mikroProg[™] for PIC®, dsPIC® and PIC32®

mikroProgTM is a fast USB programmer with mikroICDTM hardware In-Circuit Debugger support. Smart engineering allows mikroProg to support PIC10®, PIC12®, PIC16®, PIC18®, dsPIC30/33®, PIC24® and PIC32® devices in a single programmer!











TO OUR VALUED CUSTOMERS

I want to express my thanks to you for being interested in our products and for having confidence in MikroElektronika.

The primary aim of our company is to design and produce high quality electronic products and to constantly improve the performance thereof in order to better suit your needs.

Nebojsa Matic General Manager

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Introduction to mikroProg[™]



mikroProgTM for PIC®, dsPIC® and PIC32® represents fast and reliable programmer with ICD support. Specially designed firmware allows programming of all Microchip® microcontrollers: PIC®, dsPIC®, PIC24® and PIC32®. And there's no need for firmware change each time you select a new microcontroller architecture because mikroProgTM firmware takes care of all supported architectures. Supporting new microcontrollers is easy. Just by downloading the latest version of mikroProg SuiteTM for PIC® your programmer is ready to program new devices.

Key features

- In-Circuit Debugging (ICD).
- One firmware for PIC®, dsPIC®, PIC24® and PIC32® microcontroller families
- New microcontrollers support via latest version of mikroProg[™] Suite for PIC® software
- Can provide power supply for target device
- flat cable
- 02 USB MINIB connector
- OB DATA transfer indication LED
- 04 ACTIVE indication LED
- 05 LINK indication LED
- 06 POWER indication LED



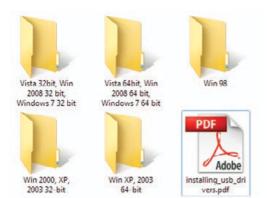
1. Driver installation

mikroProgTM requires drivers in order to work. Drivers are located on the link bellow:



http://www.mikroe.com/downloads/get/1202/mikroprog_for_pic_drivers_v200.zip

When you locate the drivers, please extract files from the ZIP archive. Folder with extracted files contains folders with drivers for different operating systems. Depending on which operating system you use, choose adequate folder and open it.



In the opened folder you should be able to locate the driver setup file. Double click on setup file to begin installation of the programmer drivers.

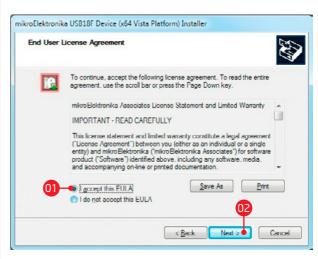


step 1 - Start installation



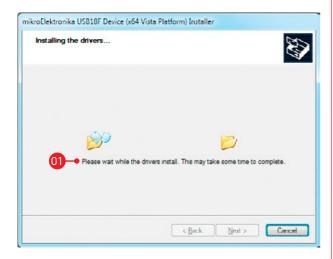
01 In welcome screen click on Next> button

step 2 - Accept EULA



- In order to proceed select: I accept the this EULA (End User License Agreement)
- O2 Click Next> button

step 3 - Installing the drivers



01 Drivers are installed automatically

step 4 - Finish installation



01 Click on **Finish** button to end installation process

2. Connecting to a PC

After driver installation is complete, you can now connect the programmer with your PC using USB cable provided with the package. Green **POWER LED** should turn ON, indicating the presence of power supply. Amber-colored **LINK LED** will turn ON when link between mikroProg[®] and PC is established. Link can be established only when correct drivers are installed on your PC.

3. mikroProg Suite[™] for PIC[®] software

mikroProg SuiteTM for PIC® software is intended for programming PIC®, dsPIC®, PIC24® and PIC32® microcontrollers from Microchip®. The graphic interface of this program is clear and easy-to-use, which makes the use of this program faster. The program's main window includes basic options for programming microcontrollers. In addition, there are advanced programming options that enable experienced users to set configuration bits on their own. The program includes views providing basic information about the selected MCU, voltage monitoring, etc.



4. Powering target device via mikroProg™

One of the key benefits of mikroProgTM is that is can power your target device. You can set power supply voltage in range from **2.7V** to **5V** with output current up to **250mA**. This option is activated from **mikroProg SuiteTM for PIC®** (v2.29) software. Click the MCU Info button to display **Voltage Options** section. First you must select MCU family and choose your target MCU from a dropdown list. mikroProgTM will automatically set the default value of power supply for your MCU. You can also manually set voltage supply value by moving slider under mikroProg SuiteTM for PIC® window, **Figure 4-1**.

To enable power supply, first set desired voltage and then click on check box "Power board from programmer".

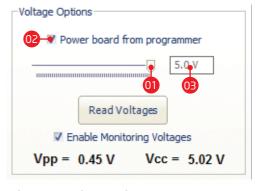


Figure 4-1: Voltage options

- Of Setting supply voltage value from 2.7 to 5V (max 250mA)
- O2 Check box for enabling supply voltage from programmer
- OB Box with selected supply voltage

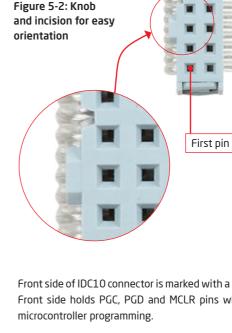
5. Connecting with

a target device

For connection with a target device mikroProg[™] uses female IDC10 connector, **Figure 5-1**. In order to make proper connection with the target board it is necessary to pay attention to IDC10 connector pinout. Every pin has a different purpose and for easy orientation IDC10 connector is marked with a little knob and incision, Figure 5-2.

Figure 5-1: IDC10

connector



Front side of IDC10 connector is marked with a knob and incision. Front side holds PGC, PGD and MCLR pins which are used for

6. IDC10 Pinout

- 01 MCU-VCC MCU power supply
- MCU-PGC Serial programming clock
- 05 MCU-PGD Serial programming data
- 07 MCU-MCLR Master clear/Programming voltage
- 09 GND Ground
- O2 VCC
- 04 PGC
- 06 PGD
- 08 MCLR
- 10 GND

These pins are multiplexed (see section 8.0 for more information)

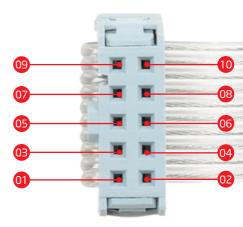


Figure 6-1: IDC10 pinout

7. Connection examples

For connecting mikroProgTM with your target device a best solution is to provide 1x5 or 2x5 male headers which are connected with programing pins on microcontroller. You can see several examples of connection schematics in the **Section 10** of this manual.

Using 1x5 male headers

When connecting mikroProgTM with your device via 1x5 header make sure to use front side of IDC10 connector (side with a knob and incision), **Figure 7-2**. 1x5 programming headers are found in some of Mikroelektronika products, like mikromedia boards, **Figure 7-2**.

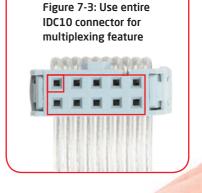
Figure 7-2:
Connecting
mikroProg[™] to
mikromedia board
via 1x5 male header

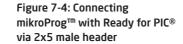
Figure 7-1: Use only front row for programming



Using 2x5 male headers

By using 2x5 male connector in your device you can exploit the multiplexing feature of mikroProgTM for PIC®, dsPIC® and PIC32®. We'll explain how multiplexer operates and what are it's key benefits in **Section 8** of this manual.



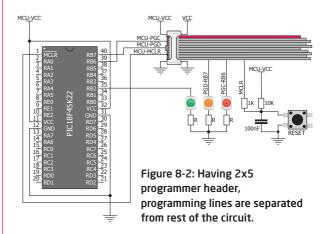


8. Multiplexer

Multiplexer is specially designed circuit which serves as a switch. Purpose of multiplexer is that there's no need for disconnecting mikroProg[™] programmer from a device when programming is finished. Multiplexing is always available, but can only be used with 2x5 male header on target board as shown on **Figure** 8-1. Multiplexer allows the usage of programming pins (PGC and PGD) as I/O lines when not in programming/debugging mode. Master clear reset (MCLR) pin is also multiplexed and can be used for resetting target MCU when not in programming/ debugging mode.

Figure 8-1: mikroProg™ 2x5 male header next to reset button

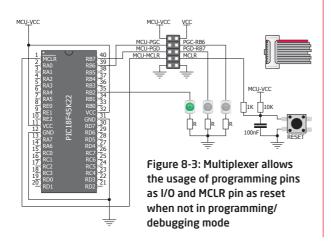
Programming pins or I/Os?

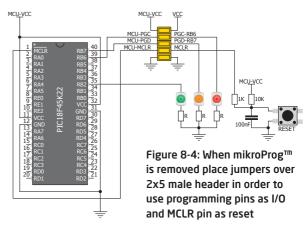


While pins on MCU are separated from rest of the circuit, they can not be used as I/O or reset pins as shown on **Figure 8-2**. There are two ways to connect programming pins: 1. with mikroProgTM 2x5 female connector 2. by placing jumpers over 2x5 male header.

Multiplexer decides pin function

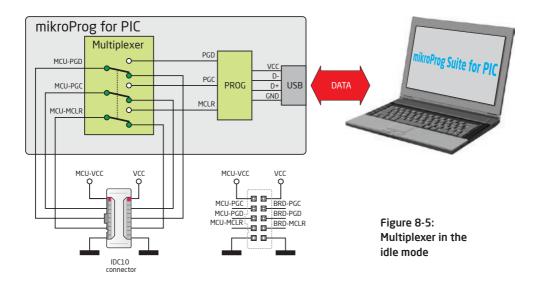
Programming pins just as I/Os





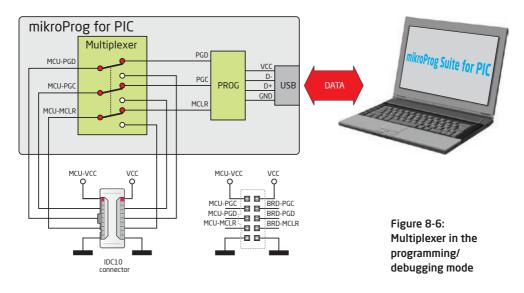
Programming/debugging is enabled when mikroProgTM is connected to the device. As shown on **Figure 8-3**, when programming/debugging is finished, multiplexer reconnects programming/debugging pins so they can be used as I/Os. There's no need to remove mikroProgTM connector. When mikroProgTM is removed, place jumpers over 2x5 male header in order to use programming/debugging pins as I/O, and MCLR pin as reset (**Figure 8-4**). In programming/debugging mode MCLR pin is used by mikroProgTM, otherwise it is used by MCU.

Multiplexer in idle mode



When programming/debugging is not in progress, the multiplexer releases the programming pins and MCLR, thus enabling them to be used as I/O pins or reset. This also enables the programmer to be connected to the target device without affecting its operation.

Multiplexer in programming/debugging mode



During programming/debugging, the multiplexer disconnects the microcontroller pins used for programming/debugging from the target device. This enables the programming/debugging process to be safely performed without affecting the operation of the device itself. It also prevents external signals from affecting the programming/debugging process. When the programming/debugging process has been completed, the multiplexer releases the microcontroller pins used for programming, so that they can be used as I/O pins or reset respectively.

10. Examples of connection schematics

Following examples demonstrate connections with some of the most popular supported MCUs. For all other MCUs consult manufacturer's datasheet. All PIC®, dsPIC® and PIC32® MCUs use PGC, PGD and MCLR/Vpp pins for programming. Some MCUs have several groups of programming pins. For example dsPIC33FJ128GP710A has three pairs of programmable pins PGED1-PGEC1, PGED2-PGEC2 or PGED3-PGEC3 (MCLR/Vpp pin is same for all pin groups). Whichever group of programming pins you decide to use, make sure to connect each pin properly.

PGC - Serial programming clock

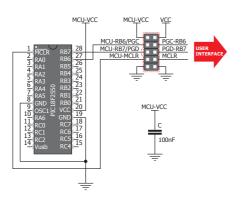
PGD - Serial programming data

MCLR/Vpp - Master clear/Programming voltage

Note: In order for microcontroller to work properly, decoupling capacitors must be connected as close as possible to microcontroller's VCC pins.

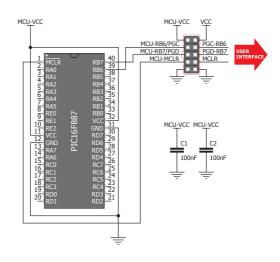
PIC DIP28

Figure 10-1: Connecting 2x5 male header with PIC18F2550 in 28-pin DIP package



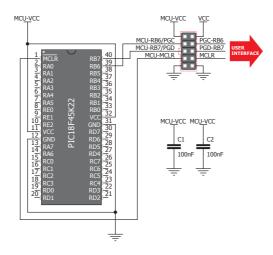
PIC DIP40

Figure 10-2: Connecting 2x5 male header with PIC16F887 in 40-pin DIP package



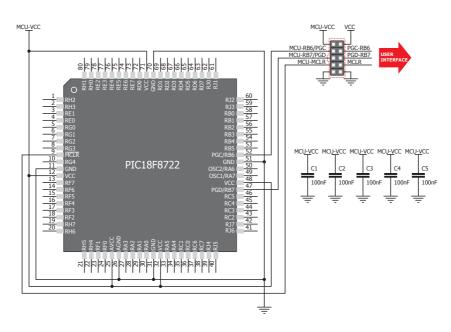
PIC18FK DIP40

Figure 10-3: Connecting 2x5 male header with PIC18F45K22 in 40-pin DIP package



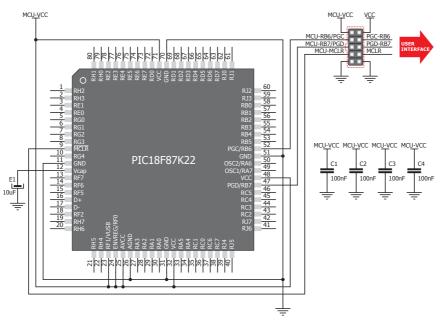
PIC18F TQFP80

Figure 10-4: Connecting 2x5 male header with PIC18F8722 in 80-pin TQFP package



PIC18FK TQFP80

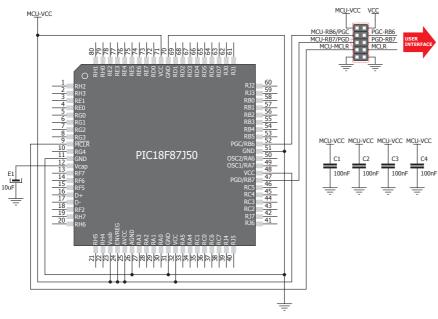
Figure 10-5: Connecting 2x5 male header with PIC18F87K22 in 80-pin TQFP package



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PIC18FJ TQFP80

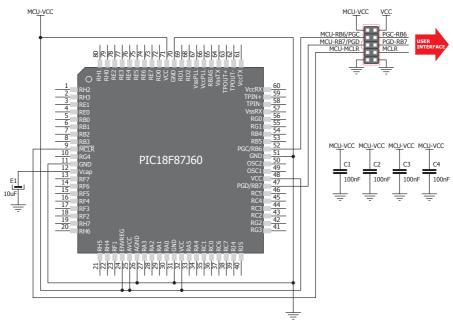
Figure 10-6: Connecting 2x5 male header with PIC18F87J50 in 80-pin TQFP package



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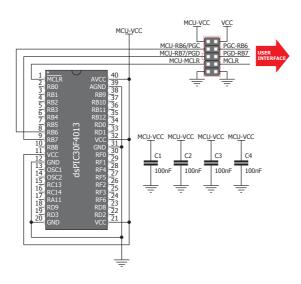
PIC18FJ TQFP80

Figure 10-7: Connecting 2x5 male header with PIC18F87J60 in 80-pin TQFP package



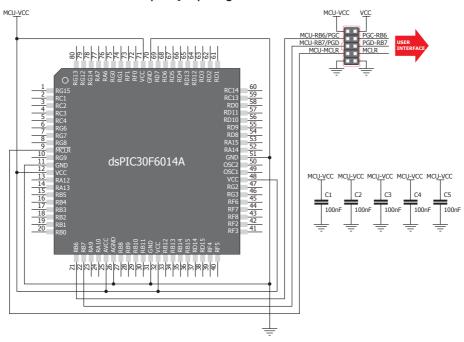
dsPIC30 DIP40

Figure 10-8: Connecting 2x5 male header with dsPIC30F4013 in 40-pin DIP package

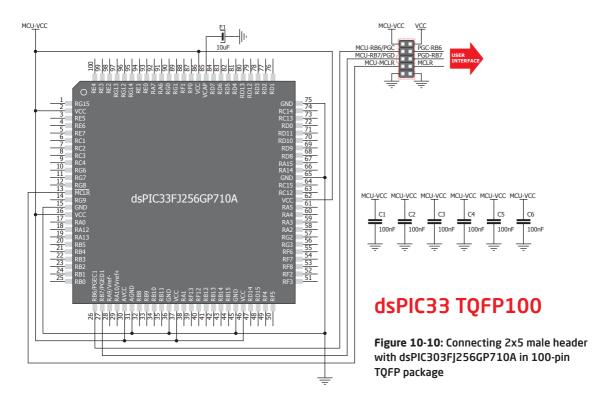


dsPIC30 TQFP80

Figure 10-9: Connecting 2x5 male header with dsPIC30F6014A in 80-pin TQFP package

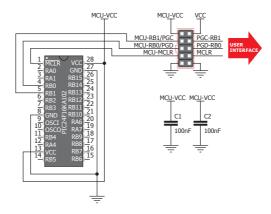


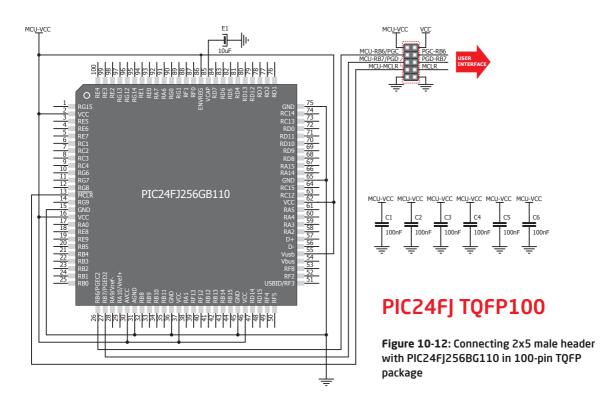
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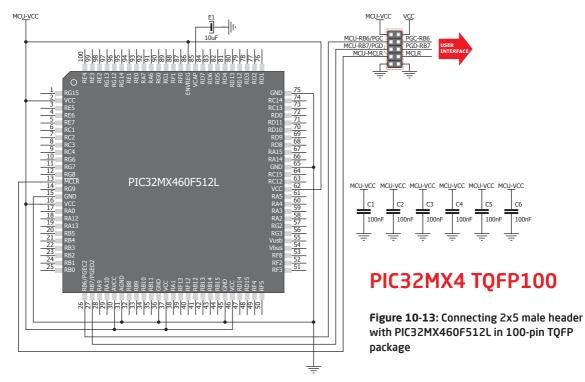
PIC24FK TQFP80

Figure 10-11: Connecting 2x5 male header with PIC24F16KA102 in 28-pin DIP package

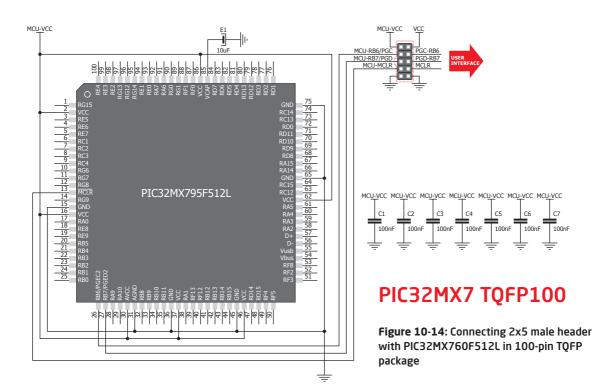




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Notes:	
MOTOC	
MOTE2.	

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