptable SCK Period when QSPI as slave device |
| T2 | 16.5 | | | SCK HIGH |
| Т3 | 16.5 | | | SCLK LOW |
| T4 | T3-1.7 | | T3-0.7 | Data output setup time to corresponding SCK edge |
| T5 | T2+0.1 | | T2+1.1 | Data output hold time to corresponding SCK edge |
| Т6 | 4.65 | | 9.35 | Data input required setup time to corresponding SCK edge |
| Т7 | | | 0.1 | Data input required hold time to corresponding SCK edge |
| Т8 | | 6*T1 | | SSxO setup time to 1 st SCK period boundary |
| Т9 | | 6*T1 | | SSxO hold time from last SCK period boundary |
| T10@master | | 6*T1 | | Idle time on SCK between byte boundary when master |
| T10@slave | 0 | | | Idle time on SCK between byte boundary when slave |

Table 5.2 SPI Timing for VCCIO=3.3V



5.3 I²C Bus Interface

 I^2C (Inter Integrated Circuit) is a multi-master serial bus invented by Philips. I^2C uses two bi-directional open-drain wires called serial data (SDA) and serial clock (SCL). Common I^2C bus speeds are the 100 kbit/s standard mode (SM), 400 kbit/s fast mode (FM), 1 Mbit/s Fast mode plus (FM+), and 3.4 Mbit/s High Speed mode (HS)

An I²C bus node can operate either as a master or a slave:

Master node – issues the clock and addresses slaves

Slave node – receives the clock line and address.

The FT4222H can operate as a master or slave, and is capable of speeds up to 3.4MBit/s. Besides the speed mode defined in $\rm I^2C$ standard specification, the $\rm I^2C$ controller of FT4222H can support flexible SCL frequency defined by the following function

SCL Freq =
$$\frac{\text{Operating Clock Frequency}}{M*(N+1)}$$
 $M = 6 \text{ or } 8$; $N = 1, 2, 3, \dots, 127$

When the target frequency is below 100KHz, the M will be equal to 8; otherwise, M will be equal to 6. For example, to generate a 2.5MHz frequency on SCL, the M will be selected as 6. Then with an operating clock frequency equal to 60MHz the user can set N as 3. The SCL frequency for I²C master mode can be set via the FT4222_I2CMaster_Init command defined in the support library, LibFT4222. Refer to the <u>User Guide For LibFT4222</u> for further details.

5.3.1 I²C Pin Definition

The I^2C function in the FT4222H is a fully configurable I^2C master/slave device. When the chip configuration is set as CNFMODE0 or CNFMODE3 and the USB-to- I^2C bridge function is enabled via the FT4222_I2CMaster_Init API which is defined in the support library LibFT4222. The pins of the FT4222H will be mapped accordingly. The I^2C pins are

- Clock SCL (pin-13), as clock output with open-drain design when I^2C bus is set as master. as clock input when I^2C bus is set as slave.
- Data SDA (pin-14), command/address/data transfer between master and slave with opendrain design

5.3.2 I²C Bus Protocol

There are four potential modes of operation for a given bus device, although most devices only use a single role (Master or Slave) and its two modes (Transmit and Receive):

- Master transmit sending data to a slave
- Master receive receiving data from a slave
- Slave transmit sending data to a master
- Slave receive receiving data from the master

The following figure shows the basic I²C bus protocol

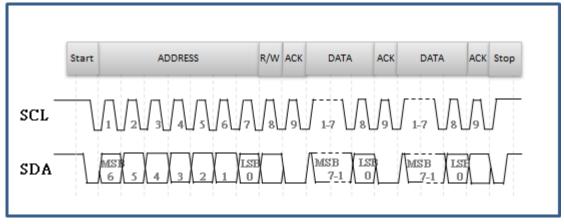


Figure 5.6 I²C Bus Protocol



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The master is initially in master transmit mode by sending a start bit followed by the 7-bit address of the slave it wishes to communicate with, which is finally followed by a single bit representing whether it wishes to write(0) to or read(1) from the slave.

If the slave exists on the bus then it will respond with an ACK bit (active low for acknowledged) for that address. The master then continues in either transmit or receive mode (according to the read/write bit it sent), and the slave continues in its complementary mode (receive or transmit, respectively).

The address and the data bytes are sent most significant bit first. The start bit is indicated by a high-to-low transition of SDA with SCL high; the stop bit is indicated by a low-to-high transition of SDA with SCL high.

If the master wishes to write to the slave then it repeatedly sends a byte with the slave sending an ACK bit. (In this situation, the master is in master transmit mode and the slave is in slave receive mode.)

If the master wishes to read from the slave then it repeatedly receives a byte from the slave, the master sends an ACK bit after every byte but the last one. (In this situation, the master is in master receive mode and the slave is in slave transmit mode.)

The master then ends transmission with a stop bit, or it may send another START bit if it wishes to retain control of the bus for another transfer (a "combined message").

I²C defines three basic types of message, each of which begins with a START and ends with a STOP:

- Single message where a master writes data to a slave;
- Single message where a master reads data from a slave;
- Combined messages, where a master issues at least two reads and/or writes to one or more slaves

In a combined message, each read or write begins with a START and the slave address. After the first START, these are also called repeated START bits; repeated START bits are not preceded by STOP bits, which is how slaves know the next transfer is part of the same message.

Users can refer to the I²C specification for more information on the protocol.

5.3.3 I²C Slave Address

When the FT4222H is configured as a USB to I^2C master bridge, it must be able to issue any value of 7-bits slave address. Users can issue I^2C commands to read or write data to a slave via the commands FT4222_I2CMaster_Read and FT4222_I2CMaster_Write, defined in the support library LibFT4222, with a corresponding slave address.

When the FT4222H is configured as a USB to I^2C slave bridge, the slave address may be defined by the user. This slave address parameter is defined by default as 40h and can be set once in the I^2C Slave Address parameter which is defined in the user data area of the OTP memory. For further details refer to Section 9.

5.3.4 I²C Timing

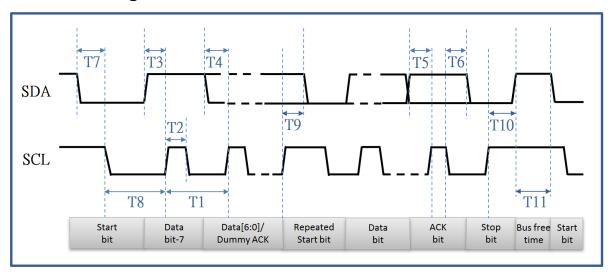
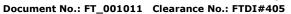


Figure 5.7 I²C Bus Timing







| D 1 | Min (| T () | Marrie | David III |
|----------------------------|------------------|------------|---------------------------|--|
| Parameter | Min(ns) | Typ(ns) | Max(ns) | Description |
| T0@48MHz | | 20.833 | | T0 is the period when operating clock=48MHz |
| T0@60MHz | | 16.666 | | T0 is the period when operating clock=60MHz |
| T0@80MHz | | 12.500 | | T0 is the period when operating clock=80MHz |
| | T | Tir | ning for I ² C | Master |
| T1@SM | 16*T0 | 8*(1+N)*T0 | | SCK Period when I ² C as master with standard speed mode(SM) |
| T1@FM/HM | 12*T0 | 6*(1+N)*T0 | | SCK Period when I^2C as master with FM, FM+, HS speed mode |
| T2 | 8*T0 | 4*(1+N)*T0 | | SCK high pulse width when I ² C as master with standard speed mode(SM) |
| T2 | 4*T0 | 2*(1+N)*T0 | | SCK high pulse width when I ² C as master with FM, FM+, HS speed mode |
| Т3 | | 2*(1+N)*T0 | | SDA output setup time to SCL rising edge when ${\rm I}^2{\rm C}$ as master |
| T4 | | 2*(1+N)*T0 | | SDA output hold time tos SCL falling edge when ${\rm I}^2{\rm C}$ as master |
| T5 | | | >=0 | input setup time requirement from SDA to SCL rising edge when I^2C as master |
| T6 | | | >=0 | input hold time requirement from SDA to SCL falling edge when I ² C as master |
| T7 | | 2*(1+N)*T0 | | Start bit setup time to SCL falling edge |
| T8 | | 4*(1+N)*T0 | | Start bit hold time to SCL falling edge |
| Т9 | | 2*(1+N)*T0 | | Stop bit setup time to SCL rising edge |
| T10 | | 2*(1+N)*T0 | | Stop bit hold time to SCL rising edge |
| T11 | 4*(1+N)*T0 | | | Bus free time between Start and Stop bit |
| | 1 | Ti | ming for I ² | C Slave |
| T1 | 12*T0 | | | Acceptable SCL Period when I ² C as slave device |
| T2 | 1*T0 | | | SCL high pulse width requirement when I ² C as slave |
| Т3 | | | >=0 | input setup time requirement from SDA to SCL rising edge when I ² C as slave device |
| T4 | 1*T0 | | | input hold time requirement from SDA to SCL falling edge when I ² C as slave device |
| T5 | | T8 - T6 | | SDA output setup time to SCL rising edge |
| Т6 | 3*T0 | 4*T0 | 5*T0 | SDA output hold time to SCL falling edge |
| Table 5.3 I ² C | Timing for VCCIO | D=3.3V | ı | |

Note that N can be ranged from 1 to 255 $\,$



5.4 GPIOs

When configuration mode of FT4222H is set as CNFMODE0 or CNFMODE1, a GPIO pipe will be enabled. These 4 pins, GPIO0, GPIO1, GPIO2 and GPIO3, can be set as general purpose Input/Output pins or other functions such as multi-channel SPI slave selections, I2C interface, suspend out indicator, remote wake up input or interrupt. If no functions are set on these pins, the default function is GPIO. User can set the direction for GPIOs via the API, FT4222_GPIO_Init, defined in LibFT4222. The logic level can be read and written via the APIs, FT4222_GPIO_Read and FT4222_GPIO_Write.

FT4222H also provides an interrupt input source for user to ultilize. GPIO3(pin-16) can be set as an interrupt input source via the API, FT4222_SetWakeUpInterrupt, defined in LibFT4222. GPIO3 can be set as rising edge or falling edge triggered interrupt via FT_Prog. The related parameter defined in user area is named as interrupt trigger edge. The default setting is rising edge triggered. Detail can be referred to Table9.1.

Figure 5.8 shows the different behaviour when GPIO3 acts as GPIO or interrupt. Interrupt is default set as rising edge triggered. User can choose either one for their application.

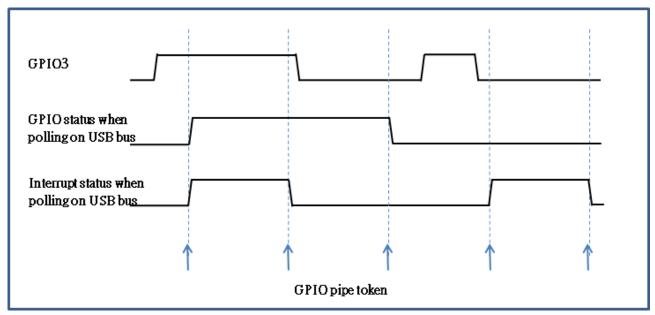


Figure 5.8 Different status when GPIO3 set as GPIO or interrupt input



6 Devices Characteristics and Ratings

6.1 Absolute Maximum Ratings

The absolute maximum ratings for the FT4222H devices are as follows. These are in accordance with the Absolute Maximum Rating System (IEC 60134). Exceeding these may cause permanent damage to the device.

| Parameter | Value | Unit | Conditions |
|--|--|-----------|------------|
| Storage Temperature | -65°C to 150°C | Degrees C | |
| Floor Life (Out of Bag) At Factory Ambient (30°C / 60% Relative Humidity) | 168 Hours (IPC/JEDEC J- STD-033A MSL Level 3 Compliant)* | Hours | |
| Ambient Operating Temperature (Power Applied) | -40°C to 85°C | Degrees C | |
| MTTF FT4222H | TBD | Hours | |
| VCCIN Supply Voltage | -0.3 to +5.5 | V | |
| VCCIO IO Voltage | -0.3 to +4.0 | V | |
| VPP Supply Voltage | 6.5±0.25 | V | |
| DC Input Voltage – USBDP and USBDM | -0.5 to +3.63 | V | |
| DC Input Voltage – High Impedance Bi-directionals (powered from VCCIO) | -0.3 to +(VCCIO+0.5V) | V | |
| DC Output Current - Outputs | 100 ** | mA | |

Table 6.1 Absolute Maximum Ratings

6.2 ESD and Latch-up Specifications

| Description | Specification |
|---------------------------|---------------|
| Human Body Mode (HBM) | > ± 2kV |
| Machine mode (MM) | > ± 200V |
| Charged Device Mode (CDM) | > ± 500V |
| Latch-up | > ± 200mA |

Table 6.2 ESD and Latch-Up Specifications

^{*} If devices are stored out of the packaging beyond this time limit the devices should be baked before use. The devices should be ramped up to a temperature of $+125^{\circ}$ C and baked for up to 17 hours.

^{**} This DC output currunt is also as the power supply source for FT4222H operating. If it must be the source for other component on the system, it only can supply 25mA or less.

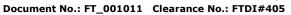


6.3 DC Characteristics

DC Characteristics (Ambient Temperature = -40°C to +85°C)

| Parameter | Description | Minimum | Typical | Maximum | Units | Conditions |
|-----------|-----------------------------------|---------|---------|---------|-------|---|
| VCC1 | VCCIN Operating | 4.5 | 5 | 5.5 | V | VCCIN is supplied with 5V |
| VCCI | Supply Voltage | 2.97 | 3.3 | 3.63V | ٧ | VCCIN is supplied with 3.3V |
| | | 2.97 | 3.3 | 3.63 | ٧ | VCCIO is supplied with 3.3V |
| VCC2 | VCCIO Operating Supply Voltage | 2.25 | 2.5 | 2.75 | V | VCCIO is supplied with 2.5V |
| | | 1.62 | 1.8 | 1.98 | ٧ | VCCIO is supplied with 1.8V |
| | | | 50 | 52 | mA | Normal Operation at 24MHz |
| Tool | Operating Supply Current | | 62 | 64 | mA | Normal Operation at 48MHz |
| Icc1 | | | 68 | 70 | mA | Normal Operation at 60MHz |
| | | | 78 | 80 | mA | Normal Operation at 80MHz |
| | Suspend Supply Current | | 375 | 460 | μA | USB Suspend when SPI Master |
| Loca | | | 377 | 465 | μΑ | USB Suspend when SPI Slave |
| Icc2 | | | 386 | 419 | μА | USB Suspend when I ² C Master |
| | | | 388 | 456 | μΑ | USB Suspend when I ² C Slave |
| 3V3 | 3.3v regulator output | 2.97 | 3.3 | 3.63 | V | VCCIN must be greater than 3V3 otherwise VOUT3V3 is an input which must be driven with 3.3V |

Table 6.3 Operating Voltage and Current



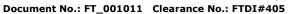


| Parameter | Description | Minimum | Typical | Maximum | Units | Conditions |
|-----------|--|---------|---------|---------|-------|---|
| | | 2.97 | VCCIO | VCCIO | V | Ioh = +/-2mA I/O Drive strength* = 4mA |
| Voh | Output Voltage High | 2.97 | VCCIO | VCCIO | V | I/O Drive strength* = 8mA |
| | | 2.97 | VCCIO | VCCIO | V | I/O Drive strength* = 12mA |
| | | 2.97 | VCCIO | VCCIO | V | I/O Drive strength* = 16mA |
| | | | 0 | 0.4 | V | Iol = +/-2mA I/O Drive strength* = 4mA |
| Vol | Output Voltage Low | | 0 | 0.4 | V | I/O Drive strength* = 8mA |
| | | | 0 | 0.4 | V | I/O Drive strength* = 12mA |
| | | | 0 | 0.4 | V | I/O Drive strength* = 16mA |
| Vil | Input low Switching Threshold | | | 0.8 | V | LVTTL |
| Vih | Input High Switching Threshold | 2.0 | | | V | LVTTL |
| Vt | Switching Threshold | | 1.49 | | V | LVTTL |
| Vt- | Schmitt trigger negative going threshold voltage | | 1.15 | | V | |
| Vt+ | Schmitt trigger positive going threshold voltage | | 1.64 | | V | |
| Rpu | Input pull-up resistance | 40 | 75 | 190 | ΚΩ | Vin = 0 |
| Rpd | Input pull-down resistance | 40 | 75 | 190 | ΚΩ | Vin =VCCIO |
| Iin | Input Leakage Current | -10 | +/-1 | 10 | μΑ | Vin = 0 |
| Ioz | Tri-state output leakage current | -10 | +/-1 | 10 | μΑ | Vin = 5.5V or 0 |

Table 6.4 I/O Pin Characteristics VCCIO = +3.3V (except USB PHY pins)

^{*} The I/O drive strength and slow slew-rate are configurable in the OTP memory.







| Parameter | Description | Minimum | Typical | Maximum | Units | Conditions |
|-----------|---|---------|---------|---------|-------|--|
| | | 2.25 | VCCIO | VCCIO | V | Ioh = +/-2mA I/O Drive strength* = 4mA |
| Voh | Output Voltage High | 2.25 | VCCIO | VCCIO | V | I/O Drive strength* = 8mA |
| | | 2.25 | VCCIO | VCCIO | V | I/O Drive strength* = 12mA |
| | | 2.25 | VCCIO | VCCIO | V | I/O Drive strength* = 16mA |
| | | | 0 | 0.4 | V | Iol = +/-2mA I/O Drive strength* = 4mA |
| Vol | Output Voltage Low | | 0 | 0.4 | V | I/O Drive strength* = 8mA |
| | | | 0 | 0.4 | V | I/O Drive strength* = 12mA |
| | | | 0 | 0.4 | V | I/O Drive strength* = 16mA |
| Vil | Input low Switching Threshold | | | 0.8 | V | LVTTL |
| Vih | Input High Switching Threshold | 1.7 | | | V | LVTTL |
| Vt | Switching Threshold | | 1.1 | | V | LVTTL |
| Vt- | Schmitt trigger negative going threshold voltage | | 0.8 | | V | |
| Vt+ | Schmitt trigger positive going threshold voltage | | 1.2 | | V | |
| Rpu | Input pull-up resistance | 40 | 75 | 190 | ΚΩ | Vin = 0 |
| Rpd | Input pull-down resistance | 40 | 75 | 190 | ΚΩ | Vin =VCCIO |
| Iin | Input Leakage Current | -10 | +/-1 | 10 | μΑ | Vin = 0 |
| Ioz | Tri-state output leakage current O Pin Characteristics VCC | -10 | +/-1 | 10 | μΑ | Vin = 5.5V or 0 |

Table 6.5 I/O Pin Characteristics VCCIO = +2.5V (except USB PHY pins)

 $[\]ensuremath{^{*}}$ The I/O drive strength and slow slew-rate are configurable in the OTP memory.



| Parameter | Description | Minimum | Typical | Maximum | Units | Conditions |
|-----------|--|---------|---------|---------|-------|--|
| | | 1.62 | VCCIO | VCCIO | V | Ioh = +/-2mA I/O Drive strength* = 4mA |
| Voh | Output Voltage High | 1.62 | VCCIO | VCCIO | V | I/O Drive strength* = 8mA |
| | | 1.62 | VCCIO | VCCIO | V | I/O Drive strength* = 12mA |
| | | 1.62 | VCCIO | VCCIO | V | I/O Drive strength* = 16mA |
| | | | 0 | 0.4 | V | Iol = +/-2mA I/O Drive strength* = 4mA |
| Vol | Vol Output Voltage Low | | 0 | 0.4 | V | I/O Drive strength* = 8mA |
| | | | 0 | 0.4 | V | I/O Drive strength* = 12mA |
| | | | 0 | 0.4 | V | I/O Drive strength* = 16mA |
| Vil | Input low Switching Threshold | | | 0.63 | V | LVTTL |
| Vih | Input High Switching Threshold | 1.17 | | | V | LVTTL |
| Vt | Switching Threshold | | 0.77 | | V | LVTTL |
| Vt- | Schmitt trigger negative going threshold voltage | | 0.557 | | V | |
| Vt+ | Schmitt trigger positive going threshold voltage | | 0.893 | | V | |
| Rpu | Input pull-up resistance | 40 | 75 | 190 | ΚΩ | Vin = 0 |
| Rpd | Input pull-down resistance | 40 | 75 | 190 | ΚΩ | Vin =VCCIO |
| Iin | Input Leakage Current | -10 | +/-1 | 10 | μΑ | Vin = 0 |
| Ioz | Tri-state output leakage current | -10 | +/-1 | 10 | μА | Vin = 5.5V or 0 |

Table 6.6 I/O Pin Characteristics VCCIO = +1.8V (except USB PHY pins)

 $[\]ensuremath{^{*}}$ The I/O drive strength and slow slew-rate are configurable in the OTP memory.



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DC Characteristics (Ambient Temperature = -40°C to +85°C)

| Parameter | Description | Minimum | Typical | Maximum | Units | Conditions |
|--|---------------------------------|---------|---------|---------|-------|------------------------------------|
| V _{PHY} , V _{PLL} | PHY Operating Supply Voltage | 3.0 | 3.3 | 3.6 | V | 3.3V I/O |
| $ m I_{CCPHY}$ | PHY Operating Supply Current | | 30 | 60 | mA | High-speed operation at 480 MHz |
| I _{CCPHY} (susp) | PHY Suspend Supply Current | | 210 | 250 | μΑ | USB Suspend |

Table 6.7 USB PHY Operating Voltage and Current

| Parameter | Description | Minimum | Typical | Maximum | Units | Conditions |
|---------------------|---|---------|---------|---------|-------|--|
| V _{HSDIFF} | High Speed Differential input voltage sensitivity | 300 | | | mV | $V_{I(DP)} - V_{I(DM)}$ Measure at the connection of an application circuit |
| V _{HSCM} | Common mode voltage range of high speed data signaling | -50 | | 500 | mV | |
| | High speed Squelch | | | 100 | mV | Squelch is detected |
| V_{HSSQ} | detection thresdhold | 150 | | | mV | Squelch is not detected |
| V | High Speed | 625 | | | mV | Disconnection is detected |
| V _{HSDSC} | disconnection detection threshold | | | 525 | mV | Disconnection is not detected |
| V _{HSOI} | High Speed idle level output voltage(Differential) | -10 | | 10 | mV | |
| V _{HSOL} | High Speed low level output voltage(Differential) | -10 | | 10 | mV | |
| V _{HSOL} | High Speed high level output voltage(Differential) | 360 | | 400 | mV | |
| V _{CHIRPJ} | Chirp-J output voltage(Differential) | 700 | | 1100 | mV | |
| V_{CHIRPK} | Chirp-K output voltage(Differential) | -900 | | -500 | mV | |
| V_{DI} | Full Speed Differential input voltage sensitivity | 0.2 | | | V | $V_{I(DP)} - V_{I(DM)}$ |
| V _{CM} | Differential common mode voltage range of full speed data signaling | 0.8 | | 2.5 | V | |



| FTD |
|------------|
| Chip |

| V_{SE} | Full Speed Single-ended receiver threshold | 0.8 | 2.0 | V | |
|--------------------|--|-----|-----|---|--|
| V _{OLPHY} | Full Speed Low-level output voltage | 0 | 0.3 | V | |
| V _{OHPHY} | Full Speed High-level output voltage | 2.8 | 3.6 | V | |

Table 6.8 USB I/O Pin (DP, DM) Characteristics

6.4 OTP Memory Reliability Characteristics

The internal 128 Bytes OTP memory has the following reliability characteristics:

| Parameter | Value | Unit |
|----------------|-----------|-------|
| Data Retention | 10 | Years |
| Write Cycle | 1 | Times |
| Read Cycle | Unlimited | Times |

Table 6.9 OTP Memory Characteristics



7 FT4222H Configurations

The following sections illustrate possible USB power configurations for the FT4222H.

7.1 USB Bus Powered Configuration

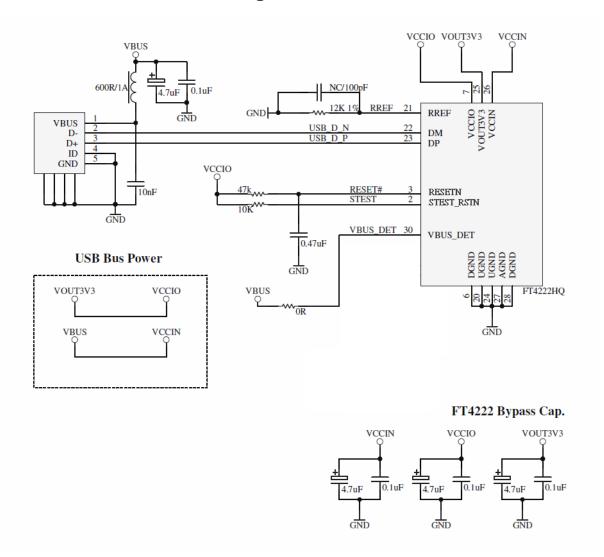


Figure 7.1 Bus Powered Configuration

Error! Reference source not found. Illustrates the FT4222H in a typical USB2.0 bus powered design configuration. A USB bus powered device gets its power from the USB bus. Basic rules for USB bus power devices are as follows

- i) On plug-in to USB, the device should draw no more current than 100mA.
- ii) In USB Suspend mode the device should draw no more than 2.5mA.
- iii) A bus powered, high power USB device (one that draws more than 100mA) can use SUSP_OUT(pin-15) as a power disable function and use it to keep the current below 2.5mA on USB suspend.
- iv) A device that consumes more than 100mA cannot be plugged into a USB bus powered hub.
- v) No device can draw more than 500mA from the USB bus.

The power descriptors in the internal OTP memory of the FT4222H should be programmed to match the current drawn by the device.

A ferrite bead is connected in series with the USB power supply to reduce EMI noise from the FT4222H and associated circuitry being radiated down the USB cable to the USB host. The value of the Ferrite Bead depends on the total current drawn by the application. A suitable range of Ferrite Beads is available from Steward (www.steward.com), for example Steward Part # MI0805K400R-10.



7.2 Self Powered Configuration with 5V Source Input

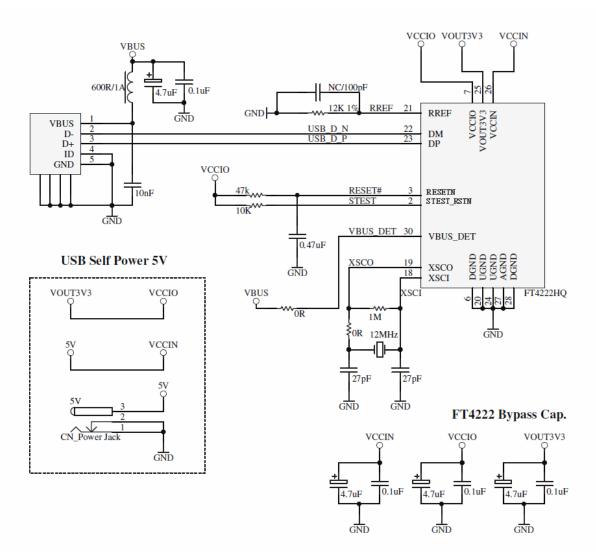


Figure 7.2 Self Powered Configuration with 5V Source Input

Error! Reference source not found. illustrates the FT4222H in a typical USB2.0 self powered configuration. A USB self powered device gets its power from its own power supply, 5V, and does not draw current from the USB bus. The basic rules for USB self powered devices are as follows –

- i) A self powered device should not force current down the USB bus when the USB host or hub controller is powered down.
- ii) A self powered device can use as much current as it needs during normal operation and USB suspend as it has its own power supply.
- iii) A self powered device can be used with any USB host, a bus powered USB hub or a self powered USB hub.

The power descriptor in the internal OTP memory of the FT4222H should be programmed to a value of zero (self powered).

In order to comply with the first requirement above, the USB bus power (USB connector pin 1) is used to control the VBUS_DET pin of the FT4222H device. When the USB host or hub is powered up an internal $1.5k\Omega$ resistor on DP is pulled up to +3.3V, thus identifying the device to the USB host or hub. When the USB host or hub is powered off, VBUS_DET pin will be low and the FT4222H is held in a suspend state. In this state the internal $1.5k\Omega$ resistor is not pulled up to any power supply (hub or host is powered down), so no current flows down DP via the $1.5k\Omega$ pull-up resistor. Failure to do this may cause some USB host or hub controllers to power up erratically.



7.3 Self Powered Configuration with 3.3V Source In

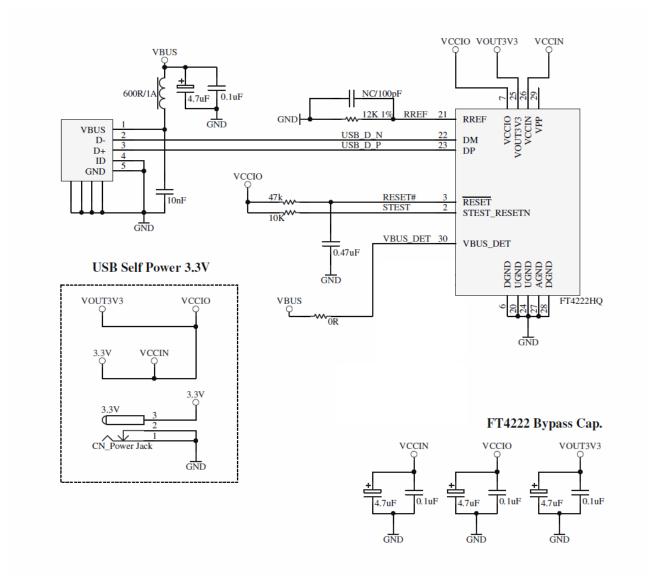


Figure 7.3 Self Powered Configuration with 3.3V Source Input

Error! Reference source not found. illustrates the FT4222H in a typical USB self powered configuration similar to **Error! Reference source not found.**. The difference here is that the self power source is 3.3V. If using 3.3V as power source in, remember to connect it to VOUT3V3 to supply actual operating voltage to USB2.0 PHY.



7.4 Crystal Oscillator Configuration

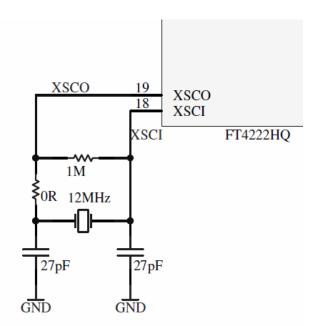


Figure 7.4 Recommended FT4222H Crystal Oscillator Configuration.

illustrates how to connect the FT4222H with a $12\text{MHz} \pm 0.003\%$ crystal. In this case loading capacitors should to be added between OSCI, OSCO and GND as shown. A value of 27pF is shown as the capacitor in the example – this will be good for many crystals but it is recommended to select the loading capacitor value based on the manufacturer's recommendations wherever possible. It is recommended to use a parallel cut type crystal.

It is also possible to use a 12 MHz oscillator with the FT4222H. In this case the output of the oscillator would drive XSCI, and XSCO should be left unconnected. The oscillator must have a CMOS output drive capability.

| Parameter | Description | Minimum | Typical | Maximum | Units | Conditions |
|-----------|-----------------------|---------|---------|---------|-------|------------|
| XSCI Vin | Input Voltage | 2.97 | 3.30 | 3.63 | V | |
| FIn | Input Frequency | | 12 | | MHz | +/- 30ppm |
| Ji | Cycle to cycle jitter | | < 150 | | pS | |

Table 7.1 XSCI Input characteristics



7.5 USB Battery Charging Detection

An addition to the USB specification (http://www.usb.org/developers/devclass_docs/BCv1.2_011912.zip) is to allow for additional charging profiles to be used for charging batteries in portable devices. These charging profiles do not enumerate the USB port of the peripheral. The FT4222H device will detect that a USB compliant dedicated charging port (DCP) is connected. Once detected while in suspend mode a battery charge detection signal is then provided to allow external logic to switch to charging mode as opposed to operation mode.

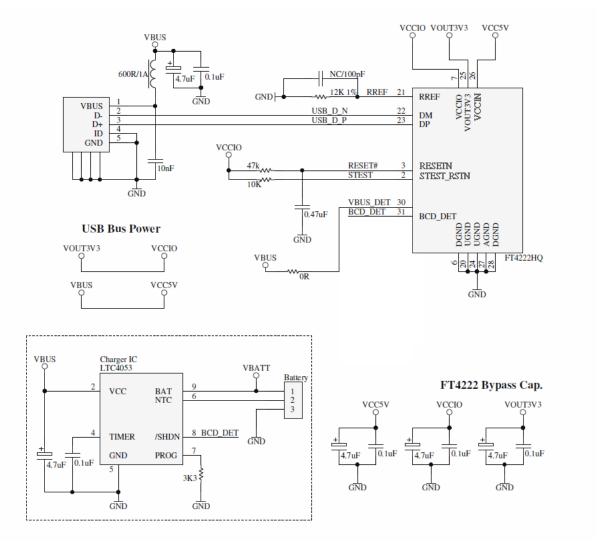


Figure 7.5 USB Battery Charging Detection

To use the FT4222H with battery charging detection, the BCD_DET pin acts as BCD Charger output to switch the external charger circuitry on. If the charging circuitry requires an active low signal to enable it, the polarity of BCD_DET can be configured in the vender configuration area of internal OTP memory.

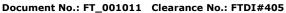
When connected to a USB compliant dedicated charging port (DCP, as opposed to a standard USB host) the device USB signals will be shorted together. The BCD charger signal will bring the LTC4053 out of suspend and allow battery charging to start. The charge current in the example above is 1A as defined by the resistance on the PROG pin.

To calculate the equivalent resistance on the LTC4053 PROG pin select a charge current, then Res = $1500 \text{V/I}_{\text{chq}}$

For more configuration options of the LTC4053 refer to:

Section4.3 Example with 1 CBUS pin in AN 175 Battery Charging Over USB

Note: If the FT4222H is connected to a standard host port such that the device is enumerated, the signal BCD_DET is inactive, LTC4053 is in shut down condition and the charging function will not be enabled.





8 Application Examples

The following diagrams show the possible applications of the FT4222H. In Figure 8.1, a control IC with an SPI slave interface but without a USB device interface can easily connect to USB by integrating the FT4222H into the system. With FTDI's mature and stable D2XX driver, and easy to use support library, LibFT4222, the FT4222H can easily connect an application to USB.

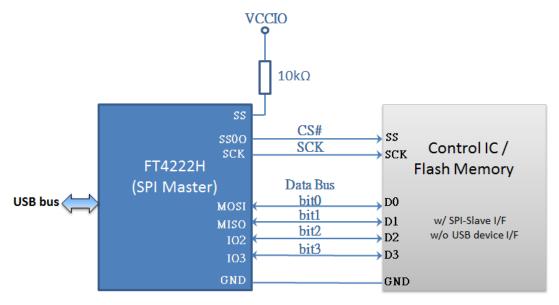


Figure 8.1 Application Example 1

In Figure 8.2, a control IC with an SPI master interface but without a USB upstream port (USB device interface) can easily connect to USB by integrating the FT4222H into the system. With single SPI slave interface defined in FT4222H and easy to use API defined in LibFT4222, it is easy to connect an application to USB via FT4222H.

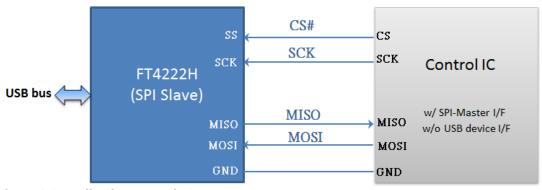


Figure 8.2 Application Example 2



In Figure8.3, a control IC with an I^2C slave interface but without a USB device interface can easily connect to USB by integrating the FT4222H into the system. With FTDI's mature and stable D2XX driver, and easy to use support library, LibFT4222, the FT4222H can easily connect an application to USB. With suitable pull-high resistor value on I^2C bus, the transfer speed at this I^2C interface can be speed up to the HS mode defined in I^2C specification.

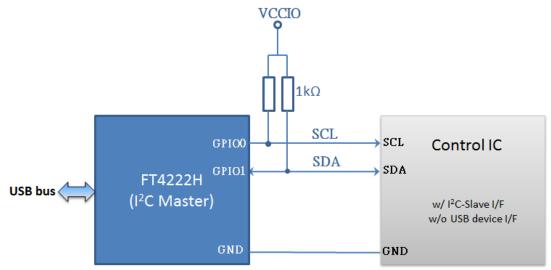


Figure 8.3 Application Example 3

In Figure 8.4, a control IC with an I^2C master interface but without a USB upstream port (USB device interface) can easily connect to USB by integrating the FT4222H into the system. With I^2C slave interface defined in FT4222H and easy to use API defined in LibFT4222, it is easy to connect an application to USB via FT4222H. With suitable pull-high resistor value on I^2C bus, the transfer speed at this I^2C interface can be speed up to the HS mode.

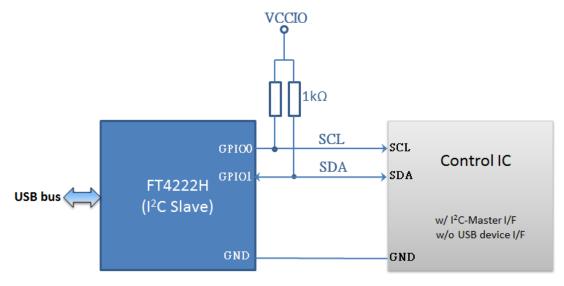


Figure 8.4 Application Example 4

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9 Internal OTP Memory Configuration

The FT4222H includes an internal OTP memory which holds the USB configuration descriptors, other configuration data for the chip and also user data areas. Following a power-on reset or a USB reset the FT4222H will scan its internal OTP memory and read the USB configuration descriptors stored there.

In many cases, the default values programmed into the OTP memory will be suitable and no reprogramming will be necessary. The defaults can be found in Section 9.1.

The OTP memory in the FT4222H can be programmed over USB if the values need to be changed for a particular application. Further details of this are provided from section 9.2 onwards.

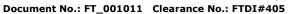
Users who do not have their own USB Vendor ID but who would like to use a unique Product ID in their design can apply to FTDI for a free block of unique PIDs. See TN 100 - USB Vendor ID/Product ID Guidelines for more details.

9.1 Default Values

The default factory programmed values of the internal OTP memory are shown in Table9.1.

| Parameter | Default Value | Notes |
|------------------------|---------------|---|
| Device Type | FT4222H | Read-Only. Indicate the Chip is FT4222H. |
| USB Vendor ID (VID) | 0403h | USB Vendor ID. Defined in USB device descriptor. The format is 16-bit hex coded and default is set as FTDI VID. |
| USB Product ID (PID) | 601Ch | USB Product ID. Defined in USB device descriptor The format is 16-bit hex coded and default is set as FTDI VID. |
| USB Version | 0200h | Read-only. Returns USB 2.0 device descriptor to the host. Note: FT4222H is a Hi-speed USB2.0 device. If the plugging-in host/hub is full speed only, FT4222H will operate at full speed without changing this USB version parameter to USB1.1. |
| Power Source | Bus Powered | Define the power source is from the USB bus or local source. |
| Max Bus Power Current | 100mA | The max power will draw from VBUS when bus power. Range from 0~500mA. If the power source is defined as self-power, it must be set as 0mA. |
| Remote Wake Up | Enable | Define if the FT4222H support remote wake up or not. |
| Manufacturer Name | FTDI | Describing the manufacturer. For string descriptor defined in USB device descriptor |
| Product Description | FT4222 | Describing the product. For string descriptor defined in USB device descriptor |
| Serial Number Enabled? | No | Enable the string descriptor for serial number or not. |







| Serial Number | None | A unique serial number is generated and programmed into the OTP memory. Refer to the Uitility FT_Prog for details |
|---|-------------|---|
| Enable Suspend Out | enable | Set GPIO2(pin-15) as USB suspend indicator |
| I ² C Slave Address | 40h | Set the I^2C slave address when I^2C Slave function is enabled. Range from $00h \sim 7Fh$ |
| SPI Drive Strength | 4mA | Adjustable drive strength for SPI related pins SCK, MISO/MOSI/IO2/IO3, SS0O. Drive strength can be set as 4mA, 8mA, 12mA and 16mA |
| SPI Weak Pullup/Pulldown | disable | Enable the weak pullup / pulldown resistor on the pin SS(pin-32). Default is disabled(without any pull). |
| SPI Slew Rate Enable? | disable | Set the slew rate control for SPI related pins SCK, MISO, MOSI, SS0O, IO2, IO3. Default is disabled |
| SPI Suspend | pull-low | Define the behaviour of SPI related pins MISO, MOSI, IO2/IO3, SS0O when USB suspend happens. Behaviour can be set as pull-high or pull-low. |
| GPIO Drive Strength | 4mA | Adjustable drive strength for GPIO related pins GPIO0, GPIO1, GPIO2, GPIO3. Drive strength can be set as 4mA, 8mA, 12mA and 16mA |
| GPIO Open Drain | disable | Set the behaviour of GPIO pins as open-drain. Default is disabled(GPIO acts as push-pull mode) |
| GPIO Weak Pullup/Pulldown | disable | Enable the weak pullup / pulldown resistor on the pins GPIO0, GPIO1, GPIO2, GPIO3. Default is disabled(without any pull). |
| GPIO Suspend | pull-low | Define the behaviour of GPIO related pins GPIO0,GPIO1, GPIO22, GPIO3 when suspend happens. Pins can be set as pull-high or pull-low |
| BCD_DET Function Disable? | No | Battery Charger Detection function can be disabled on BCD_DET pin(pin-31). |
| BCD_DET Drive Strength | 4mA | Adjustable drive strength for BCD_DET pin. Drive strength can be set as 4mA, 8mA, 12mA and 16mA |
| BCD_DET Polarity | active-high | Set the polarity on BCD_DET pinfor indicating battery charge detected. Default is set as activehigh. |
| Interrupt trigger edge Table 9.1 Default Internal OT | rising edge | Define the interrupt trigger edge when GPIO3(pin- 16) is set as INTR/WAKEUP function. Default is rising-edge triggered. |

Table 9.1 Default Internal OTP Memory Configuration



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9.2 Method of Programming the OTP Memory

9.2.1 Programming the OTP memory over USB

The OTP memory on a FT4222H device can be programmed over USB. This method is the same as for the EEPROM on other FTDI devices such as the FT232R. Please note that in order to program OTP, the FT4222H requires an additional programming voltage (6.5V) on its VPP pin. The programming board , UMFT4222PROG, supplies a easy connection bridge between FT4222H and USB host for boosting the VBUS up to 6.5V and for commincating with programming utility FT_Porg. Details can refer to the Datasheet for UMFT4222PROG, the FT4222H programming module.

The FT_Prog utility is provided free-of-charge from the FTDI website, and can be found at the link below. The user guide is also available at this link.

http://www.ftdichip.com/Support/Utilities.htm#FT Prog

Additionally, D2XX commands can be used to program the OTP memory from within user applications. For more information on the commands available, please see the D2XX Programmers Guide below.

http://www.ftdichip.com/Support/Documents/ProgramGuides/D2XX Programmer's Guide(FT 000071).pdf

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10 Package Parameters

The FT4222H is available in a VQFN-32 package. The solder reflow profile for VQFN-32 is described in Section 10.3.

10.1 VQFN-32 Package Mechanical Dimensions

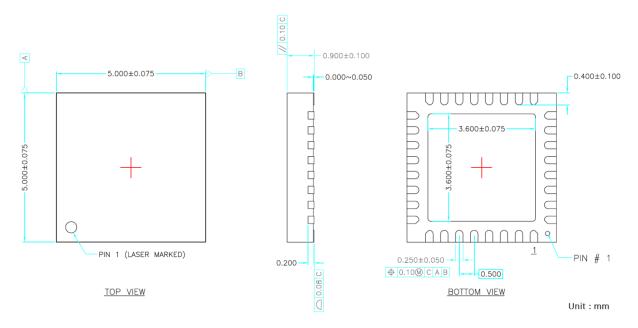


Figure 10.1 VQFN-32 Package Dimensions

The FT4222H is supplied in a RoHS compliant leadless VQFN-32 package. The package is lead (Pb) free, and uses a 'green' compound. The package is fully compliant with European Union directive 2002/95/EC.

This package is nominally $5.00 \, \text{mm} \times 5.00 \, \text{mm}$. The solder pads are on a $0.5 \, \text{mm}$ pitch. The above mechanical drawing shows the VQFN-32 package. All dimensions are in millimetres.

The centre pad on the base of the FT4222H is internally connected to GND and the PCB should not have signal tracking on the top layer under this area. Connect to GND.



10.2 VQFN-32 Package Markings

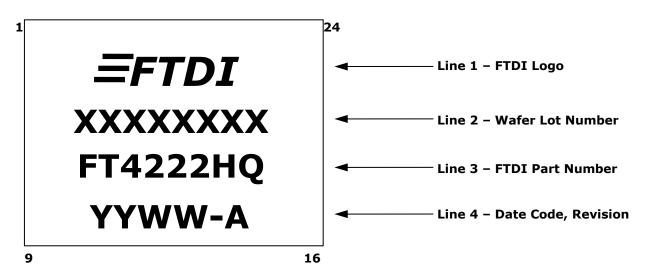


Figure 10.2 VQFN-32 Package Markings

The date code format is YYWW where WW = 2 digit week number, YY = 2 digit year number. This is followed by the revision number.

The code **XXXXXXX** is the manufacturing LOT code

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10.3 Solder Reflow Profile

The FT4222H is supplied in a Pb free VQFN-32 package. The recommended solder reflow profile is shown in **Error! Reference source not found.**.

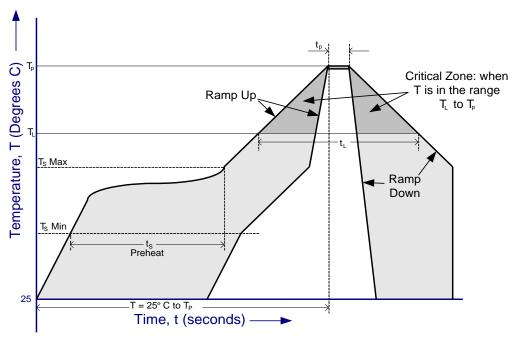


Figure 10.3 FT4222H Solder Reflow Profile

The recommended values for the solder reflow profile are detailed in **Error! Reference source not found.** Values are shown for both a completely Pb free solder process (i.e. the FT4222H is used with Pb free solder), and for a non-Pb free solder process (i.e. the FT4222H is used with non-Pb free solder).

| Profile Feature | Pb Free Solder Process | Non-Pb Free Solder Process |
|---|-------------------------------------|-------------------------------------|
| Average Ramp Up Rate $(T_s$ to $T_p)$ | 3°C / second Max. | 3°C / Second Max. |
| Preheat - Temperature Min $(T_s Min.)$ - Temperature Max $(T_s Max.)$ - Time $(t_s Min to t_s Max)$ | 150°C 200°C 60 to 120 seconds | 100°C 150°C 60 to 120 seconds |
| Time Maintained Above Critical Temperature T_L : - Temperature (T_L) - Time (t_L) | 217°C 60 to 150 seconds | 183°C 60 to 150 seconds |
| Peak Temperature (T _p) | 260°C | 240°C |
| Time within 5°C of actual Peak Temperature (t_p) | 20 to 40 seconds | 20 to 40 seconds |
| Ramp Down Rate | 6°C / second Max. | 6°C / second Max. |
| Time for T= 25°C to Peak Temperature, T_p | 8 minutes Max. | 6 minutes Max. |

Table 10.1 Reflow Profile Parameter Values



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Appendix A - References

Useful Application Notes

http://www.ftdichip.com/Support/Documents/AppNotes/AN 329 User Guide For LibFT4222.pdf

http://www.ftdichip.com/Support/Documents/DataSheets/Modules/DS UMFT4222EV.pdf

http://www.ftdichip.com/Support/Documents/DataSheets/Modules/DS UMFT4222PROG.pdf

http://www.ftdichip.com/Support/Utilities.htm#FT Prog

http://www.ftdichip.com/Support/Documents/ProgramGuides/D2XX Programmer's Guide(FT 000071).pdf

http://www.ftdichip.com/Documents/AppNotes/AN 107 AdvancedDriverOptions AN 000073.pdf

http://www.ftdichip.com/Documents/AppNotes/AN 121 FTDI Device EEPROM User Area Usage.pdf

http://www.ftdichip.com/Documents/InstallGuides.htm

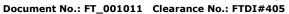
http://www.ftdichip.com/Support/Documents/TechnicalNotes/TN 100 USB VID-PID Guidelines.pdf

http://www.ftdichip.com/Support/Documents/AppNotes/AN 175 Battery%20Charging%20Over%20USB%20with%20FTEX%20Devices.pdf

http://i2c2p.twibright.com/spec/i2c.pdf

http://www.usb.org/developers/devclass_docs/BCv1.2_011912.zip







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Appendix C - Revision History

Document Title: FT4222H USB2.0 to QSPI/I²C Bridge IC

Document Reference No.: FT_001011
Clearance No.: FTDI#405

Product Page:

Document Feedback: Send Feedback

Version 1.0 Initial Release 16th September 2014

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