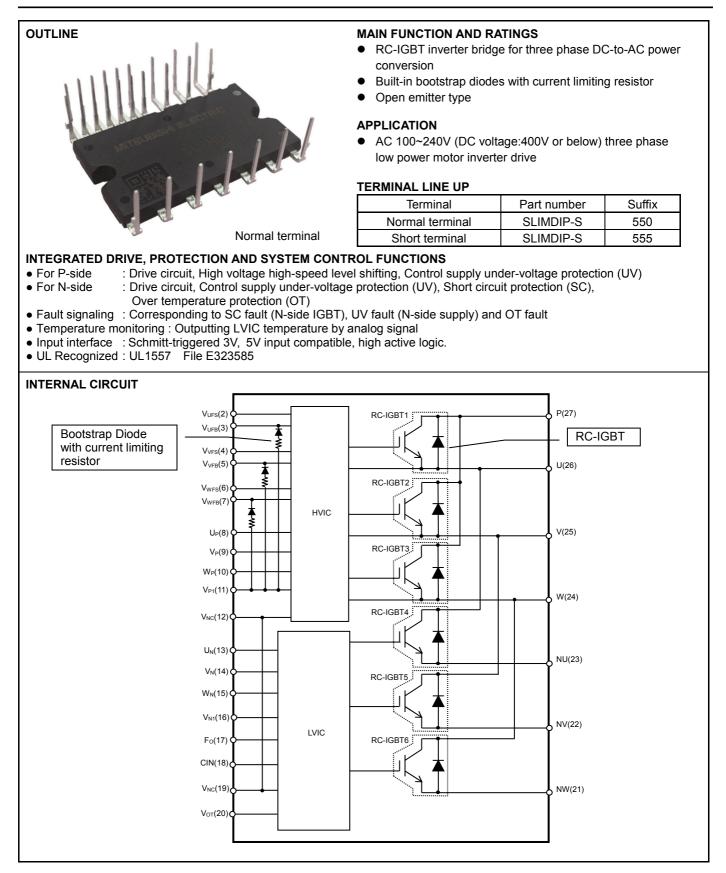


# < Dual-In-Line Package Intelligent Power Module > SLIMDIP-S

TRANSFER MOLDING TYPE **INSULATED TYPE** 



# **MAXIMUM RATINGS** (T<sub>j</sub> = 25°C, unless otherwise noted)

#### **INVERTER PART**

Symbol	Parameter	Condition	Ratings	Unit
V <sub>CC</sub>	Supply voltage	Applied between P-NU,NV,NW	450	V
V <sub>CC(surge)</sub>	Supply voltage (surge)	Applied between P-NU,NV,NW	500	V
V <sub>CES</sub>	Collector-emitter voltage		600	V
±l <sub>c</sub>	Each IGBT collector current	T <sub>C</sub> = 25°C (Note 1)	5	Α
±I <sub>CP</sub>	Each IGBT collector current (peak)	T <sub>C</sub> = 25°C, less than 1ms	10	Α
Tj	Junction temperature		-30~+150	°C

Note1: Pulse width and period are limited due to junction temperature.

#### **CONTROL (PROTECTION) PART**

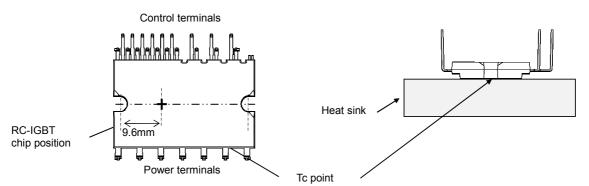
Symbol	Parameter	Condition	Ratings	Unit
VD	Control supply voltage	Applied between V <sub>P1</sub> -V <sub>NC</sub> , V <sub>N1</sub> -V <sub>NC</sub>	20	V
$V_{\text{DB}}$	Control supply voltage	Applied between V <sub>UFB</sub> -V <sub>UFS</sub> , V <sub>VFB</sub> -V <sub>VFS</sub> , V <sub>WFB</sub> -V <sub>WFS</sub>	20	V
V <sub>IN</sub>	Input voltage	Applied between UP, VP, WP, UN, VN, WN-VNC	-0.5~V <sub>D</sub> +0.5	V
V <sub>FO</sub>	Fault output supply voltage	Applied between Fo-VNC	-0.5~V <sub>D</sub> +0.5	V
I <sub>FO</sub>	Fault output current	Sink current at Fo terminal	1	mA
Vsc	Current sensing input voltage	Applied between CIN-V <sub>NC</sub>	-0.5~V <sub>D</sub> +0.5	V

#### TOTAL SYSTEM

Symbol	Parameter	Condition	Ratings	Unit
V <sub>CC(PROT)</sub>	Self protection supply voltage limit (Short circuit protection capability)	$V_D$ = 13.5~16.5V, Inverter Part T <sub>j</sub> = 125°C, non-repetitive, less than 2µs	400	V
Tc	Module case operation temperature	Measurement point of Tc is described in Fig.1 (Note2)	-30~+115	°C
T <sub>stg</sub>	Storage temperature		-40~+125	°C
V <sub>iso</sub>	Isolation voltage	60Hz, Sinusoidal, AC 1min, between connected all pins and heat sink plate	2000	V <sub>rms</sub>

#### Note2 T<sub>c</sub> MEASUREMENT POINT

Fig. 1



#### THERMAL RESISTANCE

Symbol         Parameter         Condition         Limits           Junction to case thermal         Limits         Min.         Typ.         Max.	Unit
Junction to case thermal	
Rth(j-c)QSufficience (Note 3)Inverter RC-IGBT part (per 1/6 module)5.4	K/W

Note 3: Grease with good thermal conductivity and long-term endurance should be applied evenly with about +100µm~+200µm on the contacting surface of DIPIPM and heat sink. The contacting thermal resistance between DIPIPM case and heat sink Rth(c-f) is determined by the thickness and the thermal conductivity of the applied grease. For reference, Rth(c-f) is about 0.4K/W (per 1/6 module, grease thickness: 20µm, thermal conductivity: 1.0W/m•K).

# ELECTRICAL CHARACTERISTICS (T<sub>j</sub> = 25°C, unless otherwise noted)

**INVERTER PART** 

Sumbol	Parameter	Condition			Limits			
Symbol	Falameter	Conc	Min.	Тур.	Max.	Unit		
V	Collector-emitter saturation	V <sub>D</sub> =V <sub>DB</sub> = 15V, V <sub>IN</sub> = 5V	I <sub>C</sub> = 5A, T <sub>j</sub> = 25°C	-	1.85	2.25	V	
V <sub>CE(sat)</sub>	voltage	$v_{\rm D} - v_{\rm DB} = 15v, v_{\rm IN} - 5v$	I <sub>C</sub> = 5A, T <sub>j</sub> = 125°C	-	2.05	2.45	v	
V <sub>EC</sub>	FWDi forward voltage	V <sub>IN</sub> = 0V, -I <sub>C</sub> = 5A			1.55	1.95	V	
t <sub>on</sub>				0.65	1.05	1.45	μs	
t <sub>C(on)</sub>		$V_{CC}$ = 300V, $V_{D}$ = $V_{DB}$ = 15V	-	0.30	0.55	μs		
t <sub>off</sub>	Switching times	I <sub>C</sub> = 5A, T <sub>i</sub> = 125°C, V <sub>IN</sub> = 0↔5V		-	1.15	1.60	μs	
t <sub>C(off)</sub>		Inductive Load (upper-lower a	Inductive Load (upper-lower arm)		0.15	0.40	μs	
t <sub>rr</sub>				-	0.20	-	Ms	
1	Collector-emitter cut-off	<u>)</u> ∕ −)∕	T <sub>j</sub> = 25°C	-	-	1	mA	
I <sub>CES</sub>	current	V <sub>CE</sub> =V <sub>CES</sub>	T <sub>j</sub> = 125°C	-	-	10	IIIA	

#### **CONTROL (PROTECTION) PART**

Symbol	Parameter	Cond	lition		Unit			
Symbol	Parameter	Condition			Тур.	Max.		
			V <sub>D</sub> =15V, V <sub>IN</sub> =0V	-	-	3.10		
ID		Total of $V_{P1}$ - $V_{NC}$ , $V_{N1}$ - $V_{NC}$	V <sub>D</sub> =15V, V <sub>IN</sub> =3.3V	-	-	4.20		
	Circuit current		V <sub>D</sub> =15V, V <sub>IN</sub> =5V	-	-	3.10	mA	
		Each part of VUFB-VUFS,	$V_D = V_{DB} = 15V, V_{IN} = 0V$	-	-	0.10		
IDB		$V_{VFB}$ - $\dot{V}_{VFS}$ , $V_{WFB}$ - $V_{WFS}$	V <sub>D</sub> =V <sub>DB</sub> =15V, V <sub>IN</sub> =5V	-	-	0.10		
V <sub>SC(ref)</sub>	Short circuit trip level	V <sub>D</sub> = 15V (Note 4)			0.480	0.505	V	
UV <sub>DBt</sub>	P-side Control supply		Trip level	7.0	10.0	12.0	V	
$UV_{DBr}$	under-voltage protection(UV)	T <105°C	Reset level	7.0	10.0	12.0	V	
UV <sub>Dt</sub>	N-side Control supply	- T <sub>j</sub> ≤125°C	Trip level	10.3	-	12.5	V	
UV <sub>Dr</sub>	under-voltage protection(UV)		Reset level	10.8	-	13.0	V	
V <sub>OT</sub>	Temperature Output		LVIC Temperature=95°C	2.76	2.89	3.03	V	
		Pull down R=5.1kΩ (Note 5)	LVIC Temperature=25°C	0.86	1.16	1.39	V	
OTt	Over temperature protection	V <sub>D</sub> = 15V	Trip level	115	130	145	°C	
OT <sub>rh</sub>	(Note6)	Detect LVIC temperature	Hysteresis of trip-reset	-	10	-	°C	
V <sub>FOH</sub>		V <sub>SC</sub> = 0V, F <sub>o</sub> terminal pulled u	$V_{SC}$ = 0V, F <sub>0</sub> terminal pulled up to 5V by 10kΩ			-	V	
V <sub>FOL</sub>	Fault output voltage	$V_{SC}$ = 1V, $I_{FO}$ = 1mA		-	-	0.95	V	
t <sub>FO</sub>	Fault output pulse width		(Note 7)	20	-	-	μs	
l <sub>in</sub>	Input current	$V_{IN} = 5V$	0.70	1.00	1.50	mA		
V <sub>th(on)</sub>	ON threshold voltage			-	1.70	2.35		
$V_{\text{th(off)}}$	OFF threshold voltage	Applied between $U_P$ , $V_P$ , $W_P$ , $U_N$ , $V_N$ , $W_N$ - $V_{NC}$		0.70	1.30	-	v	
$V_{\text{th(hys)}}$	ON/OFF threshold hysteresis voltage		0.25	0.40	-			
V <sub>F</sub>	Bootstrap Di forward voltage	IF=10mA including voltage drop b	by limiting resistor (Note 8)	1.1	1.7	2.3	V	
R	Built-in limiting resistance	Included in bootstrap Di		80	100	120	Ω	

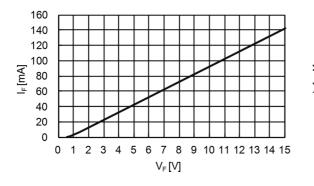
Note 4 : SC protection works only for N-side IGBT. Please select the external shunt resistance such that the SC trip-level is less than 1.7 times of the current rating.
 5 : Temperature of LVIC vs. Vo⊤ output characteristics is described in Fig.3.
 6 : When the LVIC temperature exceeds OT trip temperature level(OTt), OT protection works and Fo outputs. In that case if the heat sink dropped off or fixed

6 : When the LVIC temperature exceeds OT trip temperature level(OT<sub>t</sub>), OT protection works and Fo outputs. In that case if the heat sink dropped off or fixed loosely, don't reuse that DIPIPM. (There is a possibility that junction temperature of power chips exceeded maximum Tj(150°C).
7 : Fault signal Fo outputs when SC, UV or OT protection works. Fo pulse width is different for each protection modes. At SC failure, Fo pulse width is a fixed

7 : Fault signal Fo outputs when SC, UV or OT protection works. Fo pulse width is different for each protection modes. At SC failure, Fo pulse width is a fixed width (=minimum 20µs), but at UV or OT failure, Fo outputs continuously until recovering from UV or OT state. (But minimum Fo pulse width is 20µs.)
8 : The observatories of becarter and is fixed on the observatories of becarter and the observatories of

8 : The characteristics of bootstrap Di is described in Fig.2.

Fig. 2 Characteristics of Bootstrap Di V<sub>F</sub>-I<sub>F</sub> curve (@Ta=25°C) Including Voltage Drop by Limiting Resistor (Right chart is enlarged chart.)



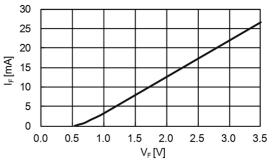


Fig. 3 Temperature of LVIC vs. V<sub>OT</sub> Ouput Characteristics

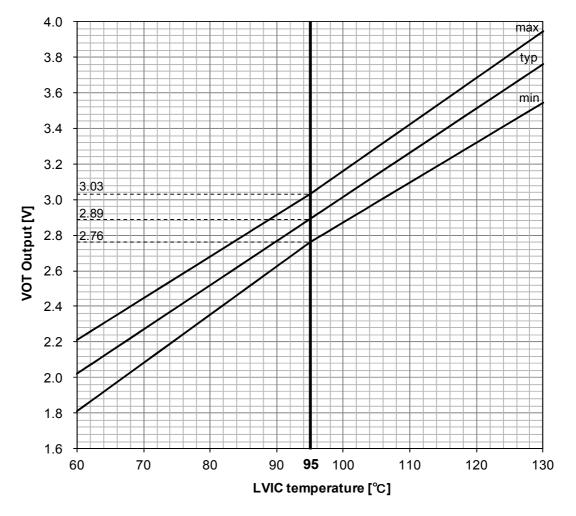
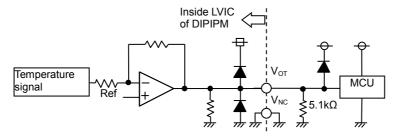


Fig. 4 Pattern Wiring Around the Analog Voltage Output Circuit [Vot terminal]



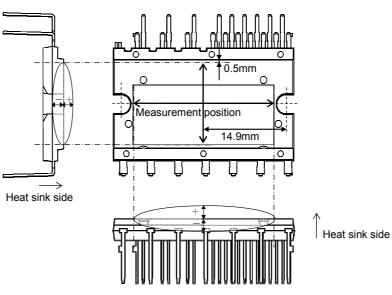
- (1) V<sub>OT</sub> outputs the analog signal that is amplified signal of temperature detecting element on LVIC by inverting amplifier.
   (2) It is recommended to insert 5kΩ (5.1kΩ is recommended) pull down resistor for getting linear output characteristics at low temperature below room temperature. When the pull down resistor is inserted between V<sub>OT</sub> and V<sub>NC</sub>(control GND), the extra circuit current, which is calculated approximately by V<sub>OT</sub> output voltage divided by pull down resistance, flows as LVIC circuit current continuously. In the case of using Vor for detecting high temperature over room temperature only, it is unnecessary to insert the pull down resistor.
- (3) In the case of using Vot with low voltage controller like 3.3V MCU, Vot output might exceed control supply voltage 3.3V when temperature rises excessively. If system uses low voltage controller, it is recommended to insert a clamp Di between control supply of the controller and VoT output for preventing over voltage destruction
- (4) In the case of not using Vot, leave Vot output NC (No Connection).

Please also refer the application note for SLIMDIP series about the usage of  $V_{\text{OT}}$ .

### **MECHANICAL CHARACTERISTICS AND RATINGS**

Parameter	Condition			Limits			
				Тур.	Max.	Unit	
Mounting torque	Mounting screw : M3 (Note 9)	Mounting screw : M3 (Note 9) Recommended 0.69N·m				N∙m	
Terminal pulling strength	Control terminal: Load 5N Power terminal: Load 10N	JEITA-ED-4701	10	-	-	s	
Terminal bending strength	Control terminal: Load 2.5N Power terminal: Load 5N 90deg. bend	JEITA-ED-4701	2	-	-	times	
Weight			-	5.5	-	g	
Heat radiation part flatness	Heat radiation part flatness (Note 10)					μm	

Note 9: Plain washers (ISO 7089~7094) are recommended. Note 10: Measurement positions of heat radiation part flatness are as below



#### **RECOMMENDED OPERATION CONDITIONS**

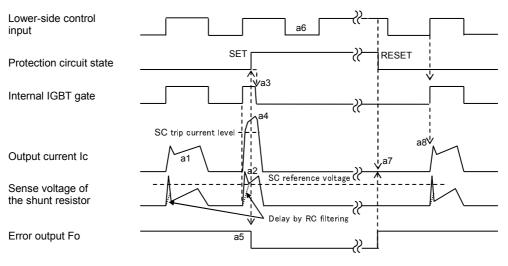
Symbol Parameter		Condition			Limits			
		Condition	Condition			Max.	Unit	
V <sub>CC</sub>	Supply voltage	Applied between P-NU, NV, NW			300	400	V	
V <sub>D</sub>	Control supply voltage	Applied between V <sub>P1</sub> -V <sub>NC</sub> , V <sub>N1</sub> -V <sub>NC</sub>		13.5	15.0	16.5	V	
V <sub>DB</sub>	Control supply voltage	Applied between VUFB-VUFS, VVFB-VVFS, VV	VFB-VWFS	13.0	15.0	18.5	V	
$\Delta V_D, \Delta V_{DB}$	Control supply variation				-	+1	V/µs	
t <sub>dead</sub>	Arm shoot-through blocking time	For each input signal, T <sub>C</sub> ≤100°C	1.0	-	-	μs		
f <sub>PWM</sub>	PWM input frequency	Tc≤100°C, T <sub>i</sub> ≤125°C			_	20	kHz	
1	Allowable r.m.a. ourrant	$V_{CC} = 300V, V_D = V_{DB} = 15V, P.F = 0.8,$ Sinusoidal PWM		-	-	2.5	Armo	
I <sub>O</sub>	Allowable r.m.s. current	$T_c \le 100^{\circ}C, T_j \le 125^{\circ}C$ (Note11)	f <sub>PWM</sub> = 15kHz	-	-	2.0	Arms	
PWIN(on)			(Note 12)			-		
PWIN(off)	Minimum input pulse width		0.7	-	-	μs		
V <sub>NC</sub>	V <sub>NC</sub> variation	Between V <sub>NC</sub> -NU, NV, NW (including sur	-5.0	-	+5.0	V		
Tj	Junction temperature			-20	-	+125	°C	

Note 11: Allowable r.m.s. current depends on the actual application conditions. 12: DIPIPM might not make response if the input signal pulse width is less than PWIN(on), PWIN(off).

Fig. 5 Timing Charts of The DIPIPM Protective Functions

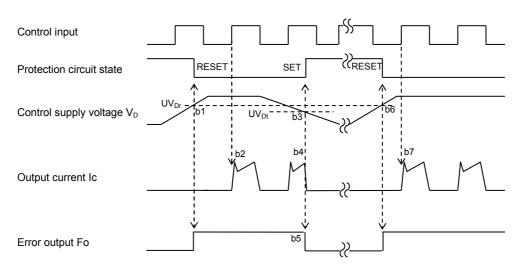
[A] Short-Circuit Protection (N-side only with the external shunt resistor and RC filter)

- a1. Normal operation: IGBT ON and outputs current.
- a2. Short circuit current detection (SC trigger)
- (It is recommended to set RC time constant 1.5~2.0µs so that IGBT shut down within 2.0µs when SC.)
- a3. All N-side IGBT's gates are hard interrupted.
- a4. All N-side IGBTs turn OFF.
- a5.  $F_{\text{O}}$  outputs for  $t_{\text{Fo}}\text{=}\text{minimum}$  20µs.
- a6. Input = "L": IGBT OFF
- a7. Fo finishes output, but IGBTs don't turn on until inputting next ON signal (L $\rightarrow$ H).
- (IGBT of each phase can return to normal state by inputting ON signal to each phase.)
- a8. Normal operation: IGBT ON and outputs current.



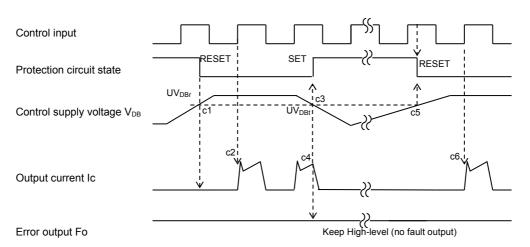
[B] Under-Voltage Protection (N-side, UV<sub>D</sub>)

- b1. Control supply voltage V<sub>D</sub> exceeds under voltage reset level (UV<sub>Dr</sub>), but IGBT turns ON by next ON signal (L $\rightarrow$ H). (IGBT of each phase can return to normal state by inputting ON signal to each phase.)
- b2. Normal operation: IGBT ON and outputs current.
- b3. V<sub>D</sub> level drops to under voltage trip level. (UV<sub>Dt</sub>).
- b4. All N-side IGBTs turn OFF in spite of control input condition.
- b5. Fo outputs for  $t_{Fo}$ =minimum 20µs, but output is extended during V<sub>D</sub> keeps below UV<sub>Dr</sub>.
- b6.  $V_D$  level reaches  $UV_{Dr}$ .
- b7. Normal operation: IGBT ON and outputs current.



[C] Under-Voltage Protection (P-side, UV<sub>DB</sub>)

- c1. Control supply voltage V<sub>DB</sub> rises. After the voltage reaches under voltage reset level UV<sub>DBr</sub>, IGBT turns on by next ON signal (L→H).
- c2. Normal operation: IGBT ON and outputs current.
- c3. V<sub>DB</sub> level drops to under voltage trip level (UV<sub>DBt</sub>).
- c4. IGBT of the corresponding phase only turns OFF in spite of control input signal level, but there is no Fo signal output.
- c5.  $V_{DB}$  level reaches UV<sub>DBr</sub>.
- c6. Normal operation: IGBT ON and outputs current.



[D] Over Temperature Protection (N-side, Detecting LVIC temperature)

- d1. Normal operation: IGBT ON and outputs current.
- d2. LVIC temperature exceeds over temperature trip level( $OT_t$ ).
- d3. All N-side IGBTs turn OFF in spite of control input condition.
- d4. Fo outputs for  $t_{Fo}$ =minimum 20µs, but output is extended during LVIC temperature keeps over  $OT_t$ .
- d5. LVIC temperature drops to over temperature reset level.
- d6. Normal operation: IGBT turns on by next ON signal (L $\rightarrow$ H).

(IGBT of each phase can return to normal state by inputting ON signal to each phase.)

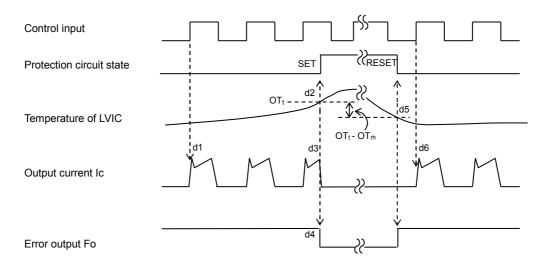
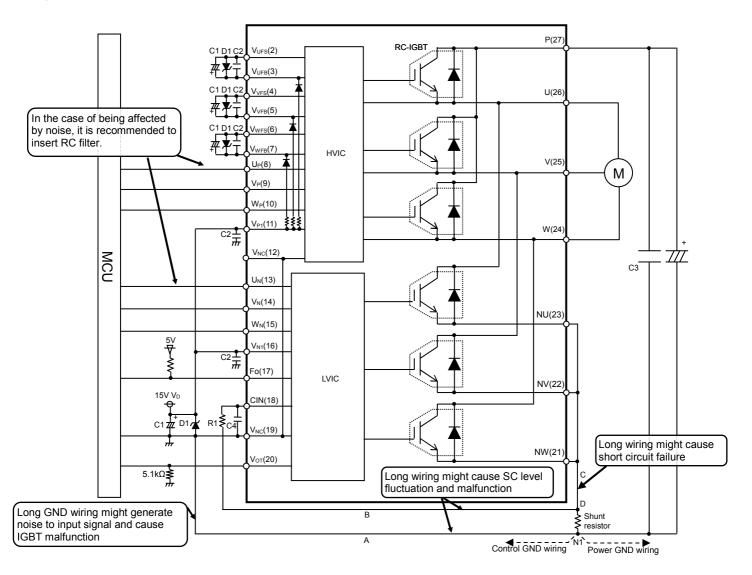
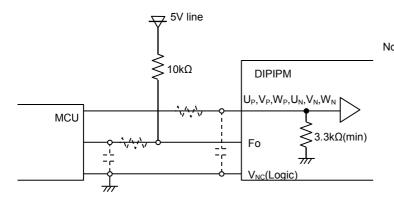


Fig. 6 Example of Application Circuit



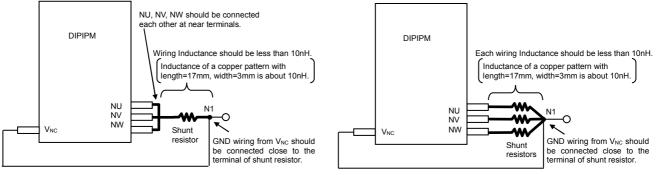
- (1) If control GND is connected with power GND by common broad pattern, it may cause malfunction by power GND fluctuation. It is recommended to connect control GND and power GND at only a point N1 (near the terminal of shunt resistor).
- (2) It is recommended to insert a Zener diode D1(24V/1W) between each pair of control supply terminals to prevent surge destruction.
- (3) To prevent surge destruction, the wiring between the smoothing capacitor and the P, N1 terminals should be as short as possible. Generally a 0.1-0.22µF snubber capacitor C3 between the P-N1 terminals is recommended.
- (4) R1, C4 of RC filter for preventing protection circuit malfunction is recommended to select tight tolerance, temp-compensated type. The time constant R1C4 should be set so that SC current is shut down within 2µs. (1.5µs~2µs is general value.) SC interrupting time might vary with the wiring pattern, so the enough evaluation on the real system is necessary.
- (5) To prevent malfunction, the wiring of A, B, C should be as short as possible.
- (6) The point D at which the wiring to CIN filter is divided should be near the terminal of shunt resistor. NU, NV, NW terminals should be connected at near NU, NV, NW terminals.
- (7) All capacitors should be mounted as close to the terminals as possible. (C1: good temperature, frequency characteristic electrolytic type and C2:0.01µ-2µF, good temperature, frequency and DC bias characteristic ceramic type are recommended.)
- (8) Input drive is High-active type. There is a minimum 3.3kΩ pull-down resistor in the input circuit of IC. To prevent malfunction, the wiring of each input should be as short as possible. When using RC coupling circuit, make sure the input signal level meet the turn-on and turn-off threshold voltage.
- (9) Thanks to built-in HVIC, direct coupling to MCU without any optocoupler or transformer isolation is possible.
- (10) Fo output is open drain type. It should be pulled up to MCU or control power supply (e.g. 5V,15V) by a resistor that makes I<sub>Fo</sub> up to 1mA. (I<sub>FO</sub> is estimated roughly by the formula of control power supply voltage divided by pull-up resistance. In the case of pulled up to 5V, 10kΩ (5kΩ or more) is recommended.)
- (11) Two V<sub>NC</sub> terminals are connected inside DIPIPM, please connect either one to the 15V power supply GND outside and leave another one open.
- (12) If high frequency noise superimposed to the control supply line, IC malfunction might happen and cause DIPIPM erroneous operation. To avoid such problem, line ripple voltage should meet dV/dt ≤+/-1V/µs, Vripple≤2Vp-p.

Fig. 7 MCU I/O Interface Circuit



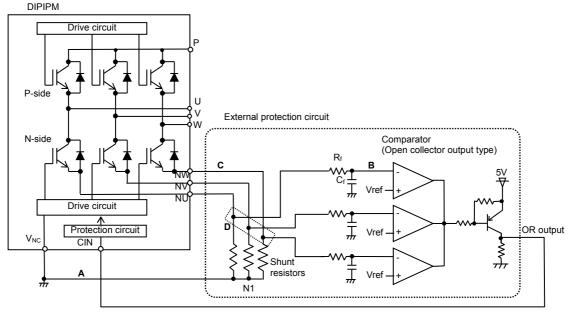
Note: The RC coupling (parts shown in the dotted line) at each input depends on user's PWM control strategy and the wiring impedance of the printed circuit board. The DIPIPM signal input section integrates a  $3.3k\Omega(min)$  pull-down resistor. Therefore, when using an external filtering resistor, please pay attention to the signal voltage drop at input terminal.

#### Fig. 8 Pattern Wiring Around the Shunt Resistor



Low inductance shunt resistor like surface mounted (SMD) type is recommended.

Fig. 9 External SC Protection Circuit with Using Three Shunt Resistors



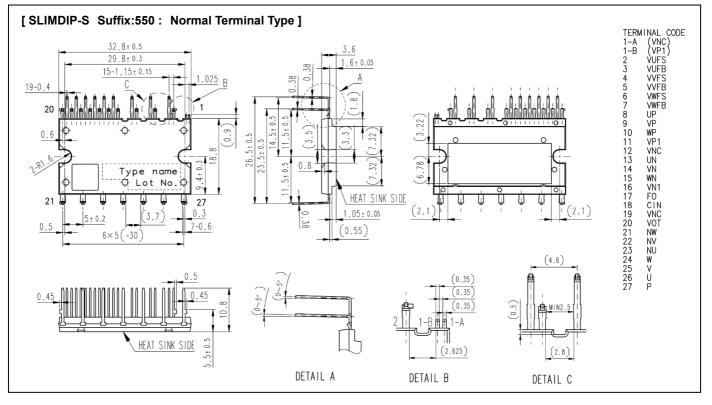
(1) It is necessary to set the time constant R<sub>f</sub>C<sub>f</sub> of external comparator input so that IGBT stop within 2µs when short circuit occurs. SC interrupting time might vary with the wiring pattern, comparator speed and so on.

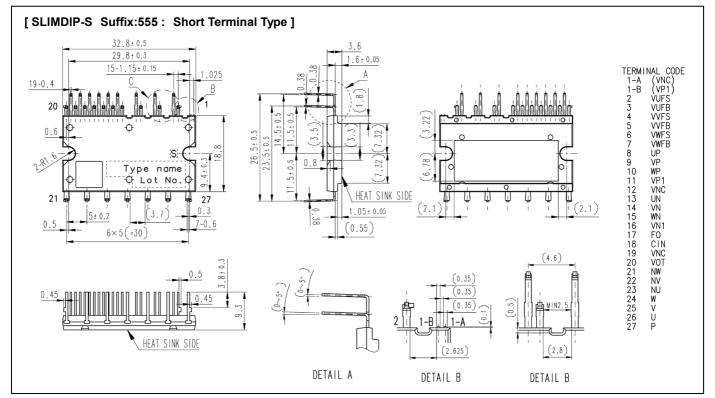
(2) The threshold voltage Vref should be set up the same rating of short circuit trip level (Vsc(ref) typ. 0.48V).

- (3) Select the external shunt resistance so that SC trip-level is less than specified maximum value.
- (4) To avoid malfunction, the wiring A, B, C should be as short as possible.
- (5) The point D at which the wiring to comparator is divided should be near the terminal of shunt resistor.
- (6) OR output high level should be over 0.505V (=maximum Vsc(ref)).

(7) GND of Comparator, Vref circuit and Cf should be not connected to noisy power GND but to control GND wiring.

Fig. 10 Package Outlines





Note: Connect only one  $V_{NC}$  terminal (No.12 or 19) to the system GND and leave another one open.

**Revision Record** 

Rev.	Date	Page	Revised contents
1	12/09/2016	-	New

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