DATA SHEET

Part No.	AN44075A
Package Code No.	HSOP034-P-0300A

Contents

	3
■ Features	3
Applications	3
■ Package	3
■ Туре	3
■ Application Circuit Example (Block Diagram)	4
■ Pin Descriptions	5
■ Absolute Maximum Ratings	6
■ Operating Supply Voltage Range	6
Electrical Characteristics	7
■ Electrical Characteristics (Reference values for design)	9
■ Technical Data	10
Control mode (truth table)	10

AN44075A Driver IC for DC motor

Overview

AN44075A is a one channel H-bridge driver IC. 1-ch. DC motor can be controlled by a single driver IC.

Features

- Built-in thermal protection and low voltage detection circuit
- Built-in over current protection (when external resistance is added to pin 7 and pin 8.)
- Built-in 5 V power supply

Applications

• IC for DC motor drives

Package

• 34 pin plastic small outline package with back heat sink (SOP type)

■ Type

• Bi-CDMOS IC



■ Application Circuit Example (Block Diagram)

Note) This application circuit is shown as an example but does not guarantee the design for mass production set.

Pin No.	Pin name	Туре	Description	
1	VM2	Power supply	Motor power supply 2	
2	N.C.		not used	
3	AOUT2	Output	Motor drive output 2	
4	N.C.		not used	
5	N.C.		not used	
6	N.C.		not used	
7	RCSA1	Input / Output	Current detection 1	
8	RCSA2	Input / Output	Current detection 2	
9	GND	Ground	Die pad ground	
10	N.C.		not used	
11	N.C.		not used	
12	N.C.		not used	
13	N.C.		not used	
14	AOUT1	Output	Motor drive output 1	
15	N.C.		not used	
16	VM1	Power supply	Motor power supply 1	
17	VPUMP	Output	Charge pump circuit output	
18	BC2	Output	Charge pump capacitor connection 2	
19	BC1	Output	Charge pump capacitor connection 1	
20	N.C.		not used	
21	N.C.		not used	
22	VREFA	Input	Peak current setting input	
23	VREFB	Input	Load short threshold input	
24	S5VOUT	Output	Internal reference voltage (5 V output)	
25	GND	Ground	Signal ground	
26	GND	Ground	Die pad ground	
27	SEL	Input	Test mode input	
28	STBY	Input	Standby input	
29	APWM	Input	PWM input	
30	AIN1	Input	Forward-reverse input	
31	AIN2	Input	Brake mode input	
32	NFAULT	Output	Abnormal detection output	
33	N.C.		not used	
34	TJMON	Output	VBE monitor	

A No.	Parameter	Symbol	Rating	Unit	Note
1	Supply voltage (pin 1, pin 16)	V _M	37	V	*1
5	Output pin voltage (pin 3, pin 14)	V _{OUT}	37	V	*2
6	Motor drive current (pin 3, pin 14)	I _{OUT}	±3.0	А	*2, *3
7	Flywheel diode current (pin 3, pin 14)	If	3.0	А	*2, *3
2	Power dissipation	P _D	0.466	W	*4
3	Operating ambient temperature	T _{opr}	-20 to +70	°C	*5
4	Storage temperature	T _{stg}	-55 to +150	°C	*5

Note) *1: The range under absolute maximum ratings, power dissipation.

*2: Do not apply external currents to any pin specially mentioned. For circuit currents, (+) denotes current flowing into the IC and (-) denotes current flowing out of the IC.

*3: Rating when cooling fin on the back side of the IC is connected to the GND pattern of the glass epoxy 4-layer board. (GND area: 2nd-layer or 3rd-layer: more than 1 500 mm²)

In case of no cooling fin on the back side of the IC, rating current is 1.5 A on the glass epoxy 2-layer board.

*4: Power dissipation shows the value of only package at $T_a = 70^{\circ}C$.

When using this IC, refer to the $\bullet P_D - T_a$ diagram in the \blacksquare Technical Data and use under the condition not exceeding the allowable value. *5: Expect for the storage temperature and operating ambient temperature, all ratings are for $T_a = 25^{\circ}$ C.

Operating Supply Voltage Range

Parameter	Symbol	Range	Unit	Note
Supply voltage range	V_{M}	10.0 to 35.0	V	

Note) The values under the condition not exceeding the above absolute maximum ratings and the power dissipation.

Electrical Characteristics at V_{CC} = 24 V Note) $T_a = 25^{\circ}C \pm 2^{\circ}C$ unless otherwise specified.

В	Devenueter	O wash at	Oraditions		Limits			No
No.	Parameter	Symbol	Conditions		Тур	Max	Unit	te
Outp	ut drivers	_				_		
1	High-level output saturation voltage	V _{OH}	$I_{SA1} = I_{SA2} = -1 A$	$\begin{vmatrix} V_M \\ -0.47 \end{vmatrix}$	V _M - 0.36		V	_
2	Low-level output saturation voltage	V _{OL}	$I_{SA1} = I_{SA2} = 1 A$	_	0.50	0.65	V	_
3	Flywheel diode forward voltage	V _{DI}	$I_{DI} = \pm 1 A$	0.5	1.0	1.5	V	
4	Output leakage current	I _{LEAK}	$V_{\rm M} = 37 \text{ V}, V_{\rm SRCS} = 0 \text{ V}$	_	10	20	μΑ	_
Pow	er supply							
5	Supply current 1 (sleep)	I _{M1}	$V_{\text{STBY}} = 0 \text{ V}$	_	65	105	μΑ	
6	Supply current 2 (with circuit turned on)	I _{M2}	$V_{STBY} = 5 V$	_	7.3	12	mA	_
7	Reference voltage	V _{S5VOUT}	$I_{S5VOUT} = -2.5 \text{ mA}$	4.5	5.0	5.5	V	_
8	Output impedance	Z _{S5VOUT}	$\Delta I_{S5VOUT} = -5 \text{ mA}$	_	18	27	Ω	_
IN in	IN input							
9	High-level IN input voltage	V _{INH}	_	2.1		5	V	_
10	Low-level IN input voltage	V _{INL}	_	0		0.6	V	-
11	High-level IN input current	I _{INH}	$V_{AIN1} = V_{AIN2} = 5 V$	- 10		10	μΑ	_
12	Low-level IN input current	I _{INL}	$V_{AIN1} = V_{AIN2} = 0 V$	-10		10	μΑ	_
Stan	dby input							
13	High-level STBY input voltage	V _{STBYH}	_	2.1		5	V	-
14	Low-level STBY input voltage	V _{STBYL}	_	0		0.6	V	_
15	High-level STBY input current	I _{STBYH}	$V_{\text{STBY}} = 5 \text{ V}$	30		80	μΑ	_
16	Low-level STBY input current	I _{STBYL}	$V_{STBY} = 0 V$	-10		10	μΑ	_
PWN	PWM input							
17	High-level PWM input voltage	V _{PWMH}	_	2.1		5	V	-
18	Low-level PWM input voltage	V _{PWML}	_	0		0.6	V	_
19	High-level PWM input current	I _{PWMH}	$V_{APWM} = 5 V$	60		150	μΑ	_
20	Low-level PWM input current	I _{PWML}	$V_{APWM} = 0 V$	-10		10	μΑ	_
21	PWM input max. frequency	f _{PWM}	_	_		200	kHz	_
22	Input min. pulse width	t _w		2			μs	

Electrical Characteristics at V_{CC} = 24 V (continued) Note) $T_a = 25^{\circ}C\pm 2^{\circ}C$ unless otherwise specified.

В	Doromotor	Symbol		Limits			Lipit	No
No.	Parameter	Symbol	Conditions	Min	Тур	Max	Unit	te
Peak current detection / over current protection								
23	Input bias current	I _{REF}	$V_{REFA} = V_{REFB} = 5 V$	83	100	125	μΑ	_
24	PWM frequency	f _{PWM}	$V_{\text{REFA}} = 0 \text{ V}, V_{\text{REFB}} = 5 \text{ V}$	17	26	35	kHz	-
25	Pulse blanking time	T _B	$V_{\text{REFA}} = 0 \text{ V}, V_{\text{REFB}} = 5 \text{ V}$	1.5	2.5	4.5	μs	-
26	Comp threshold 1	VT _{H1}	$V_{\text{REFA}} = V_{\text{REFB}} = 5 \text{ V}$	480	500	520	mV	-
27	Comp threshold 2	VT _{H2}	$V_{REFA} = 5.5 V, V_{REFB} = 2.5 V$	475	500	525	mV	_
28	NFAULT output voltage	V _{NFLT}	$I_{\rm NFLT} = 1 {\rm mA}$	_		0.4	V	

Electrical Characteristics (Reference values for design) at V_{CC} = 9 V

Note) $T_a = 25^{\circ}C \pm 2^{\circ}C$ unless otherwise specified. The characteristics listed below are reference values for design of the IC and are not guaranteed by inspection. If a problem does occur related to these characteristics, Panasonic will respond in good faith to user concerns.

В	B Decomptor		Conditions	Limits			L lucit	No
No.	Parameter	Symbol Conditions		Min	Тур	Max	Unit	te
Output drivers								
29	Output slew rate 1	VTr	Rising edge		270		V/µs	
30	Output slew rate 2	VT_{f}	Falling edge		330		V/µs	—
31	Dead time	T _D	T _D —		0.45		μs	
Ther	mal protection							
32	Thermal protection operating temperature	TSD _{on}			150	_	°C	
33	Thermal protection hysteresis width	ΔTSD			40	—	°C	—
Low	Low voltage protection							
34	Protection operating voltage	UVLO1			8.0		V	
35	Protection release voltage	UVLO2	_		8.6		V	

Technical Data

• Control mode (truth table)

	INF	TUY		OUTPUT		
STBY	AIN1	AIN2	APWM	AOUT1	AOUT2	Mode
		"H"	"L"	"H"	"H"	Short brake
"H" "L"	"L"	_	"H"	"L"	"H"	Forward
	"H"		"H"	"H"	"L"	Reverse
		"L"	"L"	OFF	OFF	Stop
"L"		—		OFF	OFF	Standby

INPUT	OUTPUT		
SEL	Mode		
" H"	Short detect off		
"L"	Short detect on		

Request for your special attention and precautions in using the technical information and semiconductors described in this book

- (1) If any of the products or technical information described in this book is to be exported or provided to non-residents, the laws and regulations of the exporting country, especially, those with regard to security export control, must be observed.
- (2) The technical information described in this book is intended only to show the main characteristics and application circuit examples of the products. No license is granted in and to any intellectual property right or other right owned by Panasonic Corporation or any other company. Therefore, no responsibility is assumed by our company as to the infringement upon any such right owned by any other company which may arise as a result of the use of technical information described in this book.
- (3) The products described in this book are intended to be used for standard applications or general electronic equipment (such as office equipment, communications equipment, measuring instruments and household appliances).
 - Consult our sales staff in advance for information on the following applications:
 - Special applications (such as for airplanes, aerospace, automobiles, traffic control equipment, combustion equipment, life support systems and safety devices) in which exceptional quality and reliability are required, or if the failure or malfunction of the products may directly jeopardize life or harm the human body.
 - Any applications other than the standard applications intended.
- (4) The products and product specifications described in this book are subject to change without notice for modification and/or improvement. At the final stage of your design, purchasing, or use of the products, therefore, ask for the most up-to-date Product Standards in advance to make sure that the latest specifications satisfy your requirements.
- (5) When designing your equipment, comply with the range of absolute maximum rating and the guaranteed operating conditions (operating power supply voltage and operating environment etc.). Especially, please be careful not to exceed the range of absolute maximum rating on the transient state, such as power-on, power-off and mode-switching. Otherwise, we will not be liable for any defect which may arise later in your equipment.

Even when the products are used within the guaranteed values, take into the consideration of incidence of break down and failure mode, possible to occur to semiconductor products. Measures on the systems such as redundant design, arresting the spread of fire or preventing glitch are recommended in order to prevent physical injury, fire, social damages, for example, by using the products.

- (6) Comply with the instructions for use in order to prevent breakdown and characteristics change due to external factors (ESD, EOS, thermal stress and mechanical stress) at the time of handling, mounting or at customer's process. When using products for which damp-proof packing is required, satisfy the conditions, such as shelf life and the elapsed time since first opening the packages.
- (7) This book may be not reprinted or reproduced whether wholly or partially, without the prior written permission of our company.

20080805

AMEYA360 Components Supply Platform

Authorized Distribution Brand :



Website :

Welcome to visit www.ameya360.com

Contact Us :

► Address :

401 Building No.5, JiuGe Business Center, Lane 2301, Yishan Rd Minhang District, Shanghai , China

≻ Sales :

- Direct +86 (21) 6401-6692
- Email amall@ameya360.com
- QQ 800077892
- Skype ameyasales1 ameyasales2

Customer Service :

Email service@ameya360.com

> Partnership :

Tel +86 (21) 64016692-8333

Email mkt@ameya360.com