

# SANYO Semiconductors DATA SHEET

An ON Semiconductor Company

LV8549M -

# Bi-CMOS integrated circuit 12V Low Saturation Voltage Drive

# Stepping Motor Driver

#### Overview

The LV8549M is a stepping motor driver IC of low saturation voltage. It is optimal for motor drive in 12V system product a 2-phase bipolar stepping motor.

#### **Functions**

- DMOS output transistor adoption (Upper and lower total RON= $1\Omega$  typ)
- The compact package (MFP-10S) is adopted.
- VCC max=20v, IO max=1A
- For one power supply (The control system power supply is unnecessary.)
- Current consumption 0 when standing by

## **Specifications**

#### **Absolute Maximum Ratings** at Ta = 25°C

Parameter Symbol		Conditions Ratings		Unit
Maximum power supply voltage	V <sub>CC</sub> max		-0.3 to +20	V
Output impression voltage	VOUT		-0.3 to +20	V
Input impression voltage	V <sub>IN</sub>		-0.3 to +6	V
GND pin outflow current	IGND	For ch	1.0	Α
Allowable Power dissipation	Pd max	*	1.05	W
Operating temperature	Topr		-30 to +85	°C
Storage temperature	Tstg		-40 to +150	°C

<sup>\*:</sup> When mounted on the specified printed circuit board (57.0mm ×57.0mm × 1.6mm), glass epoxy, both sides

#### **Recommended Operating Range** at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Power supply voltage	V <sub>CC</sub>		4.0 to 16	V
Input "H" level voltage	V <sub>IN</sub> H		+1.8 to +5.5	V
Input "L" level voltage	V <sub>IN</sub> L		-0.3 to +0.7	V

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Caution 1) Absolute maximum ratings represent the value which cannot be exceeded for any length of time.

Caution 2) Even when the device is used within the range of absolute maximum ratings, as a result of continuous usage under high temperature, high current, high voltage, or drastic temperature change, the reliability of the IC may be degraded. Please contact us for the further details.

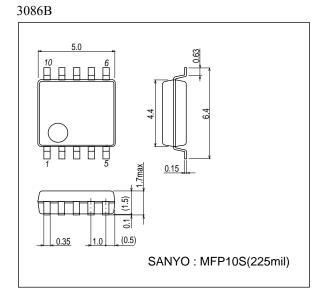
## LV8549M

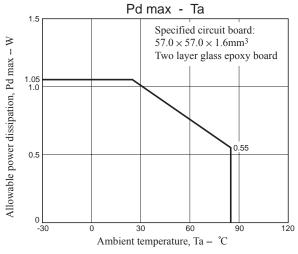
# **Electrical Characteristics** at Ta = 25°C, $V_{CC} = 12V$

D	O. made at	Conditions	Ratings			1.1	
Parameter	Symbol	Conditions	min	typ	max	Unit	
Power supply voltage	I <sub>CC</sub> 0	Standby mode ENA=L			1	μΑ	
	I <sub>CC</sub> 1	ENA=H		1.7	2.3	mA	
Input current	I <sub>IN</sub>	V <sub>IN</sub> =5V	30	50	65	μΑ	
Thermal shutdown operating Ttsd temperature		Design certification	150	180	210	°C	
Width of temperature hysteria	∆Ttsd	Design certification		40		°C	
Low voltage protection function operation voltage	VthV <sub>CC</sub>		3.3	3.5	3.65	V	
Release voltage	Vthret		3.55	3.8	3.95	V	
Output ON resistance RON (Upper and lower total)		I <sub>OUT</sub> =1.0A	0.7	1	1.25	Ω	
Output leak current	ak current I <sub>O</sub> leak V <sub>O</sub> =16V			·	10	μΑ	
Diode forward voltage	VD	ID=1.0A		1.0	1.2	V	

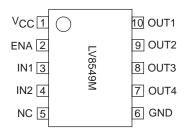
# **Package Dimensions**

unit: mm (typ)

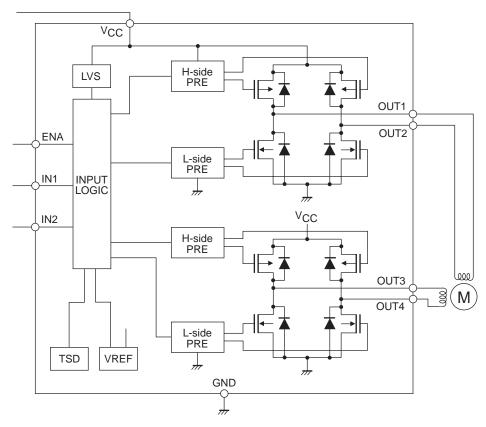




# **Pin Assignment**



# **Block Diagram**



# Pin function

Pin No.	Pin name	Pin function	Equivalent Circuit
1	Vcc	Power-supply voltage pin.  V <sub>CC</sub> voltage is impressed. The permissible operation voltage is from 4.0 to 16.0(V). The capacitor is connected for stabilization for GND pin (6pin).	
2	ENA	Motor drive control input pin. It shifts from the stand-by state to a prescribed output operation corresponding to the state of the input when the ENA pin becomes a standby mode by L, the circuit current can be adjusted to 0, and it makes it to H. It is a digital input, and the range of L level input is 0 to 0.7(V) and the range of H level input are 1.8 to 5.5(V). PWM can be input. Pull-down resistance $100(k\Omega)$ is built into in the terminal.	1kΩ 40kΩ 100kΩ
3	IN1	Motor drive control input pin.  Driving control input pin of OUT1 (10pin) and OUT2 (9pin). PWM can be input. With built-in pull-down resistance.	5VREG
4	IN2	Motor drive control input pin.  Driving control input pin of OUT3 (8pin) and OUT4 (7pin). PWM can be input. With built-in pull-down resistance.	1kΩ 40kΩ \$100kΩ
5	NC		
6	GND	Ground pin.	
7	OUT4	Driving output pin.  The motor coil is connected between terminal OUT3 (8pin).	Vcc
8	OUT3	Driving output pin. The motor coil is connected between terminal OUT4 (7pin).	OUT1 OUT2
9	OUT2	Driving output pin. The motor coil is connected between terminal OUT1 (10pin).	OUT1 (OUT3) OUT2 (OUT4)
10	OUT1	Driving output pin. The motor coil is connected between terminal OUT2 (9pin).	

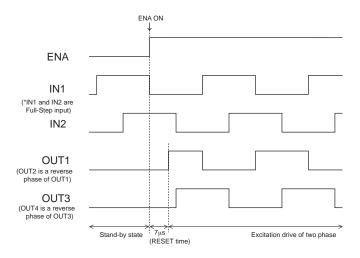
## **Operation explanation**

1. STM output control logic

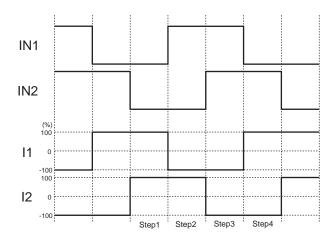
Input			Output				Ctoto	
ENA	IN1	IN2	OUT1	OUT2	OUT3	OUT4	State	
L	-	-	OFF	OFF	OFF	OFF	Stand-by	
Н	L	L	Н	┙	Η	L	Step 1	
	Н	L	L	Η	Η	L	Step2	
	Н	Н	L	Η	┙	Н	Step3	
	L	Н	Н	L	L	Н	Step4	

2. About the switch time from the stand-by state to the state of operation

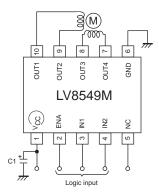
When ENA pin are "L", this IC has completely stopped operating. After the time of reset (about 7µs of an internal setting) it shifts to a prescribed output status corresponding to the state of the input when the signal enters the ENA pin.



3. Example of current wave type in each excitation mode when stepping motor parallel input is controlled.



# **Application Circuit Example**



- \* Bypass capacitor (C1) connected between  $V_{CC}$ -GND of all examples of applied circuit recommends the electric field capacitor of  $0.1\mu A$  to  $10\mu A$ .
- Confirm there is no problem in operation in the state of the motor load including the temperature property about the value of the capacitor.

Mount the position where the capacitor is mounted on nearest IC.

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