

LYPR540AH

MEMS motion sensor: 3 axis analog output gyroscope

Preliminary data

Features

- Analog supply voltage 2.7 V to 3.6 V
- Wide extended operating temperature range (-40°C to 85°C)
- 3 indipendent angular rate channels
- ±400 dps and ±1600 dps full-scale
- High shock survivability
- Embedded self-test
- ECOPACK[®] RoHS and "Green" compliant (see *Section 5*)

Application

- Motion and man machine interface
- Gaming and virtual reality input devices
- Fitness and wellness
- Pointing device and remote controllers
- Industrial and robotics
- Personal navigation devices

Description

The LYPR5.40.4 is a three axis yaw, pitch and roll analog gwoscope featuring three separate analog out put channels.

LYPR540AH provides amplified (±400 dps full scale) and not amplified (±1600 dps full scale) outputs for each sensible axis available at the same time through dedicated pins, and is capable of detecting rates with a -3 dB bandwidth up to 140 Hz.



ST 3 axis gyroscope family leverages on robust and mature manufacturing process already used for the production of hundreds million micromachined accelerometers with excellent acceptance from the market.

Sensing element is manufactured using specialized micromachining processes, while the IC interfaces are realized using a CMOS technology that allows to design a dedicated circuit which is trimmed to better match the sensing element characteristics.

The LYPR540AH is available in plastic Land Grid Array (LGA) package. Several years ago ST pioneered successfully the usage of this package for accelerometers. Today ST has the widest manufacturing capability and strongest expertise in the world for production of sensors in plastic LGA package.

Table 1. Device summary

Order code	Temperature range [°C]	Package	Packing
LYPR540AH	-40 to +85	LGA-28L	Tray
LYPR540AHTR	-40 to +85	LGA-28L	Tape and reel

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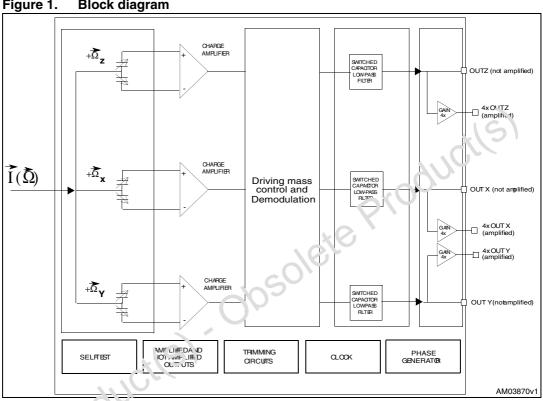
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Block diagram and pin description 1

1.1 **Block diagram**

Figure 1. **Block diagram**



Pin description

Figure 2. Pin connection

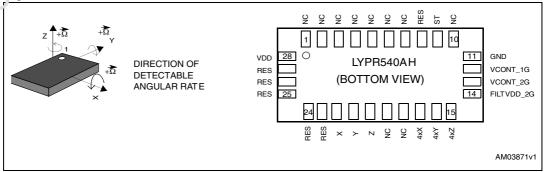


Table 2. Pin description

Pin#	Name	Function
1-7	NC	Internally not connected
8	Reserved	Connect to GND
9	ST	Self tets (logic 0: normal mode; logic 1: self test)
10	NC	Internally not connected
11	GND	0V supply voltage
12	VCONT_1G	PLL filter connection
13	VCONT_2G	PLL filter connection
14	FILTVDD_2G	PLL filter connection
15	4xZ	Z amplified output
16	4xY	Y amplified output
17	4xX	X amplified output
18	NC	Internally not connected
19	NC	Internally not connected
20	Z	Z not amplified output
21	Υ	Y not amplified ייבליבי
22	X	X not a nplifed output
23	Reserved	Connect to GND
24-27	Reserved	Connect to VDD
28	COV	Power supply
etePro	gine	

2 Module specifications

2.1 Mechanical characteristics

Vdd = 3V, T = 25 °C unless otherwise noted^(a)

Table 3. Mechanical characteristics

Symbol	Parameter	Test conditions	Min.	Typ. ⁽¹⁾	Max.	Unit
FS		Not amplified output (X,Y,Z)		±1600		
FSA	Measurement range	Amplified output (4xX,4xY,4xZ)		±400		dps
So		Not amplified output (X,Y,Z)		0.8		
SoA	Sensitivity	Amplified output (4xX,4xY,4xZ)		3.2	700	mV/dps
SoDr	Sensitivity change vs. temperature			7.07		%/°C
Voff	Zero-rate level		x0	1.5		V
VoffDR	Zero rate level drift over temperature	0/9		0.08		dps/°C
NL	Non linearity ⁽²⁾	Best fit straight i're		±1		% FS
BW	Bandwidth ⁽³⁾	0		140		Hz
Rn	Rate noise density			0.02		dps/√Hz
Тор	Operating temperature range	(5)	-40		+85	°C

^{1.} Typical specifications are not guaranteed.

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^{2.} Guaranteed by design.

^{3.} The product is capable of reacting angular rates extending from DC to the selected BW.

a. The product is factory calibrated at 3 V. The operational power supply range is from 2.7 V to 3.6 V.

2.2 **Electrical characteristics**

Vdd = 3 V, T = 25 °C unless otherwise noted

Electrical characteristics Table 4.

Symbol	Parameter	Test conditions	Min.	Typ. ⁽¹⁾	Max.	Un
Vdd	Supply voltage		2.7	3	3.6	V
ldd	Supply current			10.8		m/
Мот	Calf tast input	Logic 0 level	0		0.2*Vdd	V
VsT	Self-test input	Logic 1 level	0.8*Vdd		Vdd]
Тор	Operating temperature range		-40		+85	°C
				DIO).	
	Operating temperature range ecifications are not guaranteed.	9) Obs	olete	Proc		

2.3 Absolute maximum ratings

Stresses above those listed as "absolute maximum ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device under these conditions is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

Table 5. Absolute maximum ratings

Symbol	Ratings	Maximum value	Unit
Vdd	Supply voltage	-0.3 to 6	V
Vin	Input voltage on any control pin (ST)	-0.3 to Vdd +0.3	V
Α	Acceleration	3000 for 0.5 ms	g
	Acceleration	10000 for 0.1 n.s	g
T _{STG}	Storage temperature range	-40 'o +1?J	°C
ESD	Electrostatic discharge protection	2 (\\BM)TBC	kV



This is a mechanical shock sensitive device, imprope: handling can cause permanent damages to the part



Josoleite Produci(S)

This is an ESD sensitive device, improper handling can cause permanent damages to the part

Terminology LYPR540AH

3 Terminology

3.1 Sensitivity

An angular rate gyroscope is a device that produces a positive-going output voltage for counterclockwise rotation around the sensitive axis considered. Sensitivity describes the gain of the sensor and can be determined by applying a defined angular velocity to it. This value changes very little over temperature and time.

3.2 Zero-rate level

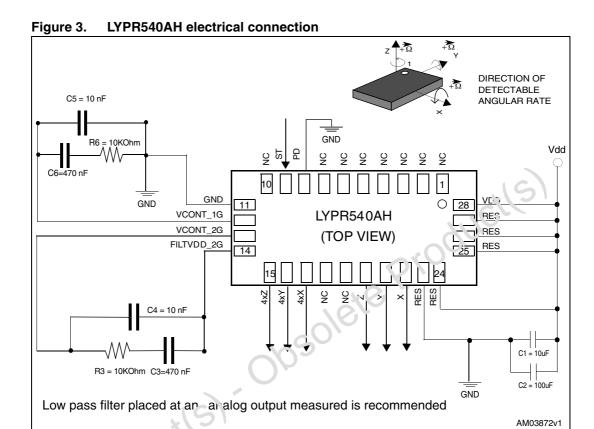
Zero-rate level describes the actual output signal if there is no angular rate present. The zero-rate level of precise MEMS sensors is, to some extent, a result of stress to the sensor and therefore zero-rate level can slightly change after mounting the sensor onto a printed circuit board or after exposing it to extensive mechanical stress. This value changes very little over temperature and time.

3.3 Self-test

Self-test allows testing the mechanical and electrical part of the sensor, allowing the seismic mass to be moved by means of an electrostatic test-force. The Self-test function is off when the ST pin is connected to GND. When the ST pin is tied to Vdd, an actuation force is applied to the sensor, emulating a definite Coriolis force. In this case the sensor output will exhibit a voltage change in its DC level which is also depending on the supply voltage. When ST is active, the device output letel is given by the algebraic sum of the signals produced by the angular velocity acting on the sensor and by the electrostatic test-force. If the output signals change within the amplitude specified then the mechanical element is working properly and the parameters of the interface chip are within the defined specification.

LYPR540AH Application hints

4 Application hints



4.1 External capacitors

The derice core is supplied through Vdd line. Power supply decoupling capacitors (C2=100 $^{\circ}$ F ceramic, C1=10 $^{\circ}$ F Al) should be placed as near as possible to the supply pin of the device (common design practice).

All the voltage and ground supplies must be present at the same time to have proper behavior of the IC (refer to *Figure 3*).

The LYPR540AH IC includes a PLL (phase-locked loop) circuit to synchronize driving and sensing interfaces. Capacitors and resistors must be added at the **FILTVDD_2G**, **VCONT_2G**, **VCONT_1G** pins (as shown in *Figure 3*) to implement a second-order low-pass filter.

4.2 Soldering information

The LGA package is compliant with the ECOPACK[®], RoHS and "Green" standard. It is qualified for soldering heat resistance according to JEDEC J-STD-020C.

Leave "pin 1 Indicator" unconnected during soldering.

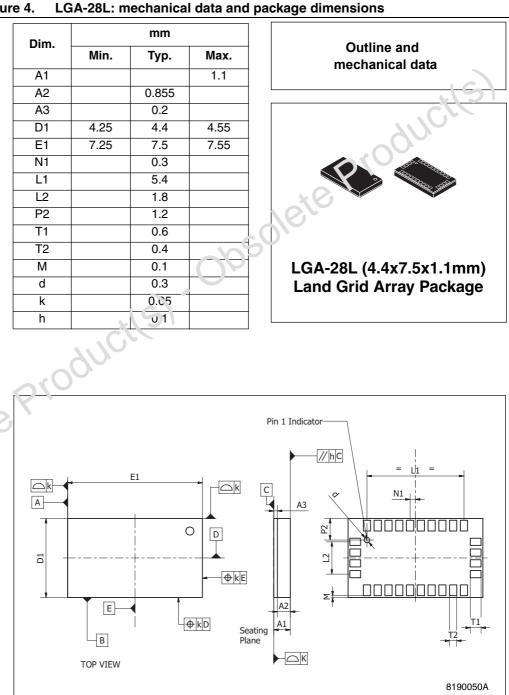
Land pattern and soldering recommendation are available at www.st.com/

Package information LYPR540AH

5 **Package information**

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: www.st.com. ECOPACK is an ST trademark

Figure 4.



LYPR540AH Revision history

6 Revision history

Table 6. Document revision history

Date	Revision	Changes
06-Nov-2009	1	Initial release.



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