



PCF85063TP

Tiny Real-Time Clock/calendar

Rev. 3 — 11 July 2013

Product data sheet

1. General description

The PCF85063TP is a CMOS¹ Real-Time Clock (RTC) and calendar optimized for low power consumption. An offset register allows fine-tuning of the clock. All addresses and data are transferred serially via the two-line bidirectional I²C-bus. Maximum bus speed is 400 kbit/s. The register address is incremented automatically after each written or read data byte.

2. Features and benefits

- Provides year, month, day, weekday, hours, minutes, and seconds based on a 32.768 kHz quartz crystal
- Clock operating voltage: 0.9 V to 5.5 V
- Low current: typical 0.22 μ A at $V_{DD} = 3.3$ V and $T_{amb} = 25$ °C
- 400 kHz two-line I²C-bus interface (at $V_{DD} = 1.8$ V to 5.5 V)
- Programmable clock output for peripheral devices (32.768 kHz, 16.384 kHz, 8.192 kHz, 4.096 kHz, 2.048 kHz, 1.024 kHz, and 1 Hz)
- Selectable integrated oscillator load capacitors for $C_L = 7$ pF or $C_L = 12.5$ pF
- Minute and half minute interrupt
- Internal Power-On Reset (POR)
- Programmable offset register for frequency adjustment

3. Applications

- Digital still camera
- Digital video camera
- Printers
- Copy machines
- Mobile equipment
- Battery powered devices

1. The definition of the abbreviations and acronyms used in this data sheet can be found in [Section 20](#).



4. Ordering information

Table 1. Ordering information

| Type number | Package | | |
|-------------|---------|--|-----------|
| | Name | Description | Version |
| PCF85063TP | HWSON8 | plastic thermal enhanced very very thin small outline package; no leads; 8 terminals; body 2 × 3 × 0.75 mm | SOT1069-2 |

4.1 Ordering options

Table 2. Ordering options

| Product type number | IC revision | Sales item (12NC) | Delivery form |
|---------------------|-------------|-------------------|-----------------------|
| PCF85063TP/1 | 1 | 935297365147 | tape and reel, 7 inch |

5. Marking

Table 3. Marking codes

| Product type number | Marking code |
|---------------------|--------------|
| PCF85063TP/1 | 063 |

6. Block diagram

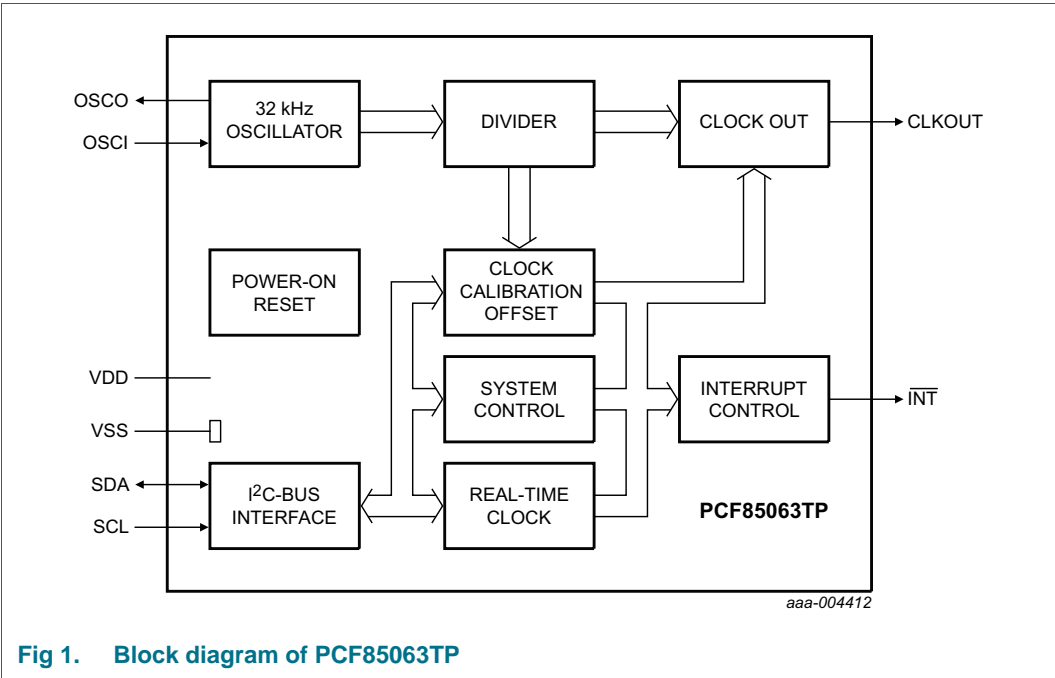
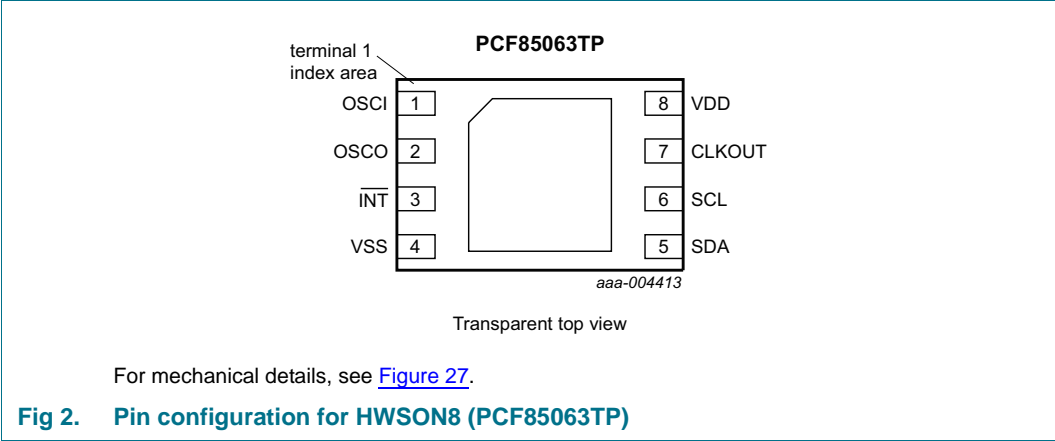


Fig 1. Block diagram of PCF85063TP

7. Pinning information

7.1 Pinning



7.2 Pin description

Table 4. Pin description

| Symbol | Pin | Type | Description |
|--------|------------------|--------------|-------------------------------|
| OSCI | 1 | input | oscillator input |
| OSCO | 2 | output | oscillator output |
| INT | 3 | output | interrupt output (open-drain) |
| VSS | 4 ^[1] | supply | ground supply voltage |
| SDA | 5 | input/output | serial data line |
| SCL | 6 | input | serial clock input |
| CLKOUT | 7 | output | clock output (push-pull) |
| VDD | 8 | supply | supply voltage |

[1] The die paddle (exposed pad) is connected to V_{SS} and should be electrically isolated.

8. Functional description

The PCF85063TP contains 11 8-bit registers with an auto-incrementing register address, an on-chip 32.768 kHz oscillator with integrated capacitors, a frequency divider which provides the source clock for the Real-Time Clock (RTC) and calendar, and an I²C-bus interface with a maximum data rate of 400 kbit/s.

The built-in address register will increment automatically after each read or write of a data byte up to the register 0Ah. After register 0Ah, the auto-incrementing will wrap around to address 00h (see [Figure 3](#)).

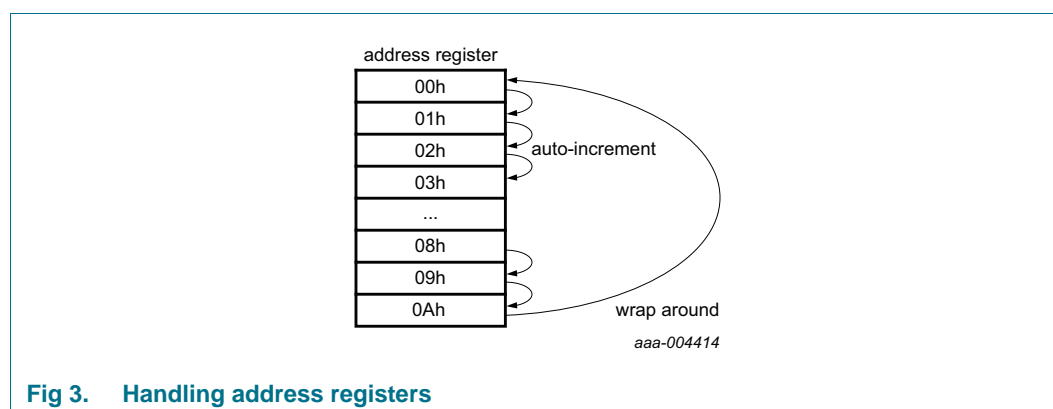


Fig 3. Handling address registers

All 11 registers (see [Table 5](#)) are designed as addressable 8-bit parallel registers although not all bits are implemented. The first two registers (memory address 00h and 01h) are used as control and status register. The register at address 02h is an offset register allowing the fine-tuning of the clock; and at 03h is a free RAM byte. The addresses 04h through 0Ah are used as counters for the clock function (seconds up to years counters).

The Seconds, Minutes, Hours, Days, Months, and Years registers are all coded in Binary Coded Decimal (BCD) format. When one of the RTC registers is written or read, the contents of all time counters are frozen. Therefore, faulty writing or reading of the clock and calendar during a carry condition is prevented.

8.1 Registers organization

Table 5. Registers overview

Bit positions labeled as - are not implemented. After reset, all registers are set according to [Table 8 on page 9](#).

| Address | Register name | Bit | | | | | | | | Reference | |
|------------------------------|---------------|-----------------|-------------------|---------------------------------|---------------------------------|----|-------------------|-------|---------|-------------------------------|-------------------------------|
| | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | |
| Control and status registers | | | | | | | | | | | |
| 00h | Control_1 | EXT_TEST | - | STOP | SR | - | CIE | 12_24 | CAP_SEL | Section 8.2.1 | |
| 01h | Control_2 | - | - | MI | HMI | TF | COF[2:0] | | | Section 8.2.2 | |
| 02h | Offset | MODE | OFFSET[6:0] | | | | | | | | Section 8.2.3 |
| 03h | RAM_byte | B[7:0] | | | | | | | | Section 8.2.4 | |
| Time and date registers | | | | | | | | | | | |
| 04h | Seconds | OS | SECONDS (0 to 59) | | | | | | | | Section 8.3.1 |
| 05h | Minutes | - | MINUTES (0 to 59) | | | | | | | | Section 8.3.2 |
| 06h | Hours | - | - | AMPM | HOURS (1 to 12) in 12 hour mode | | | | | Section 8.3.3 | |
| | | | | HOURS (0 to 23) in 24 hour mode | | | | | | | |
| 07h | Days | - | - | DAYS (1 to 31) | | | | | | | Section 8.3.4 |
| 08h | Weekdays | - | - | - | - | - | WEEKDAYS (0 to 6) | | | | Section 8.3.5 |
| 09h | Months | - | - | - | MONTHS (1 to 12) | | | | | | Section 8.3.6 |
| 0Ah | Years | YEARS (0 to 99) | | | | | | | | Section 8.3.7 | |

8.2 Control registers

8.2.1 Register Control_1

Table 6. Control_1 - control and status register 1 (address 00h) bit description

| Bit | Symbol | Value | Description | Reference |
|-----|----------|------------------|--|---------------------------------|
| 7 | EXT_TEST | | external clock test mode | Section 8.2.1.1 |
| | | 0 ^[1] | normal mode | |
| | | 1 | external clock test mode | |
| 6 | - | 0 | unused | - |
| 5 | STOP | | STOP bit | Section 8.2.1.2 |
| | | 0 ^[1] | RTC clock runs | |
| | | 1 | RTC clock is stopped; all RTC divider chain flip-flops are asynchronously set logic 0 | |
| 4 | SR | | software reset | Section 8.2.1.3 |
| | | 0 ^[1] | no software reset | |
| | | 1 | initiate software reset ^[2] ; this bit always returns a 0 when read | |
| 3 | - | 0 | unused | - |
| 2 | CIE | | correction interrupt enable | Section 8.2.3 |
| | | 0 ^[1] | no correction interrupt generated | |
| | | 1 | interrupt pulses are generated at every correction cycle | |
| 1 | 12_24 | | 12 or 24 hour mode | Section 8.3.3 |
| | | 0 ^[1] | 24 hour mode is selected | |
| | | 1 | 12 hour mode is selected | |
| 0 | CAP_SEL | | internal oscillator capacitor selection for quartz crystals with a corresponding load capacitance | - |
| | | 0 ^[1] | 7 pF | |
| | | 1 | 12.5 pF | |

[1] Default value.

[2] For a software reset, 01011000 (58h) must be sent to register Control_1 (see [Section 8.2.1.3](#)).

8.2.1.1 EXT_TEST: external clock test mode

A test mode is available which allows for on-board testing. In this mode, it is possible to set up test conditions and control the operation of the RTC.

The test mode is entered by setting bit EXT_TEST in register Control_1. Then pin CLKOUT becomes an input. The test mode replaces the internal clock signal with the signal applied to pin CLKOUT.

The signal applied to pin CLKOUT should have a minimum pulse width of 300 ns and a maximum period of 1000 ns. The internal clock, now sourced from CLKOUT, is divided down to 1 Hz by a 2⁶ divide chain called a prescaler. The prescaler can be set into a known state by using bit STOP. When bit STOP is set, the prescaler is reset to 0. (STOP must be cleared before the prescaler can operate again.)

From a stop condition, the first 1 second increment will take place after 32 positive edges on pin CLKOUT. Thereafter, every 64 positive edges cause a 1 second increment.

Remark: Entry into test mode is not synchronized to the internal 64 Hz clock. When entering the test mode, no assumption as to the state of the prescaler can be made.

Operation example:

1. Set EXT_TEST test mode (register Control_1, bit EXT_TEST = 1)
2. Set STOP (register Control_1, bit STOP = 1)
3. Clear STOP (register Control_1, bit STOP = 0)
4. Set time registers to desired value
5. Apply 32 clock pulses to pin CLKOUT
6. Read time registers to see the first change
7. Apply 64 clock pulses to pin CLKOUT
8. Read time registers to see the second change

Repeat 7 and 8 for additional increments.

8.2.1.2 STOP: STOP bit function

The function of the STOP bit (see [Figure 4](#)) is to allow for accurate starting of the time circuits. The STOP bit function causes the upper part of the prescaler (F_2 to F_{14}) to be held in reset and thus no 1 Hz ticks are generated. It also stops the output of clock frequencies lower than 8 kHz on pin CLKOUT.

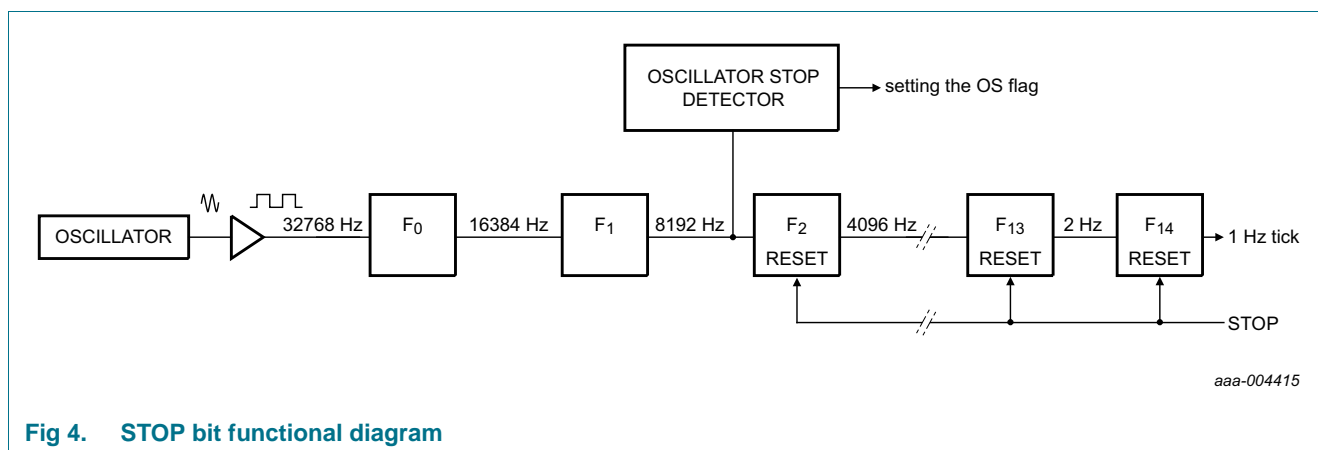


Fig 4. STOP bit functional diagram

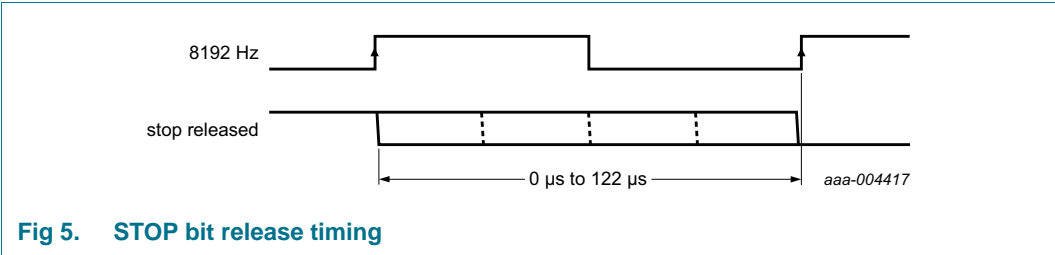
The time circuits can then be set and do not increment until the STOP bit is released (see [Figure 5](#) and [Table 7](#)).

Table 7. First increment of time circuits after STOP bit release

| Bit | Prescaler bits [1] | 1 Hz tick | Time hh:mm:ss | Comment |
|--|--|-----------|------------------|---|
| STOP | F ₀ F ₁ -F ₂ to F ₁₄ | | | |
| Clock is running normally | | | | |
| 0 | 01-0 0001 1101 0100 | | 12:45:12 | prescaler counting normally |
| STOP bit is activated by user. F ₀ F ₁ are not reset and values cannot be predicted externally | | | | |
| 1 | XX-0 0000 0000 0000 | | 12:45:12 | prescaler is reset; time circuits are frozen |
| New time is set by user | | | | |
| 1 | XX-0 0000 0000 0000 | | 08:00:00 | prescaler is reset; time circuits are frozen |
| STOP bit is released by user | | | | |
| 0 | XX-0 0000 0000 0000 | | 08:00:00 | prescaler is now running |
| | XX-1 0000 0000 0000 | | 08:00:00 | - |
| | XX-0 1000 0000 0000 | | 08:00:00 | - |
| | XX-1 1000 0000 0000 | | 08:00:00 | - |
| | : | | : | : |
| | 11-1 1111 1111 1110 | | 08:00:00 | - |
| | 00-0 0000 0000 0001 | | 08:00:01 | 0 to 1 transition of F ₁₄ increments the time circuits |
| | 10-0 0000 0000 0001 | | 08:00:01 | - |
| | : | | : | : |
| | 11-1 1111 1111 1111 | | 08:00:01 | - |
| | 00-0 0000 0000 0000 | | 08:00:01 | - |
| | 10-0 0000 0000 0000 | | 08:00:01 | - |
| | : | | : | : |
| | 11-1 1111 1111 1110 | | 08:00:01 | - |
| | 00-0 0000 0000 0001 | | 08:00:02 | 0 to 1 transition of F ₁₄ increments the time circuits |

[1] F₀ is clocked at 32.768 kHz.

The lower two stages of the prescaler (F₀ and F₁) are not reset. And because the I²C-bus is asynchronous to the crystal oscillator, the accuracy of restarting the time circuits is between zero and one 8.192 kHz cycle (see [Figure 5](#)).



The first increment of the time circuits is between 0.507813 s and 0.507935 s after STOP bit is released. The uncertainty is caused by the prescaler bits F₀ and F₁ not being reset (see [Table 7](#)) and the unknown state of the 32 kHz clock.

8.2.1.3 Software reset

A reset is automatically generated at power-on. A reset can also be initiated with the software reset command. Software reset command means setting bits 6, 4, and 3 in register Control_1 (00h) logic 1 and all other bits logic 0 by sending the bit sequence 01011000 (58h), see [Figure 6](#).

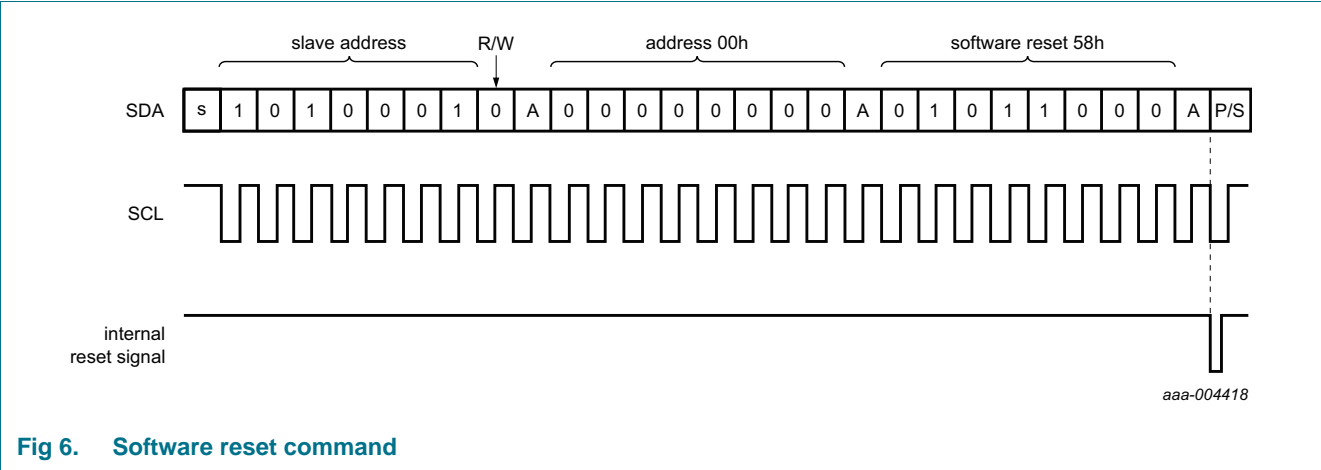


Fig 6. Software reset command

In reset state all registers are set according to [Table 8](#) and the address pointer returns to address 00h.

Table 8. Register reset values

| Address | Register name | Bit | | | | | | | |
|---------|---------------|-----|---|---|---|---|---|---|---|
| | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 00h | Control_1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 01h | Control_2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 02h | Offset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 03h | RAM_byte | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 04h | Seconds | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 05h | Minutes | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 06h | Hours | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 07h | Days | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| 08h | Weekdays | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 |
| 09h | Months | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| 0Ah | Years | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

The PCF85063TP resets to:

- Time** — 00:00:00
- Date** — 20000101
- Weekday** — Saturday

8.2.2 Register Control_2

Table 9. Control_2 - control and status register 2 (address 01h) bit description

| Bit | Symbol | Value | Description |
|--------|----------|------------------|---|
| 7 to 6 | - | 00 | unused |
| 5 | MI | | minute interrupt |
| | | 0 ^[1] | disabled |
| | | 1 | enabled |
| 4 | HMI | | half minute interrupt |
| | | 0 ^[1] | disabled |
| | | 1 | enabled |
| 3 | TF | | timer flag |
| | | 0 ^[1] | no timer interrupt generated |
| | | 1 | flag set when timer interrupt generated |
| 2 to 0 | COF[2:0] | see Table 11 | CLKOUT control |

[1] Default value.

8.2.2.1 MI and HMI: minute and half minute interrupt

The minute interrupt (bit MI) and half minute interrupt (bit HMI) are pre-defined timers for generating interrupt pulses on pin $\overline{\text{INT}}$; see Figure 7. The timers are running in sync with the seconds counter (see Table 19 on page 16).

When starting MI, the first interrupt will be generated after 1 second to 59 seconds. When starting HMI, the first interrupt will be generated after 1 second to 29 seconds. Subsequent periods do not have such a delay. The timers can be enabled independently from one another. However, a minute interrupt enabled on top of a half minute interrupt is not distinguishable.

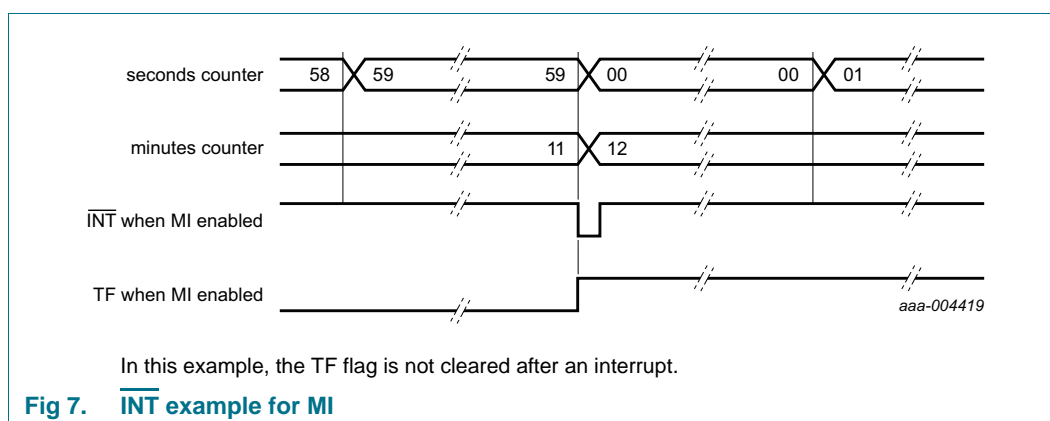


Table 10. Effect of bits MI and HMI on $\overline{\text{INT}}$ generation

| Minute interrupt (bit MI) | Half minute interrupt (bit HMI) | Result |
|---------------------------|---------------------------------|---------------------------|
| 0 | 0 | no interrupt generated |
| 1 | 0 | an interrupt every minute |
| 0 | 1 | an interrupt every 30 s |
| 1 | 1 | an interrupt every 30 s |

The duration of the timer is affected by the register Offset (see [Section 8.2.3](#)). Only when OFFSET[6:0] has the value 00h the periods are consistent.

8.2.2.2 TF: timer flag

The timer flag (bit TF) is set logic 1 on the first trigger of MI or HMI and remains set until it is cleared by command.

8.2.2.3 COF[2:0]: Clock output frequency

A programmable square wave is available at pin CLKOUT. Operation is controlled by the COF[2:0] bits in the register Control_2. Frequencies of 32.768 kHz (default) down to 1 Hz can be generated for use as a system clock, microcontroller clock, input to a charge pump, or for calibration of the oscillator.

Pin CLKOUT is a push-pull output and enabled at power-on. CLKOUT can be disabled by setting COF[2:0] to 111. When disabled, the CLKOUT is LOW.

The duty cycle of the selected clock is not controlled but due to the nature of the clock generation, all clock frequencies except 32.768 kHz have a duty cycle of 50 : 50.

The STOP bit function can also affect the CLKOUT signal, depending on the selected frequency. When the STOP bit is set logic 1, the CLKOUT pin generates a continuous LOW for those frequencies that can be stopped. For more details of the STOP bit function, see [Section 8.2.1.2](#).

Table 11. CLKOUT frequency selection

| COF[2:0] | CLKOUT frequency (Hz) | Typical duty cycle ^[1] | Effect of STOP bit |
|--------------------|-----------------------|-----------------------------------|--------------------|
| 000 ^[2] | 32768 | 60 : 40 to 40 : 60 | no effect |
| 001 | 16384 | 50 : 50 | no effect |
| 010 | 8192 | 50 : 50 | no effect |
| 011 | 4096 | 50 : 50 | CLKOUT = LOW |
| 100 | 2048 | 50 : 50 | CLKOUT = LOW |
| 101 | 1024 | 50 : 50 | CLKOUT = LOW |
| 110 | 1 ^[3] | 50 : 50 | CLKOUT = LOW |
| 111 | CLKOUT = LOW | - | - |

[1] Duty cycle definition: % HIGH-level time : % LOW-level time.

[2] Default value.

[3] 1 Hz clock pulses are affected by offset correction pulses.

8.2.3 Register Offset

The PCF85063TP incorporates an offset register (address 02h) which can be used to implement several functions, such as:

- Accuracy tuning
- Aging adjustment
- Temperature compensation

Table 12. Offset - offset register (address 02h) bit description

| Bit | Symbol | Value | Description |
|--------|-------------|------------------------------|--|
| 7 | MODE | | offset mode |
| | | 0 ^[1] | normal mode: offset is made once every two hours |
| | | 1 | course mode: offset is made every 4 minutes |
| 6 to 0 | OFFSET[6:0] | see Table 13 | offset value |

[1] Default value.

For MODE = 0, each LSB introduces an offset of 4.34 ppm. For MODE = 1, each LSB introduces an offset of 4.069 ppm. The values of 4.34 ppm and 4.069 ppm are based on a nominal 32.768 kHz clock. The offset value is coded in two's complement giving a range of +63 LSB to -64 LSB.

Table 13. Offset values

| OFFSET[6:0] | Offset value in decimal | Offset value in ppm | |
|------------------------|-------------------------|-------------------------|-----------------------|
| | | Normal mode MODE = 0 | Fast mode MODE = 1 |
| 0111111 | +63 | +273.420 | +256.347 |
| 0111110 | +62 | +269.080 | +252.278 |
| : | : | : | : |
| 0000010 | +2 | +8.680 | +8.138 |
| 0000001 | +1 | +4.340 | +4.069 |
| 0000000 ^[1] | 0 | 0 ^[1] | 0 ^[1] |
| 1111111 | -1 | -4.340 | -4.069 |
| 1111110 | -2 | -8.680 | -8.138 |
| : | : | : | : |
| 1000001 | -63 | -273.420 | -256.347 |
| 1000000 | -64 | -277.760 | -260.416 |

[1] Default value.

The correction is made by adding or subtracting clock correction pulses, thereby changing the period of a single second but not by changing the oscillator frequency.

It is possible to monitor when correction pulses are applied. To enable correction interrupt generation, bit CIE (register Control_1) has to be set logic 1. At every correction cycle a pulse is generated on pin $\overline{\text{INT}}$. The pulse width depends on the correction mode. If multiple correction pulses are applied, an interrupt pulse is generated for each correction pulse applied.

8.2.3.1 Correction when MODE = 0

The correction is triggered once every two hours and then correction pulses are applied once per minute until the programmed correction values have been implemented.

Table 14. Correction pulses for MODE = 0

| Correction value | Update every n th hour | Minute | Correction pulses on INT per minute ^[1] |
|------------------|-----------------------------------|--------------------|--|
| +1 or –1 | 2 | 00 | 1 |
| +2 or –2 | 2 | 00 and 01 | 1 |
| +3 or –3 | 2 | 00, 01, and 02 | 1 |
| : | : | : | : |
| +59 or –59 | 2 | 00 to 58 | 1 |
| +60 or –60 | 2 | 00 to 59 | 1 |
| +61 or –61 | 2 | 00 to 59 | 1 |
| | 2nd and next hour | 00 | 1 |
| +62 or –62 | 2 | 00 to 59 | 1 |
| | 2nd and next hour | 00 and 01 | 1 |
| +63 or –63 | 02 | 00 to 59 | 1 |
| | 2nd and next hour | 00, 01, and 02 | 1 |
| –64 | 02 | 00 to 59 | 1 |
| | 2nd and next hour | 00, 01, 02, and 03 | 1 |

[1] The correction pulses on pin $\overline{\text{INT}}$ are $\frac{1}{64}$ s wide.

In MODE = 0, any timer or clock output using a frequency below 64 Hz is affected by the clock correction (see [Table 15](#)).

Table 15. Effect of correction pulses on frequencies for MODE = 0

| Frequency (Hz) | Effect of correction |
|---------------------------|----------------------|
| CLKOUT | |
| 32768 | no effect |
| 16384 | no effect |
| 8192 | no effect |
| 4096 | no effect |
| 2048 | no effect |
| 1024 | no effect |
| 1 | affected |
| Timer source clock | |
| 4096 | no effect |
| 64 | no effect |
| 1 | affected |
| $\frac{1}{60}$ | affected |

8.2.3.2 Correction when MODE = 1

The correction is triggered once every four minutes and then correction pulses are applied once per second up to a maximum of 60 pulses. When correction values greater than 60 pulses are used, additional correction pulses are made in the 59th second.

Clock correction is made more frequently in MODE = 1; however, this can result in higher power consumption.

Table 16. Correction pulses for MODE = 1

| Correction value | Update every n th minute | Second | Correction pulses on INT per second ^[1] |
|------------------|-------------------------------------|----------------|--|
| +1 or -1 | 2 | 00 | 1 |
| +2 or -2 | 2 | 00 and 01 | 1 |
| +3 or -3 | 2 | 00, 01, and 02 | 1 |
| : | : | : | : |
| +59 or -59 | 2 | 00 to 58 | 1 |
| +60 or -60 | 2 | 00 to 59 | 1 |
| +61 or -61 | 2 | 00 to 58 | 1 |
| | 2 | 59 | 2 |
| +62 or -62 | 2 | 00 to 58 | 1 |
| | 2 | 59 | 3 |
| +63 or -63 | 2 | 00 to 58 | 1 |
| | 2 | 59 | 4 |
| -64 | 2 | 00 to 58 | 1 |
| | 2 | 59 | 5 |

[1] The correction pulses on pin $\overline{\text{INT}}$ are $\frac{1}{1024}$ s wide. For multiple pulses, they are repeated at an interval of $\frac{1}{512}$ s.

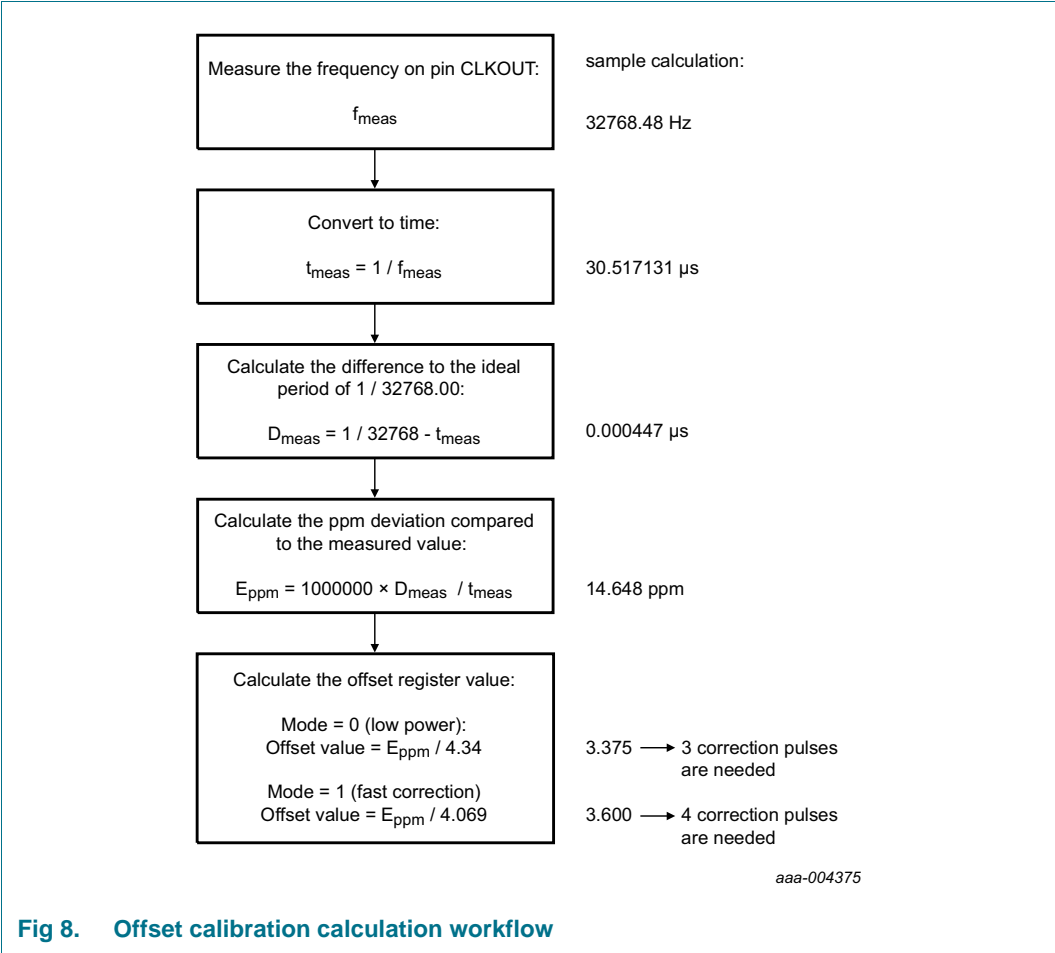
In MODE = 1, any timer source clock using a frequency below 1.024 kHz is also affected by the clock correction (see [Table 17](#)).

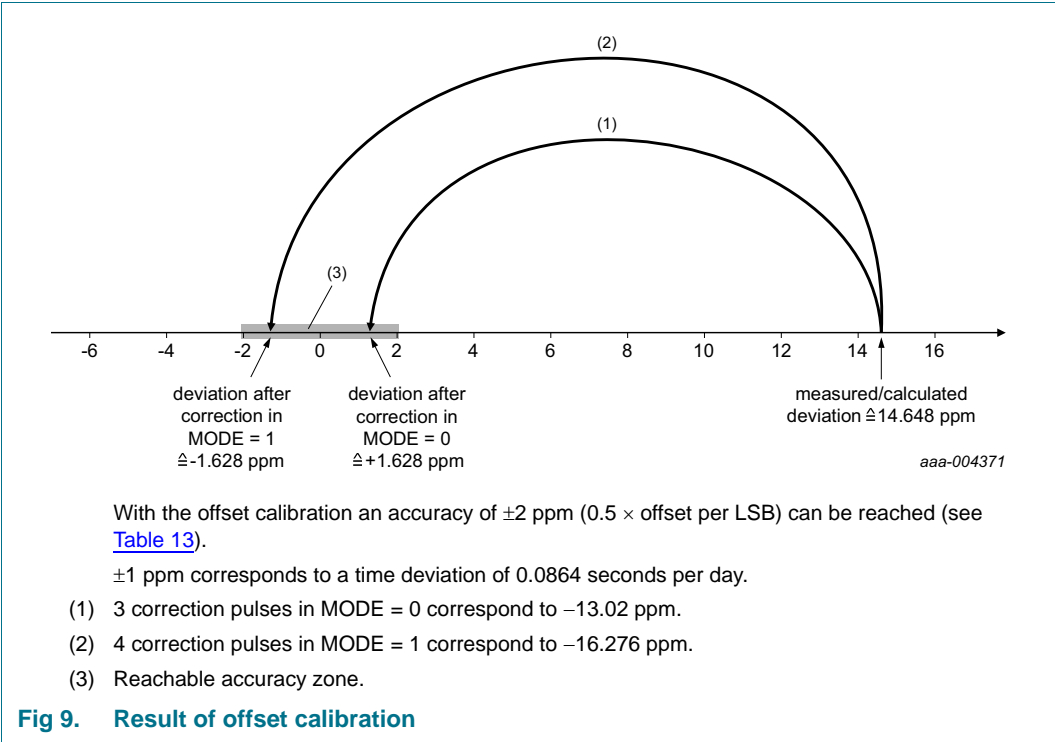
Table 17. Effect of correction pulses on frequencies for MODE = 1

| Frequency (Hz) | Effect of correction |
|---------------------------|----------------------|
| CLKOUT | |
| 32768 | no effect |
| 16384 | no effect |
| 8192 | no effect |
| 4096 | no effect |
| 2048 | no effect |
| 1024 | no effect |
| 1 | affected |
| Timer source clock | |
| 4096 | no effect |
| 64 | affected |
| 1 | affected |
| $\frac{1}{60}$ | affected |

8.2.3.3 Offset calibration workflow

The calibration offset has to be calculated based on the time. [Figure 8](#) shows the workflow how the offset register values can be calculated:





8.2.4 Register RAM_byte

The PCF85063TP provides a free RAM byte, which can be used for any purpose, for example, status byte of the system.

Table 18. RAM_byte - 8-bit RAM register (address 03h) bit description

| Bit | Symbol | Value | Description |
|--------|--------|-------------------------------------|-------------|
| 7 to 0 | B[7:0] | 00000000 ^[1] to 11111111 | RAM content |

[1] Default value.

8.3 Time and date registers

Most of the registers are coded in the BCD format to simplify application use.

8.3.1 Register Seconds

Table 19. Seconds - seconds register (address 04h) bit description

| Bit | Symbol | Value | Place value | Description |
|--------|---------|-----------------------|-------------|---|
| 7 | OS | | | oscillator stop |
| | | 0 | - | clock integrity is guaranteed |
| | | 1 ^[1] | - | clock integrity is not guaranteed; oscillator has stopped or has been interrupted |
| 6 to 4 | SECONDS | 0 ^[1] to 5 | ten's place | actual seconds coded in BCD format, see Table 20 |
| 3 to 0 | | 0 ^[1] to 9 | unit place | |

[1] Default value.

Table 20. Seconds coded in BCD format

| Seconds value in decimal | Upper-digit (ten's place) | | | Digit (unit place) | | | |
|--------------------------|---------------------------|-------|-------|--------------------|-------|-------|-------|
| | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| 00 ^[1] | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 01 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| 02 | 0 | 0 | 0 | 0 | 0 | 1 | 0 |
| : | : | : | : | : | : | : | : |
| 09 | 0 | 0 | 0 | 1 | 0 | 0 | 1 |
| 10 | 0 | 0 | 1 | 0 | 0 | 0 | 0 |
| : | : | : | : | : | : | : | : |
| 58 | 1 | 0 | 1 | 1 | 0 | 0 | 0 |
| 59 | 1 | 0 | 1 | 1 | 0 | 0 | 1 |

[1] Default value.

8.3.1.1 OS: Oscillator stop

When the oscillator of the PCF85063TP is stopped, the OS flag is set. The oscillator can be stopped, for example, by connecting one of the oscillator pins OSCI or OSCO to ground. The oscillator is considered to be stopped during the time between power-on and stable crystal resonance. This time can be in the range of 200 ms to 2 s depending on crystal type, temperature, and supply voltage.

The flag remains set until cleared by command (see [Figure 10](#)). If the flag cannot be cleared, then the oscillator is not running. This method can be used to monitor the oscillator and to determine if the supply voltage has reduced to the point where oscillation fails.

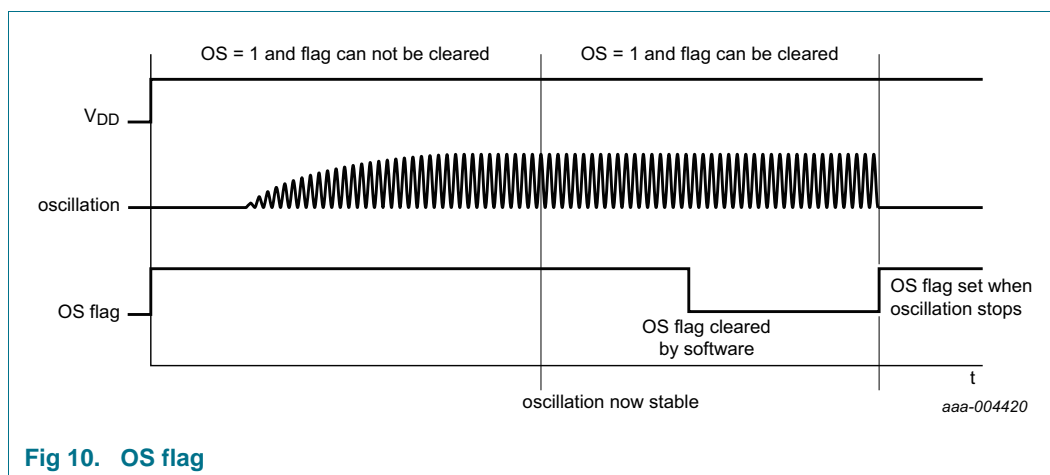


Fig 10. OS flag

8.3.2 Register Minutes

Table 21. Minutes - minutes register (address 05h) bit description

| Bit | Symbol | Value | Place value | Description |
|--------|---------|-----------------------|-------------|---|
| 7 | - | 0 | - | unused |
| 6 to 4 | MINUTES | 0 ^[1] to 5 | ten's place | actual minutes coded in BCD format |
| 3 to 0 | | 0 ^[1] to 9 | unit place | |

[1] Default value.

8.3.3 Register Hours

Table 22. Hours - hours register (address 06h) bit description

| Bit | Symbol | Value | Place value | Description |
|-----------------------------|--------|-----------------------|-------------|---|
| 7 to 6 | - | 00 | - | unused |
| 12 hour mode ^[1] | | | | |
| 5 | AMPM | | | AM/PM indicator |
| | | 0 ^[2] | - | AM |
| | | 1 | - | PM |
| 4 | HOURS | 0 ^[2] to 1 | ten's place | actual hours in 12 hour mode coded in BCD format |
| 3 to 0 | | 0 ^[2] to 9 | unit place | |
| 24 hour mode ^[1] | | | | |
| 5 to 4 | HOURS | 0 ^[2] to 2 | ten's place | actual hours in 24 hour mode coded in BCD format |
| 3 to 0 | | 0 ^[2] to 9 | unit place | |

[1] Hour mode is set by the 12_24 bit in register Control_1.

[2] Default value.

8.3.4 Register Days

Table 23. Days - days register (address 07h) bit description

| Bit | Symbol | Value | Place value | Description |
|--------|---------------------|-----------------------|-------------|---------------------------------------|
| 7 to 6 | - | 00 | - | unused |
| 5 to 4 | DAYS ^[1] | 0 ^[2] to 3 | ten's place | actual day coded in BCD format |
| 3 to 0 | | 0 ^[3] to 9 | unit place | |

[1] If the year counter contains a value, which is exactly divisible by 4 (including the year 00), the PCF85063TP compensates for leap years by adding a 29th day to February.

[2] Default value.

[3] Default value is 1.

8.3.5 Register Weekdays

Table 24. Weekdays - weekdays register (address 08h) bit description

| Bit | Symbol | Value | Description |
|--------|----------|--------|--|
| 7 to 3 | - | 00000 | unused |
| 2 to 0 | WEEKDAYS | 0 to 6 | actual weekday values, see Table 25 |

Table 25. Weekday assignments

| Day ^[1] | Bit | | |
|-------------------------|-----|---|---|
| | 2 | 1 | 0 |
| Sunday | 0 | 0 | 0 |
| Monday | 0 | 0 | 1 |
| Tuesday | 0 | 1 | 0 |
| Wednesday | 0 | 1 | 1 |
| Thursday | 1 | 0 | 0 |
| Friday | 1 | 0 | 1 |
| Saturday ^[2] | 1 | 1 | 0 |

[1] Definition may be reassigned by the user.

[2] Default value.

8.3.6 Register Months

Table 26. Months - months register (address 09h) bit description

| Bit | Symbol | Value | Place value | Description |
|--------|--------|--------|-------------|---|
| 7 to 5 | - | 000 | - | unused |
| 4 | MONTHS | 0 to 1 | ten's place | actual month coded in BCD format, see Table 27 |
| 3 to 0 | | 0 to 9 | unit place | |

Table 27. Month assignments in BCD format

| Month | Upper-digit (ten's place) | Digit (unit place) | | | |
|------------------------|------------------------------|--------------------|-------|-------|-------|
| | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| January ^[1] | 0 | 0 | 0 | 0 | 1 |
| February | 0 | 0 | 0 | 1 | 0 |
| March | 0 | 0 | 0 | 1 | 1 |
| April | 0 | 0 | 1 | 0 | 0 |
| May | 0 | 0 | 1 | 0 | 1 |
| June | 0 | 0 | 1 | 1 | 0 |
| July | 0 | 0 | 1 | 1 | 1 |
| August | 0 | 1 | 0 | 0 | 0 |
| September | 0 | 1 | 0 | 0 | 1 |
| October | 1 | 0 | 0 | 0 | 0 |
| November | 1 | 0 | 0 | 0 | 1 |
| December | 1 | 0 | 0 | 1 | 0 |

[1] Default value.

8.3.7 Register Years

Table 28. Years - years register (0Ah) bit description

| Bit | Symbol | Value | Place value | Description |
|--------|--------|-----------------------|-------------|--|
| 7 to 4 | YEARS | 0 ^[1] to 9 | ten's place | actual year coded in BCD format |
| 3 to 0 | | 0 ^[1] to 9 | unit place | |

[1] Default value.

8.4 Setting and reading the time

Figure 11 shows the data flow and data dependencies starting from the 1 Hz clock tick.

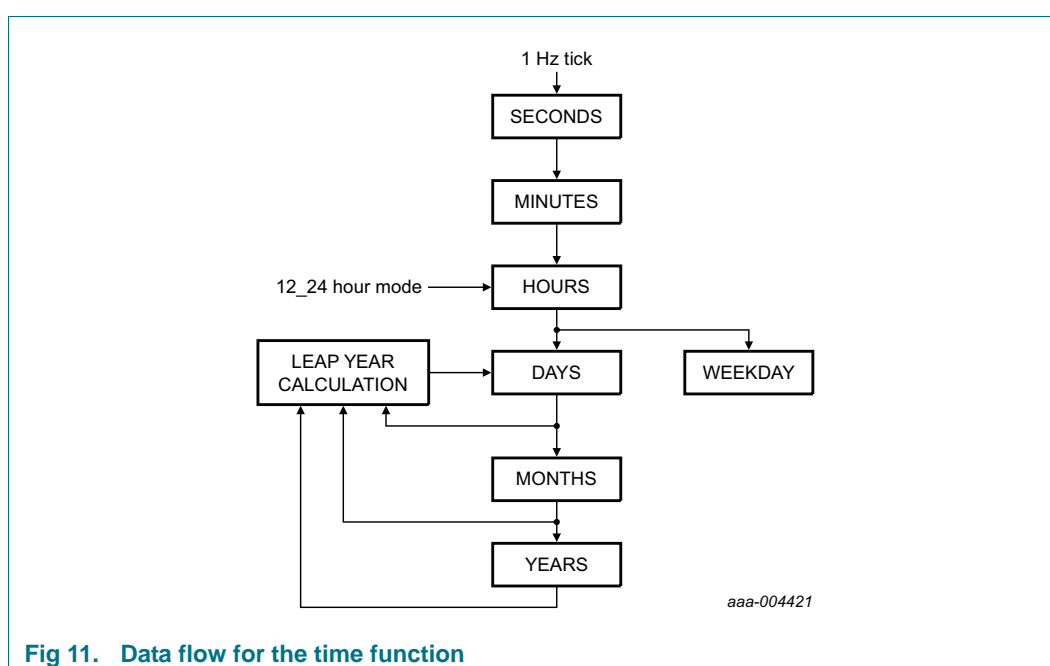


Fig 11. Data flow for the time function

During read/write operations, the time counting circuits (memory locations 04h through 0Ah) are blocked.

The blocking prevents

- Faulty reading of the clock and calendar during a carry condition
- Incrementing the time registers during the read cycle

After this read/write access is completed, the time circuit is released again and any pending request to increment the time counters that occurred during the read/write access is serviced. A maximum of 1 request can be stored; therefore, all accesses must be completed within 1 second (see Figure 12).



aaa-004422

Fig 12. Access time for read/write operations

Because of this method, it is very important to make a read or write access in one go, that is, setting or reading seconds through to years should be made in one single access. Failing to comply with this method could result in the time becoming corrupted.

As an example, if the time (seconds through to hours) is set in one access and then in a second access the date is set, it is possible that the time will increment between the two accesses. A similar problem exists when reading. A roll-over may occur between reads thus giving the minutes from one moment and the hours from the next.

Recommended method for reading the time:

1. Send a START condition and the slave address (see [Table 29 on page 24](#)) for write (A2h)
2. Set the address pointer to 4 (Seconds) by sending 04h
3. Send a RESTART condition or STOP followed by START
4. Send the slave address for read (A3h)
5. Read Seconds
6. Read Minutes
7. Read Hours
8. Read Days
9. Read Weekdays
10. Read Months
11. Read Years
12. Send a STOP condition

9. Characteristics of the I²C-bus interface

The I²C-bus is for bidirectional, two-line communication between different ICs or modules. The two lines are a Serial DAta line (SDA) and a Serial CLock line (SCL). Both lines must be connected to a positive supply via a pull-up resistor. Data transfer may be initiated only when the bus is not busy.

9.1 Bit transfer

One data bit is transferred during each clock pulse. The data on the SDA line must remain stable during the HIGH period of the clock pulse, as changes in the data line at this time are interpreted as a control signal (see [Figure 13](#)).

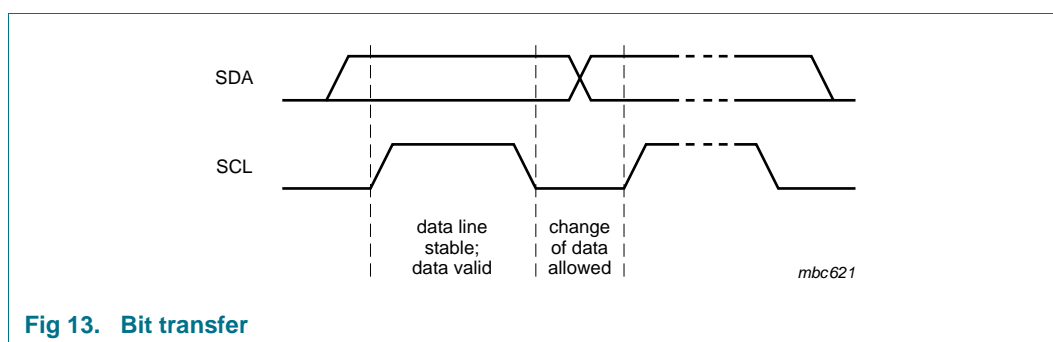


Fig 13. Bit transfer

9.2 START and STOP conditions

Both data and clock lines remain HIGH when the bus is not busy.

A HIGH-to-LOW transition of the data line while the clock is HIGH is defined as the START condition - S.

A LOW-to-HIGH transition of the data line while the clock is HIGH is defined as the STOP condition - P (see [Figure 14](#)).

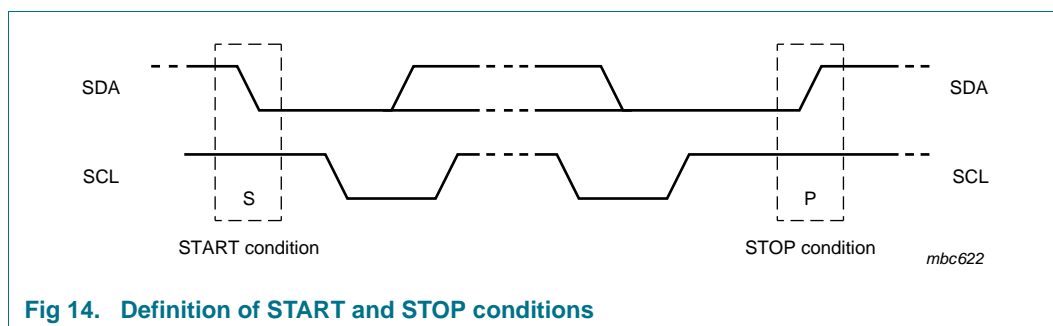
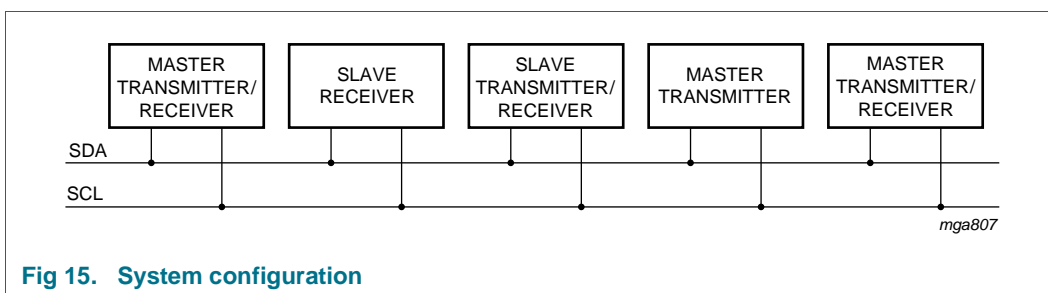


Fig 14. Definition of START and STOP conditions

9.3 System configuration

A device generating a message is a transmitter; a device receiving a message is a receiver. The device that controls the message is the master; and the devices which are controlled by the master are the slaves (see [Figure 15](#)).

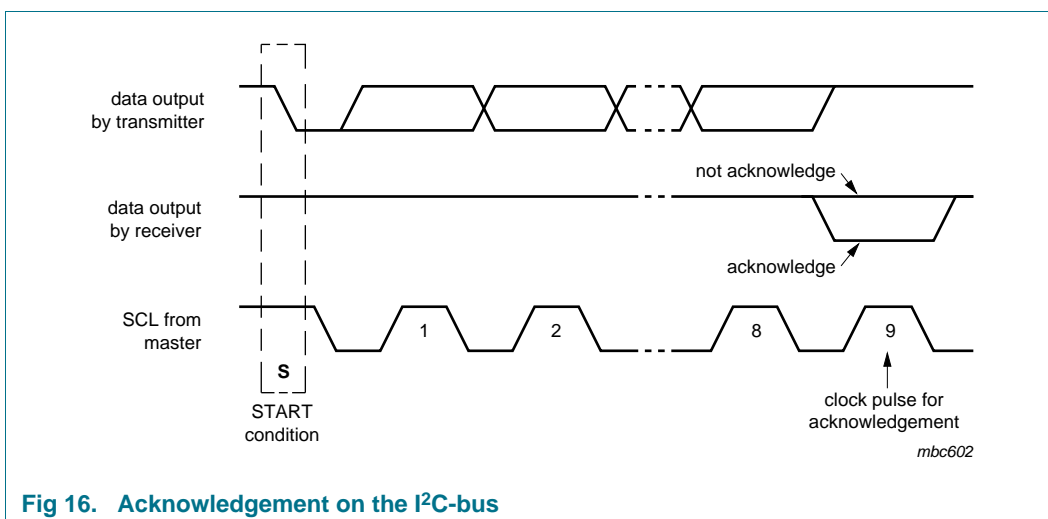


9.4 Acknowledge

The number of data bytes transferred between the START and STOP conditions from transmitter to receiver is unlimited. Each byte of 8 bits is followed by an acknowledge cycle.

- A slave receiver, which is addressed, must generate an acknowledge after the reception of each byte
- Also a master receiver must generate an acknowledge after the reception of each byte that has been clocked out of the slave transmitter
- The device that acknowledges must pull-down the SDA line during the acknowledge clock pulse, so that the SDA line is stable LOW during the HIGH period of the acknowledge related clock pulse (set-up and hold times must be considered)
- A master receiver must signal an end of data to the transmitter by not generating an acknowledge on the last byte that has been clocked out of the slave. In this event, the transmitter must leave the data line HIGH to enable the master to generate a STOP condition

Acknowledgement on the I²C-bus is shown in [Figure 16](#).



9.5 I²C-bus protocol

9.5.1 Addressing

One I²C-bus slave address (1010001) is reserved for the PCF85063TP. The entire I²C-bus slave address byte is shown in [Table 29](#).

Table 29. I²C slave address byte

| Bit | Slave address | | | | | | | 0 LSB R/ \overline{W} |
|-----|---------------|---|---|---|---|---|---|-------------------------------|
| | 7 MSB | 6 | 5 | 4 | 3 | 2 | 1 | |
| | 1 | 0 | 1 | 0 | 0 | 0 | 1 | |

After a START condition, the I²C slave address has to be sent to the PCF85063TP device.

The R/ \overline{W} bit defines the direction of the following single or multiple byte data transfer (R/ \overline{W} = 0 for writing, R/ \overline{W} = 1 for reading). For the format and the timing of the START condition (S), the STOP condition (P) and the acknowledge bit (A) refer to the I²C-bus characteristics (see [Ref. 12 "UM10204"](#)). In the write mode, a data transfer is terminated by sending either the STOP condition or the START condition of the next data transfer.

9.5.2 Clock and calendar READ or WRITE cycles

The I²C-bus configuration for the different PCF85063TP READ and WRITE cycles is shown in [Figure 17](#) and [Figure 18](#). The register address is a 4-bit value that defines which register will be accessed next. The upper 4 bits of the register address are not used.

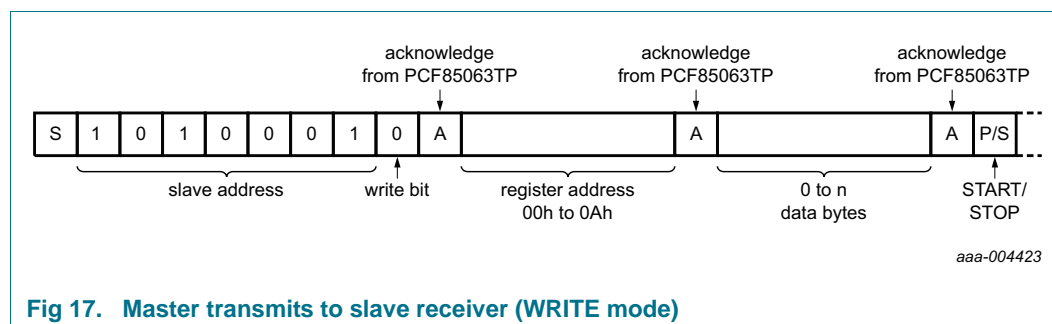
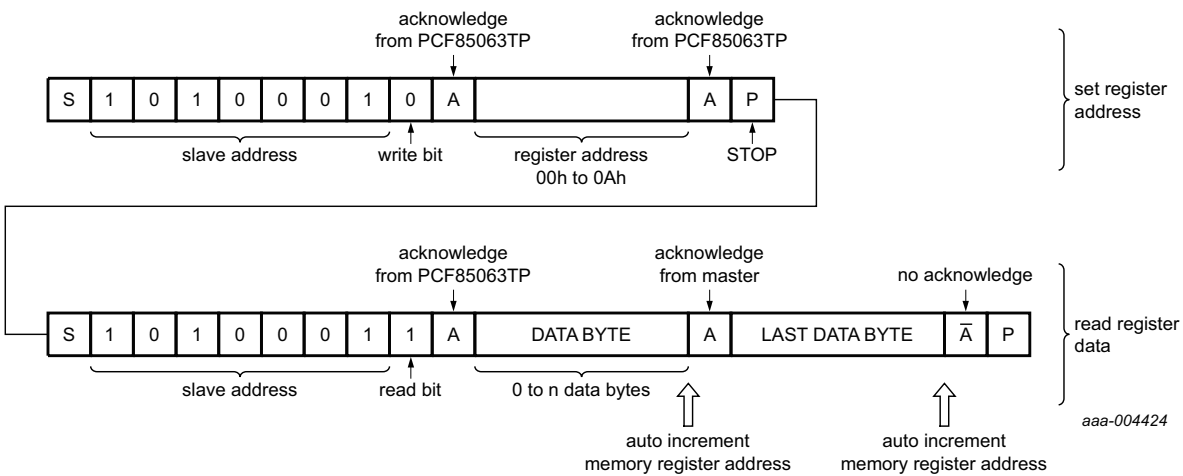


Fig 17. Master transmits to slave receiver (WRITE mode)



For multimaster configurations and to fasten the communication, the STOP-START sequence can be replaced by a repeated START (Sr).

Fig 18. Master reads after setting register address (WRITE register address; READ data)

10. Internal circuitry

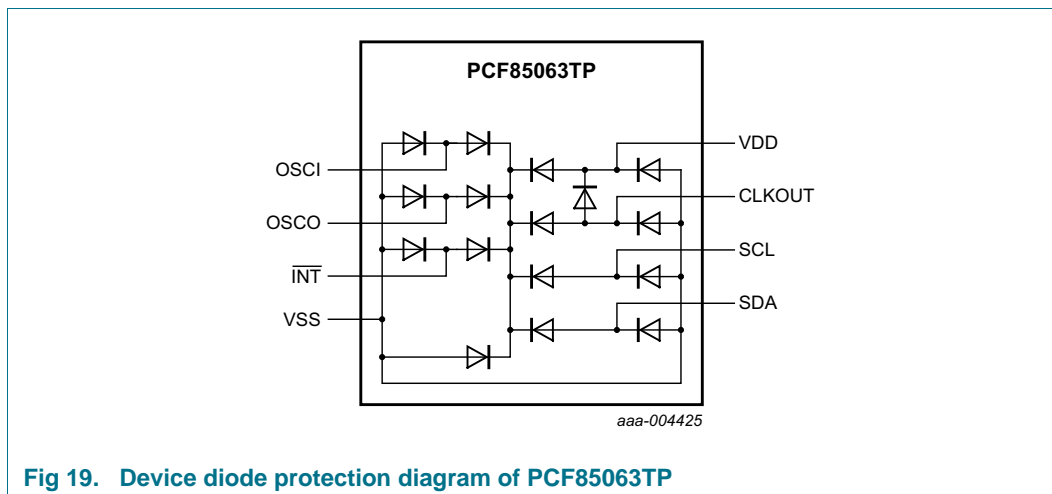


Fig 19. Device diode protection diagram of PCF85063TP

11. Safety notes

CAUTION



This device is sensitive to ElectroStatic Discharge (ESD). Observe precautions for handling electrostatic sensitive devices.

Such precautions are described in the *ANSI/ESD S20.20*, *IEC/ST 61340-5*, *JESD625-A* or equivalent standards.

12. Limiting values

Table 30. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|-----------|---------------------------------|------------------------|---------|-------|------|
| V_{DD} | supply voltage | | -0.5 | +6.5 | V |
| I_{DD} | supply current | | -50 | +50 | mA |
| V_I | input voltage | on pins SCL, SDA, OSCI | -0.5 | +6.5 | V |
| V_O | output voltage | | -0.5 | +6.5 | V |
| I_I | input current | at any input | -10 | +10 | mA |
| I_O | output current | at any output | -10 | +10 | mA |
| P_{tot} | total power dissipation | | - | 300 | mW |
| V_{ESD} | electrostatic discharge voltage | HBM | [1] - | ±5000 | V |
| | | CDM | [2] - | ±1500 | V |
| I_{lu} | latch-up current | | [3] - | 200 | mA |
| T_{stg} | storage temperature | | [4] -65 | +150 | °C |
| T_{amb} | ambient temperature | operating device | -40 | +85 | °C |

[1] Pass level; Human Body Model (HBM) according to [Ref. 7 "JESD22-A114"](#).

[2] Pass level; Charged-Device Model (CDM), according to [Ref. 8 "JESD22-C101"](#).

[3] Pass level; latch-up testing, according to [Ref. 9 "JESD78"](#) at maximum ambient temperature ($T_{amb(max)}$).

[4] According to the store and transport requirements (see [Ref. 14 "UM10569"](#)) the devices have to be stored at a temperature of +8 °C to +45 °C and a humidity of 25 % to 75 %.

13. Characteristics

Table 31. Static characteristics

$V_{DD} = 0.9\text{ V to }5.5\text{ V}$; $V_{SS} = 0\text{ V}$; $T_{amb} = -40\text{ °C to }+85\text{ °C}$; $f_{osc} = 32.768\text{ kHz}$; quartz $R_s = 60\text{ k}\Omega$; $C_L = 7\text{ pF}$; unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------------|---------------------------|---|--------------------|-----|--------------------|------|
| Supplies | | | | | | |
| V _{DD} | supply voltage | interface inactive; f _{SCL} = 0 Hz | [1] 0.9 | - | 5.5 | V |
| | | interface active; f _{SCL} = 400 kHz | [1] 1.8 | - | 5.5 | V |
| I _{DD} | supply current | V _{DD} = 3.3 V | [2] | | | |
| | | interface inactive; f _{SCL} = 0 Hz | | | | |
| | | T _{amb} = 25 °C | - | 220 | 450 | nA |
| | | T _{amb} = 50 °C | [3] - | 250 | 500 | nA |
| | | T _{amb} = 85 °C | - | 470 | 600 | nA |
| | | interface active; f _{SCL} = 400 kHz | - | 18 | 50 | μA |
| Inputs[4] | | | | | | |
| V _I | input voltage | | V _{SS} | - | 5.5 | V |
| V _{IL} | LOW-level input voltage | | V _{SS} | - | 0.3V _{DD} | V |
| V _{IH} | HIGH-level input voltage | | 0.7V _{DD} | - | V _{DD} | V |
| I _{LI} | input leakage current | V _I = V _{SS} or V _{DD} | - | 0 | - | μA |
| | | post ESD event | -0.15 | - | +0.15 | μA |
| C _i | input capacitance | | [5] - | - | 7 | pF |
| Outputs | | | | | | |
| V _{OH} | HIGH-level output voltage | on pin CLKOUT | 0.8V _{DD} | - | V _{DD} | V |
| V _{OL} | LOW-level output voltage | on pins SDA, $\overline{\text{INT}}$, CLKOUT | V _{SS} | - | 0.2V _{DD} | V |
| I _{OH} | HIGH-level output current | output source current; V _{OH} = 2.9 V; V _{DD} = 3.3 V; on pin CLKOUT | 1 | 3 | - | mA |
| I _{OL} | LOW-level output current | output sink current; V _{OL} = 0.4 V; V _{DD} = 3.3 V | | | | |
| | | on pin SDA | 3 | 8.5 | - | mA |
| | | on pin $\overline{\text{INT}}$ | 2 | 6 | - | mA |
| | | on pin CLKOUT | 1 | 3 | - | mA |

Table 31. Static characteristics ...continued

$V_{DD} = 0.9\text{ V}$ to 5.5 V ; $V_{SS} = 0\text{ V}$; $T_{amb} = -40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$; $f_{osc} = 32.768\text{ kHz}$; quartz $R_s = 60\text{ k}\Omega$; $C_L = 7\text{ pF}$; unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--------------------------|---|---|-----|-------|------|------------|
| Oscillator | | | | | | |
| $\Delta f_{osc}/f_{osc}$ | relative oscillator frequency variation | $\Delta V_{DD} = 200\text{ mV}$; $T_{amb} = 25\text{ }^{\circ}\text{C}$ | - | 0.075 | - | ppm |
| $C_{L(itg)}$ | integrated load capacitance | on pins OSC0, OSC1 | [6] | | | |
| | | $C_L = 7\text{ pF}$ | 4.2 | 7 | 9.8 | pF |
| | | $C_L = 12.5\text{ pF}$ | 7.5 | 12.5 | 17.5 | pF |
| R_s | series resistance | | - | - | 100 | k Ω |

[1] For reliable oscillator start-up at power-on: $V_{DD(po)min} = V_{DD(min)} + 0.3\text{ V}$.

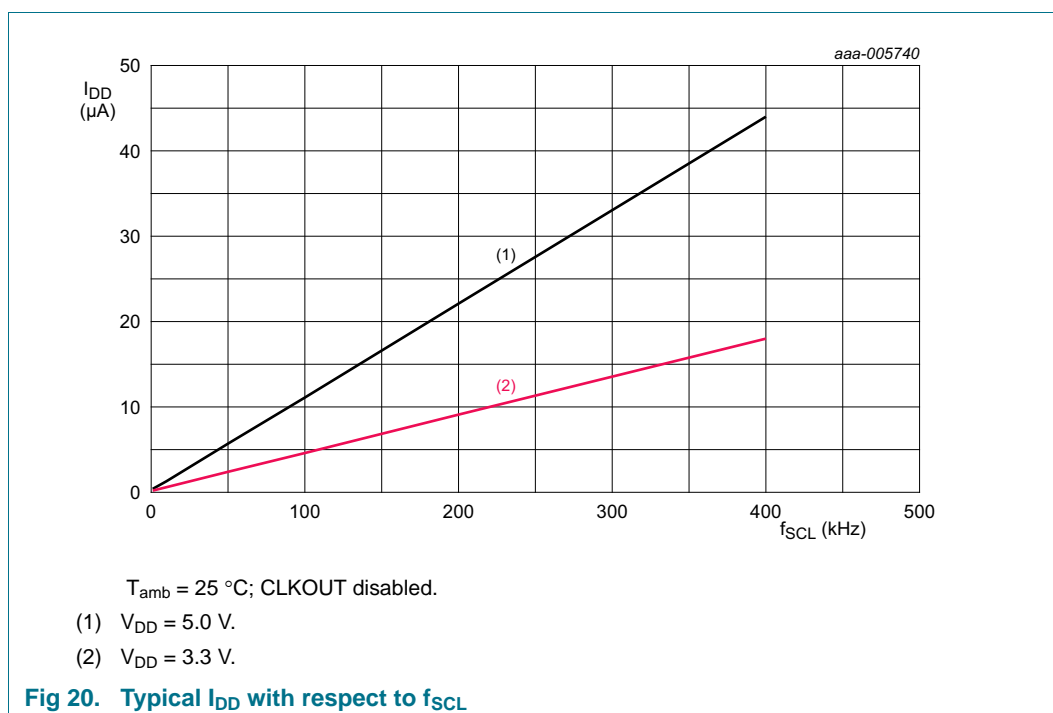
[2] Timer source clock = $1/60\text{ Hz}$, level of pins SCL and SDA is V_{DD} or V_{SS} .

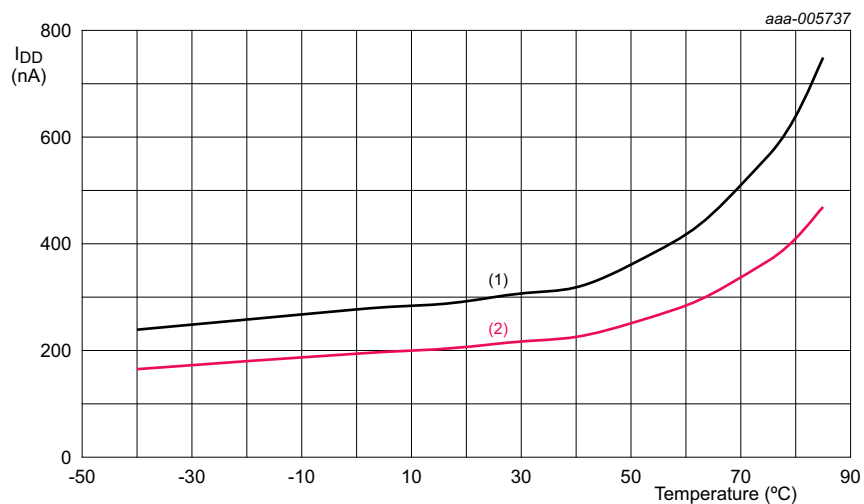
[3] Tested on sample basis.

[4] The I²C-bus interface of PCF85063TP is 5 V tolerant.

[5] Implicit by design.

[6] Integrated load capacitance, $C_{L(itg)}$, is a calculation of C_{OSCI} and C_{OSCO} in series: $C_{L(itg)} = \frac{(C_{OSCI} \cdot C_{OSCO})}{(C_{OSCI} + C_{OSCO})}$.

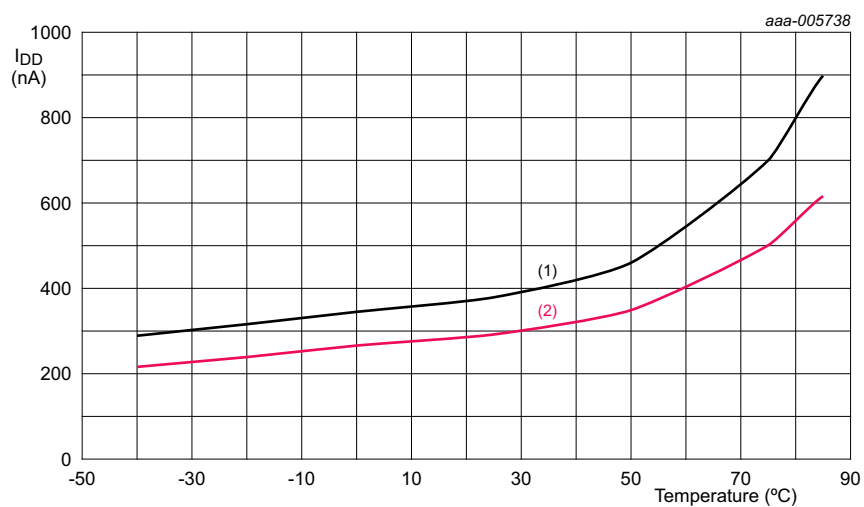




$C_{L(itg)} = 7$ pF; CLKOUT disabled.

(1) $V_{DD} = 5.5$ V.

(2) $V_{DD} = 3.3$ V.



$C_{L(itg)} = 12.5$ pF; CLKOUT disabled.

(1) $V_{DD} = 5.5$ V.

(2) $V_{DD} = 3.3$ V.

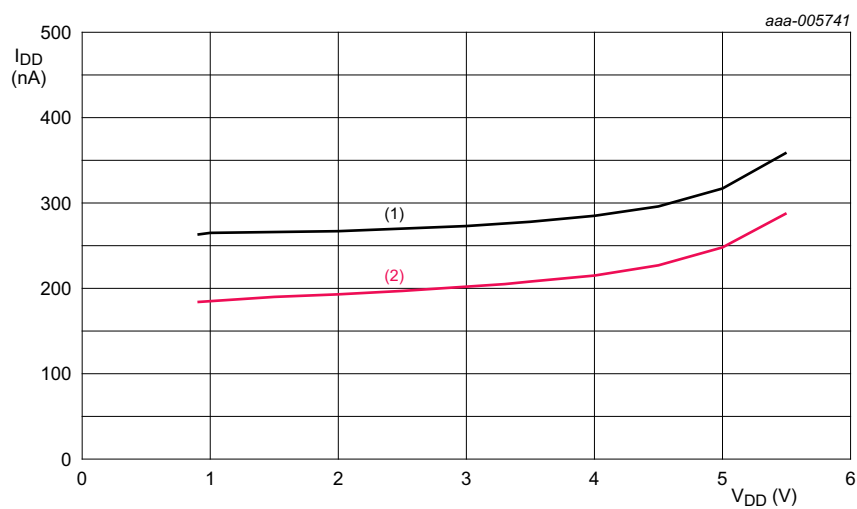
Fig 21. Typical I_{DD} as a function of temperature



$T_{amb} = 25\text{ }^{\circ}\text{C}$; $f_{CLKOUT} = 32768\text{ Hz}$.

(1) 47 pF CLKOUT load.

(2) 22 pF CLKOUT load.

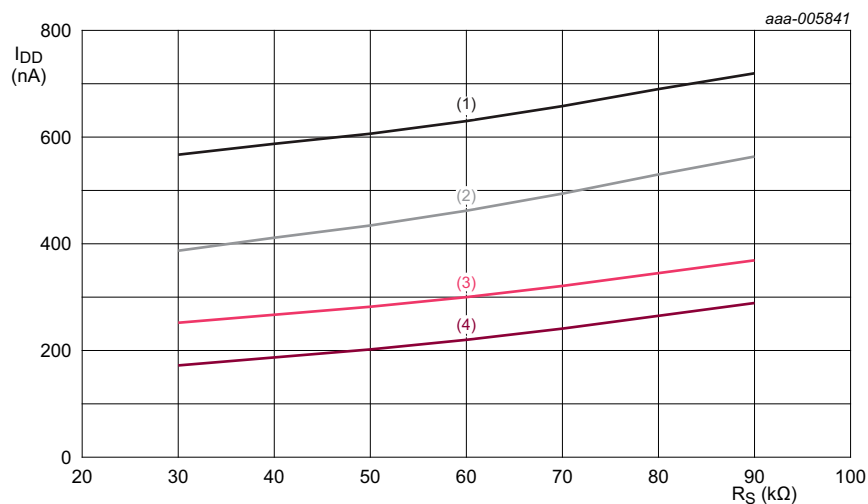


$T_{amb} = 25\text{ }^{\circ}\text{C}$; CLKOUT disabled.

(1) $C_{L(itg)} = 12.5\text{ pF}$.

(2) $C_{L(itg)} = 7\text{ pF}$.

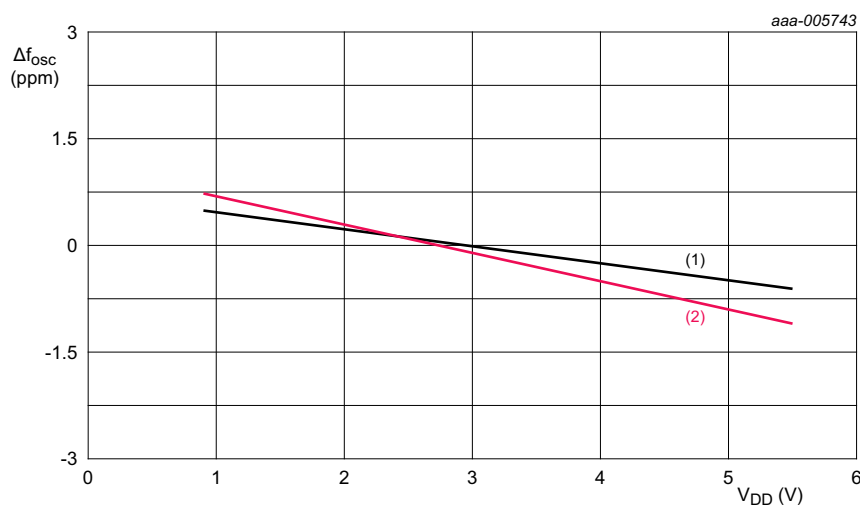
Fig 22. Typical I_{DD} with respect to V_{DD}



$V_{DD} = 3.3$ V; CLKOUT disabled.

- (1) $C_{L(itg)} = 12.5$ pF; 50 °C; maximum value.
- (2) $C_{L(itg)} = 7$ pF; 50 °C; maximum value.
- (3) $C_{L(itg)} = 12.5$ pF; 25 °C; typical value.
- (4) $C_{L(itg)} = 7$ pF; 25 °C; typical value.

Fig 23. I_{DD} with respect to quartz R_S



$T_{amb} = 25$ °C.

- (1) $C_{L(itg)} = 7$ pF.
- (2) $C_{L(itg)} = 12.5$ pF.

Fig 24. Oscillator frequency variation with respect to V_{DD}

Table 32. I²C-bus characteristics

$V_{DD} = 1.8\text{ V to }5.5\text{ V}$; $V_{SS} = 0\text{ V}$; $T_{amb} = -40\text{ }^{\circ}\text{C to }+85\text{ }^{\circ}\text{C}$; $f_{osc} = 32.768\text{ kHz}$; quartz $R_s = 60\text{ k}\Omega$; $C_L = 7\text{ pF}$; unless otherwise specified. All timing values are valid within the operating supply voltage and temperature range and referenced to V_{IL} and V_{IH} with an input voltage swing of V_{SS} to V_{DD} [1].

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--------------|---|------------|---------------|-----|-----|---------------|
| C_b | capacitive load for each bus line | | - | - | 400 | pF |
| f_{SCL} | SCL clock frequency | [2] | 0 | - | 400 | kHz |
| $t_{HD;STA}$ | hold time (repeated) START condition | | 0.6 | - | - | μs |
| $t_{SU;STA}$ | set-up time for a repeated START condition | | 0.6 | - | - | μs |
| t_{LOW} | LOW period of the SCL clock | | 1.3 | - | - | μs |
| t_{HIGH} | HIGH period of the SCL clock | | 0.6 | - | - | μs |
| t_r | rise time of both SDA and SCL signals | | $20 + 0.1C_b$ | - | 0.3 | μs |
| t_f | fall time of both SDA and SCL signals | | $20 + 0.1C_b$ | - | 0.3 | μs |
| t_{BUF} | bus free time between a STOP and START condition | | 1.3 | - | - | μs |
| $t_{SU;DAT}$ | data set-up time | | 100 | - | - | ns |
| $t_{HD;DAT}$ | data hold time | | 0 | - | - | ns |
| $t_{SU;STO}$ | set-up time for STOP condition | | 0.6 | - | - | μs |
| $t_{VD;DAT}$ | data valid time | | 0 | - | 0.9 | μs |
| $t_{VD;ACK}$ | data valid acknowledge time | | 0 | - | 0.9 | μs |
| t_{SP} | pulse width of spikes that must be suppressed by the input filter | | 0 | - | 50 | ns |

[1] A detailed description of the I²C-bus specification is given in [Ref. 12 "UM10204"](#).

[2] I²C-bus access time between two STARTs or between a START and a STOP condition to this device must be less than one second.

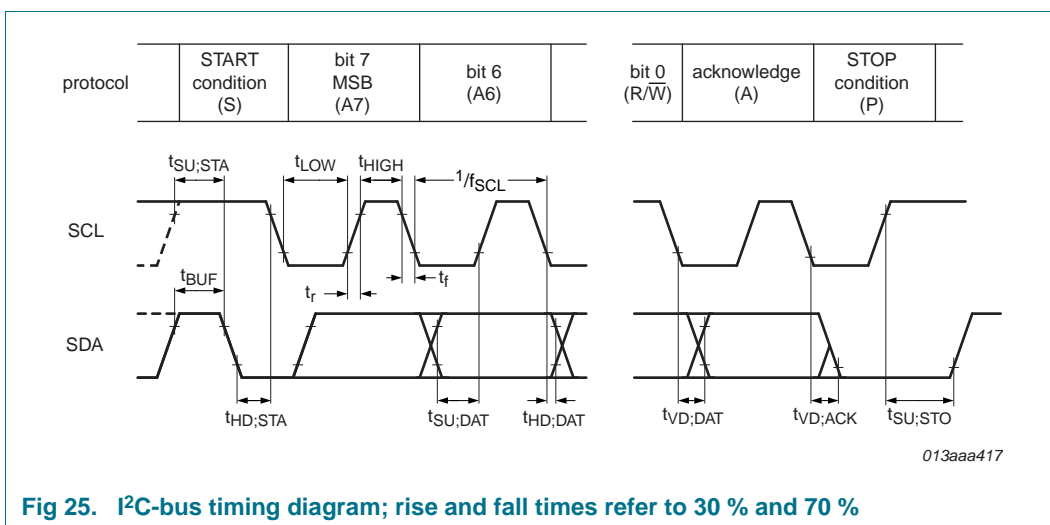
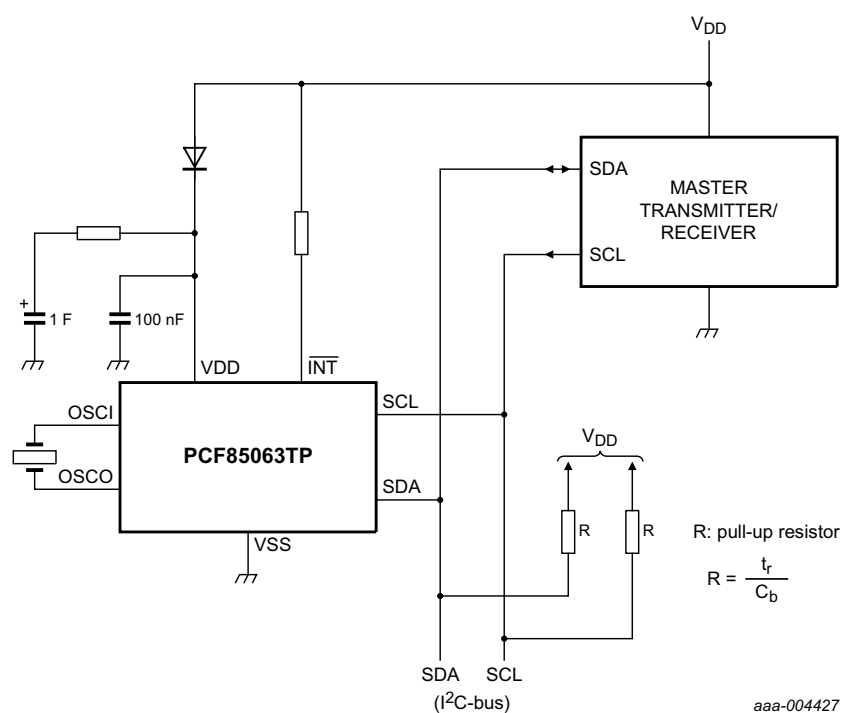


Fig 25. I²C-bus timing diagram; rise and fall times refer to 30 % and 70 %

14. Application information



A 1 farad super capacitor combined with a low V_F diode can be used as a standby or back-up supply. With the RTC in its minimum power configuration i.e. timer off and CLKOUT off, the RTC may operate for weeks.

Fig 26. Application diagram for PCF85063TP

15. Package outline

HWSON8: plastic thermal enhanced very very thin small outline package; no leads;
8 terminals; body 2 x 3 x 0.75 mm

SOT1069-2

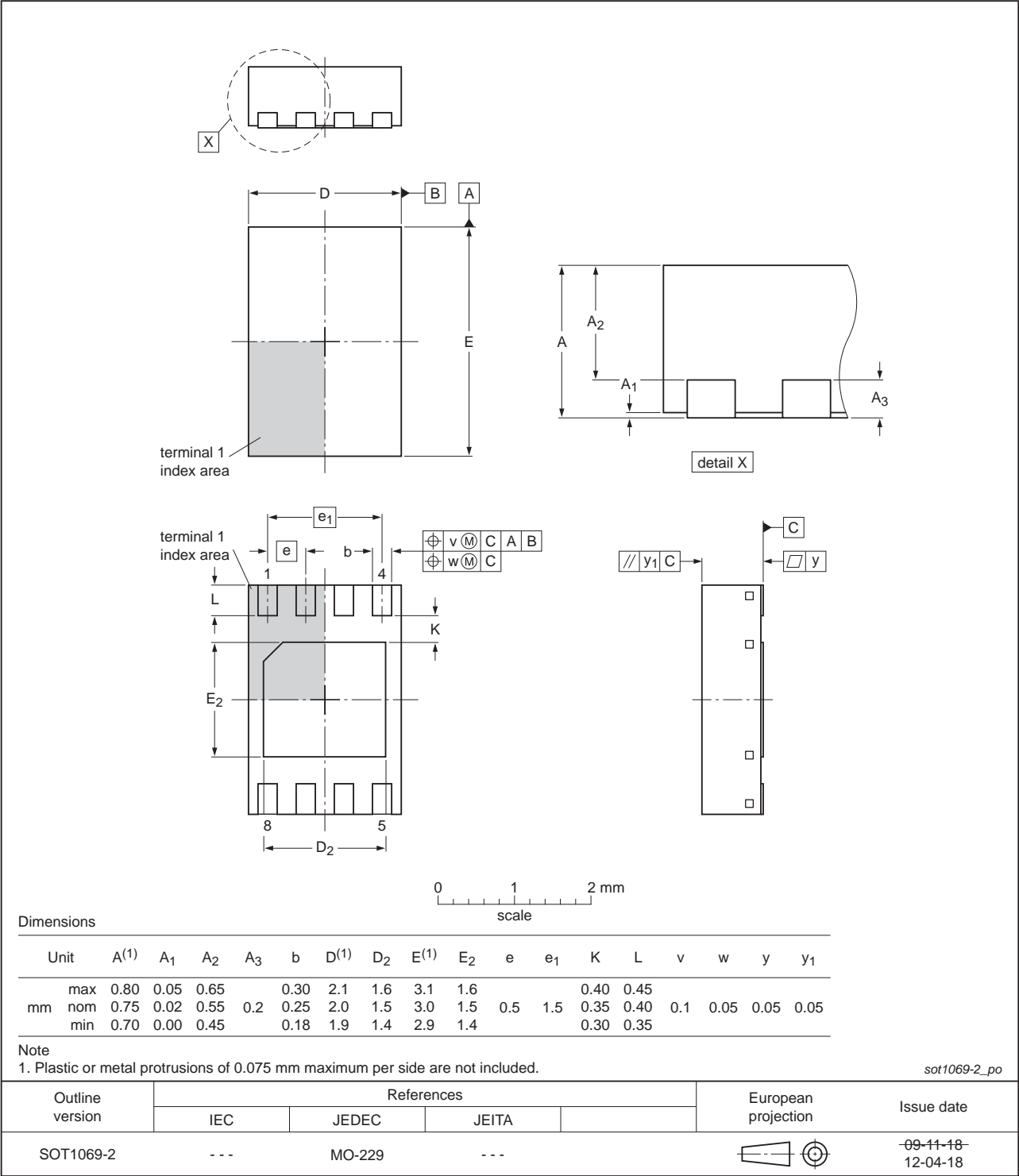


Fig 27. Package outline SOT1069-2 (HWSON8) of PCF85063TP

16. Handling information

All input and output pins are protected against ElectroStatic Discharge (ESD) under normal handling. When handling Metal-Oxide Semiconductor (MOS) devices ensure that all normal precautions are taken as described in *JESD625-A*, *IEC 61340-5* or equivalent standards.

17. Packing information

17.1 Tape and reel information

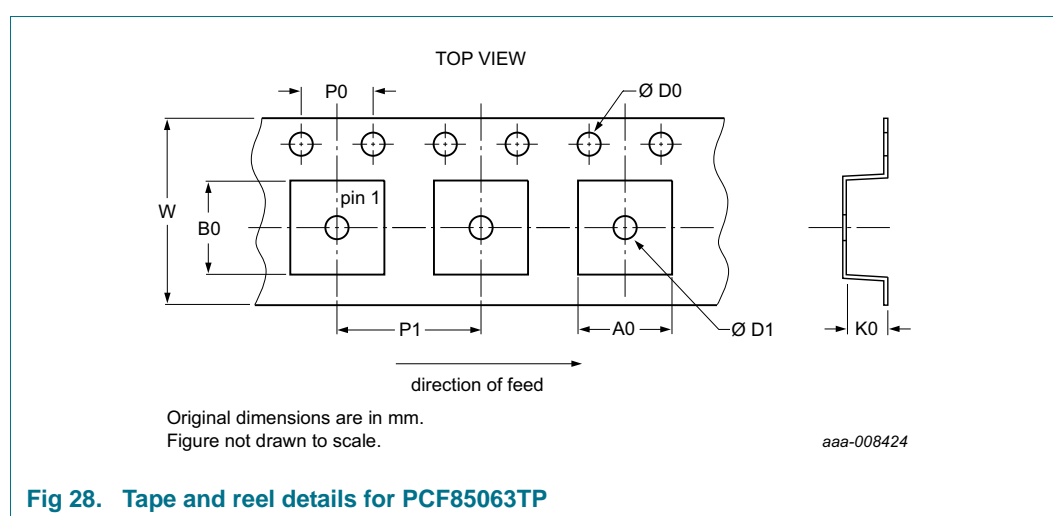


Fig 28. Tape and reel details for PCF85063TP

Table 33. Carrier tape dimensions of PCF85063TP

Nominal values without production tolerances.

| Symbol | Description | Value | Unit |
|---------------------------|-----------------------------|-------|------|
| Compartments | | | |
| A0 | pocket width in x direction | 2.25 | mm |
| B0 | pocket width in y direction | 3.25 | mm |
| K0 | pocket depth | 1.05 | mm |
| P1 | pocket hole pitch | 4 | mm |
| D1 | pocket hole diameter | 1 | mm |
| Overall dimensions | | | |
| W | tape width | 8 | mm |
| D0 | sprocket hole diameter | 1.55 | mm |
| P0 | sprocket hole pitch | 4 | mm |

18. Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

18.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

18.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leadless or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leadless SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leadless packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

18.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

18.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see [Figure 29](#)) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with [Table 34](#) and [35](#)

Table 34. SnPb eutectic process (from J-STD-020D)

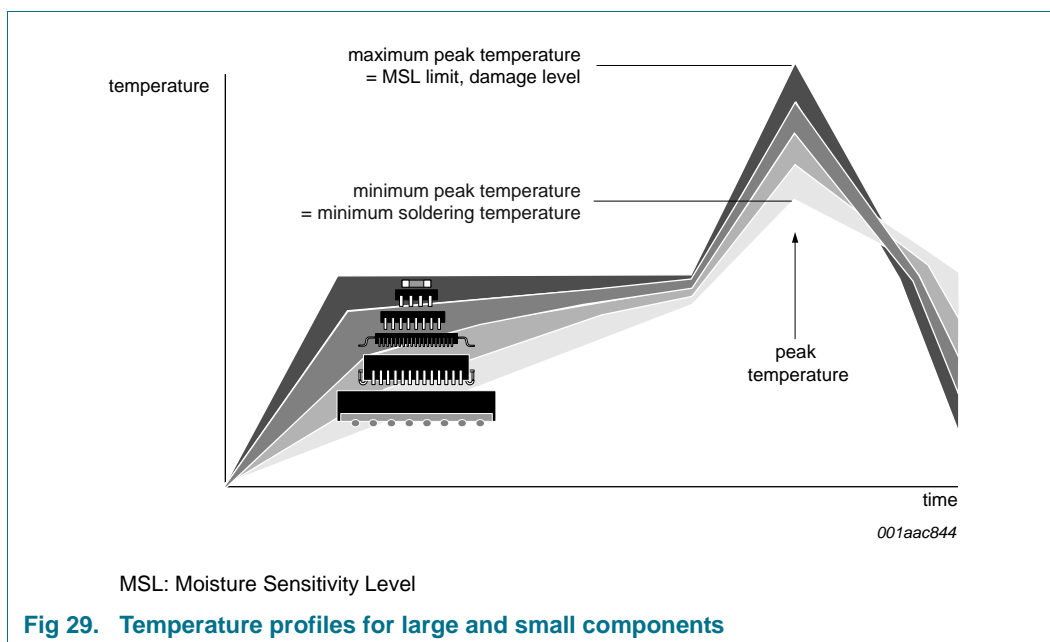
| Package thickness (mm) | Package reflow temperature (°C) | |
|------------------------|---------------------------------|-------|
| | Volume (mm ³) | |
| | < 350 | ≥ 350 |
| < 2.5 | 235 | 220 |
| ≥ 2.5 | 220 | 220 |

Table 35. Lead-free process (from J-STD-020D)

| Package thickness (mm) | Package reflow temperature (°C) | | |
|------------------------|---------------------------------|-------------|--------|
| | Volume (mm ³) | | |
| | < 350 | 350 to 2000 | > 2000 |
| < 1.6 | 260 | 260 | 260 |
| 1.6 to 2.5 | 260 | 250 | 245 |
| > 2.5 | 250 | 245 | 245 |

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see [Figure 29](#).

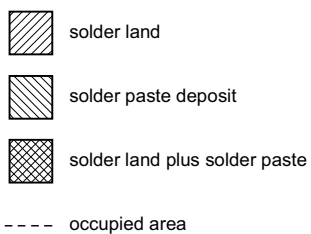
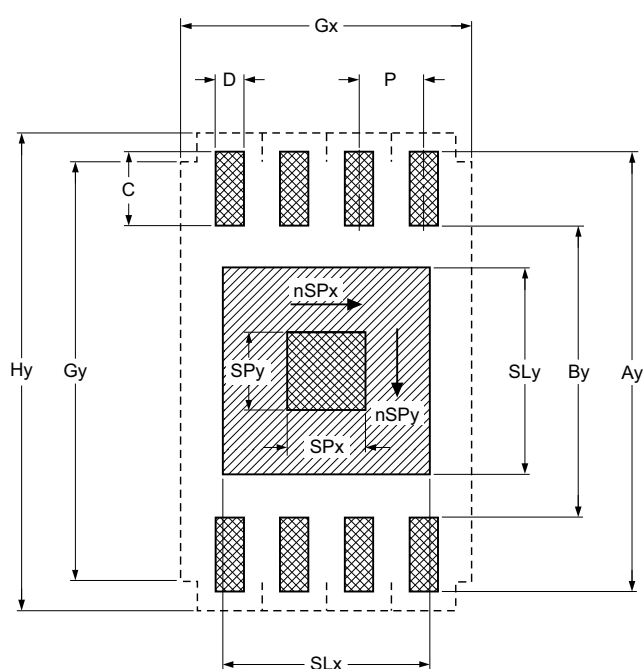


For further information on temperature profiles, refer to Application Note *AN10365* “Surface mount reflow soldering description”.

19. Footprint information

Footprint information for reflow soldering of HWSO8 package

SOT1069-2



DIMENSIONS in mm

| P | Ay | By | C | D | SLx | SLy | SPx | SPy | Gx | Gy | Hy |
|-----|------|-----|-------|------|-----|-----|-----|-----|------|------|-----|
| 0.5 | 3.45 | 2.2 | 0.625 | 0.25 | 1.6 | 1.6 | 0.6 | 0.6 | 2.25 | 3.25 | 3.7 |

| nSPx | nSPy |
|------|------|
| 1 | 1 |

| | |
|------------|---------------------------------|
| Issue date | 12-02-09 12-02-22 |
|------------|---------------------------------|

sot1069-2_fr

Fig 30. Footprint information for reflow soldering of SOT1069-2 (HWSO8) of PCF85063TP

20. Abbreviations

Table 36. Abbreviations

| Acronym | Description |
|------------------|---|
| BCD | Binary Coded Decimal |
| CMOS | Complementary Metal Oxide Semiconductor |
| ESD | ElectroStatic Discharge |
| HBM | Human Body Model |
| I ² C | Inter-Integrated Circuit |
| IC | Integrated Circuit |
| LSB | Least Significant Bit |
| MSB | Most Significant Bit |
| MSL | Moisture Sensitivity Level |
| PCB | Printed-Circuit Board |
| POR | Power-On Reset |
| RTC | Real-Time Clock |
| SCL | Serial CLock line |
| SDA | Serial DATA line |
| SMD | Surface Mount Device |

21. References

- [1] **AN10365** — Surface mount reflow soldering description
- [2] **AN10366** — HVQFN application information
- [3] **AN11247** — Improved timekeeping accuracy with PCF85063, PCF8523 and PCF2123 using an external temperature sensor
- [4] **IEC 60134** — Rating systems for electronic tubes and valves and analogous semiconductor devices
- [5] **IEC 61340-5** — Protection of electronic devices from electrostatic phenomena
- [6] **IPC/JEDEC J-STD-020** — Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices
- [7] **JESD22-A114** — Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)
- [8] **JESD22-C101** — Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components
- [9] **JESD78** — IC Latch-Up Test
- [10] **JESD625-A** — Requirements for Handling Electrostatic-Discharge-Sensitive (ESDS) Devices
- [11] **SNV-FA-01-02** — Marking Formats Integrated Circuits
- [12] **UM10204** — I²C-bus specification and user manual
- [13] **UM10301** — User Manual for NXP Real Time Clocks PCF85x3, PCA8565 and PCF2123, PCA2125
- [14] **UM10569** — Store and transport requirements
- [15] **UM10698** — User manual for I2C-bus RTC demo board OM11059A

22. Revision history

Table 37. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|----------------|--|----------------------|---------------|----------------|
| PCF85063TP v.3 | 20130711 | Product data sheet | - | PCF85063TP v.2 |
| Modifications: | <ul style="list-style-type: none"> Corrected sales item (12NC) and delivery form description in Table 2 Corrected packing information in Figure 28 | | | |
| PCF85063TP v.2 | 20130415 | Product data sheet | - | PCF85063TP v.1 |
| PCF85063TP v.1 | 20130122 | Objective data sheet | - | - |

23. Legal information

23.1 Data sheet status

| Document status ^{[1][2]} | Product status ^[3] | Definition |
|-----------------------------------|-------------------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nxp.com>.

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